

# Metric Spaces

Def: A metric space (MS) is a pair  $(M, d)$  where  $M \neq \emptyset$  is a set and  $d: M \times M \rightarrow \mathbb{R}$  is a metric i.e.

1,  $\forall x, y \in M: d(x, y) \geq 0$  &  $d(x, y) = 0 \Leftrightarrow x = y$  ... positivity

2,  $\forall x, y \in M: d(x, y) = d(y, x)$  ... symmetry

3,  $\forall x, y, z \in M: d(x, z) \leq d(x, y) + d(y, z)$  ...  $\Delta$ -ineq.

👁 In fact,  $d(x, y) \geq 0$  follows from the other axioms.

↳ assume  $d(x, y) < 0$

$\Rightarrow 0 = d(x, x) = d(x, y) + d(y, x) = 2 \cdot d(x, y) < 0 \quad \text{!}$

$\Rightarrow$  we only need to show  $d(x, y) = 0 \Leftrightarrow x = y$  when proving stuff

Def: The subset  $X \subseteq M$  determines a subspace of  $(M, d)$  which we call  $(X, d)$

Def: An isometry  $f$  of metric spaces  $(M, d_M)$  and  $(N, d_N)$  is a bijection  $f: M \rightarrow N$  which preserves distances

$\forall x, y \in M: d_M(x, y) = d_N(f(x), f(y))$

$\rightarrow$  if it exists we say that  $(M, d_M)$  and  $(N, d_N)$  are isometric.

Idea: Isometric spaces are practically indistinguishable

## • Euclidean Space

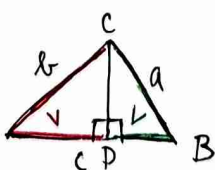
Def: The  $n$ -dim. Euclidean space is  $\mathbb{E}_n := (\mathbb{R}^n, e_n)$  where  $e_n(\tilde{x}, \tilde{y}) = \sqrt{\sum_i (x_i - y_i)^2}$

↳  $(X, e_n)$  where  $X \subseteq \mathbb{R}^n$  are also called Euclidean

Theorem:  $\mathbb{E}_n = (\mathbb{R}^n, e_n)$  is a metric space

↳ clearly ① and ② hold

↳ for  $n=1$  the  $\Delta$ -ineq is trivial

↳ for  $n=2$  consider any triangle  $A$  

PT:  $c^2 = a^2 + b^2$   
 $\Rightarrow c > a$   
 $c > b$

where WLOG:  $c \geq b \geq a$

$\rightarrow$  clearly  $a \leq b + c$  and  $b \leq a + c$ , need to show  $c \leq a + b$

$\rightarrow$  draw a height from  $C$  to find the point  $D \in AB$

↳ if  $D \notin AB$  then  $a > c$  or  $b > c$

$\rightarrow$  divide the triangle to 2 right angle triangles

$\otimes: c = d(A, D) + d(D, B) \leq \underline{a} + \underline{b}$

→ if  $n > 2$  we reduce it geometrically to  $n=2$

↳ any three different non-collinear points in  $\mathbb{R}^n$

determine a unique two dimensional plane  $P \subset \mathbb{R}^n$  isometric to  $\mathbb{R}^2$

→ the distances between the points are preserved → use  $n=2$  ▢

Ex: The distance in a graph is a metric

Ex:  $(F, d)$  where  $F$  is the set of functions which have the Riemann integral on the interval  $[a, b] \subseteq \mathbb{R}$  and

$$d(f, g) := \int_a^b |f(t) - g(t)| dt$$

→ ① and ② obviously hold

△ inequality:  $d(f, g) \leq d(f, h) + d(h, g)$

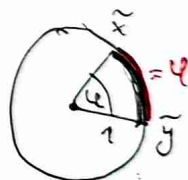
$$d(f, h) + d(h, g) = \int_a^b |f(t) - h(t)| dt + \int_a^b |h(t) - g(t)| dt$$

$$\geq \int_a^b |(f-h) + (h-g)| dt = \int_a^b |f-g| dt = d(f, g) \quad \text{▢}$$

### • The Spherical Metric

Def: The unit sphere is  $S := \{(x_1, x_2, x_3) \in \mathbb{R}^3 \mid x_1^2 + x_2^2 + x_3^2 = 1\}$

Define  $d: S \times S \rightarrow [0, \pi]$  as  $d(\tilde{x}, \tilde{y}) = \begin{cases} 0, & \tilde{x} = \tilde{y} \\ \varphi, & \tilde{x} \neq \tilde{y} \end{cases}$



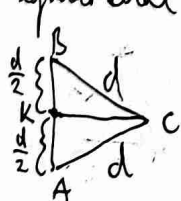
Fact:  $(S, d)$  is a metric space

Thm: The upper hemisphere  $H = \{(x_1, x_2, x_3) \in S \mid x_3 \geq 0\}$  is not flat.

↳  $(H, d)$  is not isometric to any Euclidean space  $(X, e_m) \subseteq \mathbb{E}_m$ .

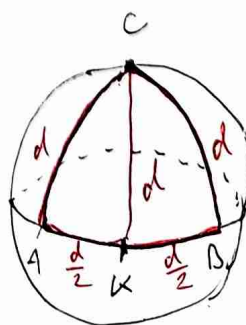
Pf: We find a property which holds for any quadruple of points in  $\mathbb{E}_m$  but not in  $H$

equilateral  $\Delta$



$$e_m(K, C) = \sqrt{d^2 - \left(\frac{1}{2}d\right)^2} = \frac{\sqrt{3}}{2}d < d$$

→ need to find 4 points on  $H$  which violate it



$$d(K, C) = d$$



## • Ultrametric Spaces (non-Archimedean)

Def: The MS  $(M, d)$  is called ultrametric  $\equiv d$  satisfies the strong  $\Delta$ -ineq

$$\forall x, y, z \in M: d(x, y) \leq \max\{d(x, z), d(z, y)\}$$

☞ if  $d(x, z) \neq d(z, y)$ , then  $d(x, y) = \max\{d(x, z), d(z, y)\}$

$$\hookrightarrow \text{let } d(x, z) < d(z, y) \text{ and } d(x, y) < \max\{d(x, z), d(z, y)\} = d(z, y)$$

$$\cdot \text{strong } \Delta \text{ ineq: } d(z, y) \leq \max\{d(z, x), d(x, y)\} < d(z, y) \quad \text{!}$$

Lemma: Every triangle in an UMS  $(M, d)$  is isosceles  $\Delta$ .



Pf: let  $a \geq b, c$

$$\Delta\text{-ineq: } a \leq \max\{b, c\} \Rightarrow a = b \text{ or } a = c$$

Def: An open ball with center  $a$  and radius  $r > 0$  in  $(M, d)$  is  $B(a, r) := \{x \in M \mid d(a, x) < r\}$

☞  $B(a, r) \neq \emptyset$  because  $a \in B(a, r)$

Lemma: For every ball in an UMS, every point is its center.

Pf: pick any  $b \in B(a, r) \dots d(a, b) < r$

$$\text{need: } d(a, x) < r \iff d(b, x) < r$$

$$\Delta\text{-ineq: } d(b, x) \leq \max\{d(b, a), d(a, x)\} < r$$

## • $p$ -adic Metric and Norm

Def: Let  $p$  be a prime and  $m \in \mathbb{Z}$ . We define the  $p$ -adic order of  $m$  as

$$\text{ord}_p(m) = \max\{m \in \mathbb{N}_0 \mid p^m \mid m\}, \quad \text{ord}_p(0) := +\infty$$

For  $a \in \mathbb{Z}, b \in \mathbb{Z} \setminus \{0\}$  we define

$$\text{ord}_p(a/b) := \text{ord}_p(a) - \text{ord}_p(b)$$

$$\text{Ex: } \text{ord}_5(297/100) = 0 - 2 = -2, \quad \text{ord}_3(297/100) = \text{ord}_3(27 \cdot 11) - \text{ord}_3(100) = 3 - 0$$

$$\text{☞ } \frac{a}{b} = \frac{c}{d} \Rightarrow \text{ord}_p\left(\frac{a}{b}\right) = \text{ord}_p\left(\frac{c}{d}\right) \quad \because \text{ord}_p\left(\frac{a}{b}\right) = \text{ord}(qa) - \text{ord}(qb) = (\text{ord}(q) + \text{ord}(a)) - (\text{ord}(q) + \text{ord}(b))$$

$$\text{☞ } \text{ord}_p(\alpha \cdot \beta) = \text{ord}_p(\alpha) + \text{ord}_p(\beta), \quad \alpha, \beta \in \mathbb{Q}$$

↖ Fundamental Thm of Arithmetic used

$$\hookrightarrow \text{ord}\left(\frac{a}{b} \cdot \frac{c}{d}\right) = \text{ord}(ac) - \text{ord}(bd) = \text{ord}(a) + \text{ord}(c) - \text{ord}(b) - \text{ord}(d) = \text{ord}\left(\frac{a}{b}\right) + \text{ord}\left(\frac{c}{d}\right)$$

Def: The  $p$ -adic norm for  $c \in (0,1)$  is the function

$$|\cdot|_p: \mathbb{Q} \rightarrow \mathbb{R}^+, \quad |x|_p := c^{\text{ord}_p(x)}, \quad |0|_p = c^{+\infty} := 0$$

Ex:  $c = \frac{1}{2} \rightarrow \left| \frac{1}{100} \right|_5 = \left( \frac{1}{2} \right)^{\text{ord}_5(1/100)} = \left( \frac{1}{2} \right)^{0-2} = 4$

⊙  $|x \cdot y|_p = |x|_p \cdot |y|_p$

$$\hookrightarrow |x \cdot y|_p = c^{\text{ord}(xy)} = c^{\text{ord } x + \text{ord } y} = c^{\text{ord } x} \cdot c^{\text{ord } y} = |x|_p \cdot |y|_p$$

Intuition

$$\text{ord}_p \sim \log$$

$$|\cdot|_p \sim c^{\log} \sim x$$

$$\log(xy) = \log x + \log y$$

$$(x \cdot y) = (x) \cdot (y)$$

## Normed Fields

Def: A normed field is a field  $(F, 0_F, 1_F, \oplus, \cdot)$  equipped with the norm  $|\cdot|_F: F \rightarrow \mathbb{R}^+$ , s.t.

1)  $\forall x \in F: |x|_F = 0 \Leftrightarrow x = 0_F$

2)  $\forall x, y \in F: |x \cdot y|_F = |x|_F \cdot |y|_F$  ... multiplicativity

3)  $\forall x, y \in F: |x \oplus y|_F \leq |x|_F + |y|_F$  ...  $\Delta$ -ineq

Lemma:  $|1_F|_F = 1$ ,  $\forall x \in F: |-x|_F = |x|_F$ ,  $\forall x = 0_F: |x^{-1}|_F = 1/|x|_F$

Pf:  $\forall x \in F: x \cdot 1_F = x \Rightarrow |x \cdot 1_F| = |x| \cdot |1_F| = |x| \Rightarrow |1_F| = 1$

$$\left. \begin{aligned} &|(-x) \cdot (-x)| = |-x| \cdot |-x| = |-x|^2 \\ &= |x \cdot x| = |x| \cdot |x| = |x|^2 \end{aligned} \right\} |x|^2 = |-x|^2 \quad \& \quad |\cdot|_F: F \rightarrow \mathbb{R}^+ \Rightarrow |x| = |-x|$$

$$\bullet |x \cdot x^{-1}| = |x| \cdot |x^{-1}| = |1_F| = 1 \Rightarrow |x| \cdot |x^{-1}| = 1 \Rightarrow |x^{-1}| = 1/|x|$$

Lemma: For every normed field  $(F, |\cdot|_F)$ , the function  $d(x, y) := |x - y|_F$  is a metric on  $F$ .

When  $|\cdot|_F$  satisfies the strong  $\Delta$ -ineq, then  $d$  is an ultrametric.

Corollary: It is easy to construct metric spaces from normed fields.

Pf: ①  $d(x, y) = 0 \Leftrightarrow |x - y| = 0 \Leftrightarrow x - y = 0_F \Leftrightarrow x = y$

②  $d(x, y) = |x - y| = |y - x| = d(y, x)$

③  $d(x, z) + d(z, y) = |x - z| + |z - y| \geq |(x - z) + (z - y)| = |x - y| = d(x, y)$

④  $|x \oplus y| \leq \max\{|x|, |y|\} \Rightarrow \max\{d(x, z), d(z, y)\} = \max\{|x - z|, |z - y|\} \geq |x - y| = d(x, y)$  ■

Theorem: For every prime  $p$  and  $c \in (0, 1)$ ,  $(\mathbb{Q}, |\cdot|_p)$  is a normed field.  
The corresponding metric space  $(\mathbb{Q}, d)$  is ultrametric.

Pf: We need to show that  $|\cdot|_p$  is a norm with the strong  $\Delta$ -ineq.

①  $|x|_p = 0 \Leftrightarrow x = 0$   $\checkmark$  ... from the definition of  $|\cdot|_p$

②  $|x \cdot y|_p = |x|_p \cdot |y|_p$   $\checkmark$  ... proven earlier

③ strong  $\Delta$ -ineq

$\forall \alpha, \beta \in \mathbb{Q}: |\alpha + \beta|_p \leq \max\{|\alpha|_p, |\beta|_p\}$

$c_{\text{ord}}(\alpha + \beta) \leq \max\{c_{\text{ord}} \alpha, c_{\text{ord}} \beta\}$ ,  $c \in (0, 1)$

$\text{ord}(\alpha + \beta) \geq \min\{\text{ord} \alpha, \text{ord} \beta\}$

$\rightarrow$  let  $\alpha = a/b$ ,  $\beta = c/d$  ... when  $\alpha = 0$  or  $\beta = 0$  it is trivial

$\Rightarrow$  let  $\text{ord}_p(\alpha) = m$ ,  $\text{ord}_p(\beta) = n$

$\hookrightarrow \alpha = \frac{a}{b} = p^m \cdot \frac{a'}{b'}$ ,  $\beta = \frac{c}{d} = p^n \cdot \frac{c'}{d'}$ ,  $a', b', c', d'$  not divisible by  $p$

$\rightarrow$  WLOG let  $m \leq n$

$\alpha + \beta = p^m \frac{a'}{b'} + p^m \frac{c'}{d'} = p^m \cdot \frac{a'd' + p^{n-m} c'b'}{b'd'} =: p^m \cdot \frac{e}{f}$

$\rightarrow p \nmid f \Rightarrow \text{ord}_p\left(\frac{e}{f}\right) \geq 0 \Rightarrow \text{ord}(\alpha + \beta) \geq m = \min(\text{ord} \alpha, \text{ord} \beta)$   $\square$

### • Ostrowski's Theorem

Def: On any field  $F$  we have the trivial norm  $\|x\| = \begin{cases} 0, & x = 0_F \\ 1, & x \neq 0_F \end{cases}$

Lemma: Let  $\|\cdot\|: F \rightarrow \mathbb{R}^+$  be a norm on  $F$ . Then  $f(\|\cdot\|): F \rightarrow \mathbb{R}_0^+$  is a norm  $\Leftrightarrow$   
 $\alpha \mapsto f(\|\alpha\|)$

i)  $f(x) \geq 0$  &  $f(x) = 0 \Leftrightarrow x = 0$

ii)  $f(x \cdot y) = f(x) \cdot f(y)$

iii)  $f(x + y) \leq f(x) + f(y)$

$f: \mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+$  is a norm

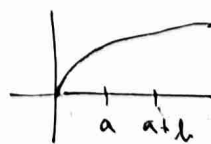
Pf: (i) shows ①, (ii) shows ②, (iii) shows ③

Lemma: Reverse 1.1 the standard norm on  $\mathbb{C}$ . Then  $|\cdot|^c$  is a norm  $\Leftrightarrow c \in (0, 1]$

Pf: i)  $\checkmark$  ii)  $|a \cdot b|^c = |a|^c \cdot |b|^c$

iii) need:  $(a + b)^c \leq a^c + b^c$ ,  $a, b \geq 0$

$\hookrightarrow$  true because  $f(x) = x^c$  is increasing concave



Def: For  $\alpha \in \mathbb{Q}$  and  $p$  prime, the canonical  $p$ -adic norm is

$\|\alpha\|_p = p^{-\text{ord}_p(\alpha)}$

... we set  $c = \frac{1}{p}$  in the general  $p$ -adic norm

# OSTROVSKI THEOREM

Lemma 1: For  $c > 0$  is  $|\cdot|^c$  a norm on  $(\mathbb{Q}, \mathbb{R}, \mathbb{C}) \iff c \leq 1 \dots c \in (0, 1]$

Lemma 2: Let  $\|\cdot\|$  be a non-trivial norm on  $\mathbb{Q}$ . Then  $\exists m \in \mathbb{N}$  s.t.  $m \geq 2$  &  $\|m\| \neq 1$ .

Lemma 3: For every coprime ( $\gcd=1$ )  $a, b \in \mathbb{Z}$  exist  $c, d \in \mathbb{Z}$  s.t.  $ac + db = 1$ .

Theorem (Ostrowski): Let  $\|\cdot\|$  be a norm on  $\mathbb{Q}$ . Then one of the following holds:

- ①  $\|\cdot\|$  is a trivial norm
- ②  $\exists c \in (0, 1]$  s.t.  $\|x\| = |x|^c \dots$  modified absolute value
- ③  $\exists c \in (0, 1)$  s.t.  $\|x\| = |x|_p = c^{\text{ord}_p(x)} \dots$  p-adic norm

Proof: Let  $\|\cdot\|$  be non-trivial, then by lemma 2  $\exists m \in \mathbb{N}$ ,  $m \geq 2$  and  $\|m\| \neq 1$ .

$\Rightarrow$  either ①:  $\exists m \in \mathbb{N}$ ,  $m \geq 2$  s.t.  $\|m\| > 1$ . ②  $\forall m \in \mathbb{N}: \|m\| \leq 1$  &  $\exists m \geq 2: \|m\| = 0$ .

①  $\exists m \in \mathbb{N}$ ,  $m \geq 2$  s.t.  $\|m\| > 1$   $\Rightarrow$  let  $m_0 \geq 2$  be the smallest such  $m$

\*1  $\odot m \in \mathbb{N}$  &  $1 \leq m < m_0 \Rightarrow \|m\| \leq 1 \dots \nearrow$

\*2  $\odot$  because  $m_0 \geq 2$  &  $\|m_0\| > 1$ :  $\exists$  unique  $c > 0$  s.t.  $\|m_0\| = m_0^c$

We can write any  $m \in \mathbb{N}$  in base- $m_0$  as

$$m = a_0 + a_1 m_0 + a_2 m_0^2 + \dots + a_s m_0^s, \quad a_i \in [0, m_0 - 1], \quad a_s \neq 0$$

$$\Rightarrow \|m\| = \left\| \sum a_i m_0^i \right\| \leq \sum \|a_i m_0^i\| = \sum \|a_i\| \cdot \|m_0^i\| = \sum_{i=0}^s \|a_i\| \cdot \|m_0\|^i$$

$$\stackrel{*1}{\leq} \sum_{i=0}^s \|m_0\|^i \stackrel{*2}{=} \sum_{i=0}^s m_0^{c \cdot i} = m_0^0 + m_0^c + m_0^{2c} + \dots + m_0^{sc}$$

$$= m_0^{sc} \left( \frac{1}{m_0^{sc}} + \frac{1}{m_0^{(s-1)c}} + \dots + \frac{1}{m_0^c} + \frac{1}{m_0^0} \right) = m_0^{sc} \sum_{i=0}^s \left( \frac{1}{m_0^c} \right)^i \stackrel{*2}{\leq} m_0^{sc} \sum_{i=0}^{\infty} \left( \frac{1}{\|m_0\|} \right)^i$$

$$\stackrel{m \geq m_0}{\leq} m^c \cdot A, \quad A = \sum_{i=0}^{\infty} \left( \frac{1}{\|m_0\|} \right)^i = \frac{1}{1 - \frac{1}{\|m_0\|}} = \frac{\|m_0\|}{\|m_0\| - 1} \geq 1 \because \|m_0\| > 1$$

Goal: show  $\|m\| = m^c$  for  $m \in \mathbb{N}$

$\rightarrow$  then from multiplicativity of norms we have  $\frac{a}{x} \in \mathbb{Q}: \left\| \frac{a}{x} \right\| = \frac{\|a\|}{\|x\|} = \left( \frac{a}{x} \right)^c$

$\Rightarrow$  by lemma 1 then  $c \in (0, 1]$  and therefore  $\|\cdot\|$  is modified absolute value

claim  $\|m\| \leq m^c$ : we know  $\|m\| \leq m^c \cdot A$ ,  $A \geq 1$  for any  $m \in \mathbb{N}$

$$\Rightarrow \text{let } m \in \mathbb{N}: \|m\|^m = \|m^m\| \leq (m^m)^c \cdot A = (m^c)^m \cdot A$$

$$\Rightarrow \text{taking } m\text{-th root: } \|m\| \leq (m^c) \cdot \sqrt[m]{A}$$

$$\rightarrow \text{now we take the limit transition } m \rightarrow \infty: \sqrt[m]{A} \rightarrow 1 \Rightarrow \|m\| \leq m^c \quad \odot 3$$

claim:  $\|m\| \geq m^c$

→ again consider expansion of  $m$  in base  $m_0$

$$m = a_0 + a_1 m_0 + a_2 m_0^2 + \dots + a_s m_0^s, \quad a_i \in [m_0 - 1]$$

⊙  $m_0^s \leq m < m_0^{s+1}$  ⊕4 ...  $m_0 = 10, m = 1293 : 1000 \leq 1293 < 10000$

⊙  $\|m_0\|^{s+1} - \|m_0^{s+1} - m\| = \|m + (m_0^{s+1} - m)\| \leq \|m\| + \|m_0^{s+1} - m\|$

$$\Rightarrow \|m\| \geq \|m_0\|^{s+1} - \|m_0^{s+1} - m\|$$

⊗2:  $\|m_0\| = m_0^c \Rightarrow \|m_0\|^{s+1} = m_0^{(s+1)c}$

⊗3:  $\|m_0^{s+1} - m\| \leq (m_0^{s+1} - m)^c$

$$\geq m_0^{(s+1)c} - (m_0^{s+1} - m)^c$$

⊕4  $\geq m_0^{(s+1)c} - (m_0^{s+1} - m_0^s)^c = m_0^{(s+1)c} - \left[ m_0^{s+1} \left( 1 - \frac{1}{m_0} \right) \right]^c$

$$= m_0^{(s+1)c} \left[ 1 - \left( 1 - \frac{1}{m_0} \right)^c \right] = m_0^{(s+1)c} \cdot B \stackrel{\oplus4}{\geq} m^c \cdot B$$

$$\Rightarrow \text{we have: } \|m\| \geq m^c \cdot B, \quad B = 1 - \left( 1 - \frac{1}{m_0} \right)^c > 0 \quad \because m_0 \geq 2 \Rightarrow 1 - \frac{1}{m_0} \in \left[ \frac{1}{2}, 1 \right)$$

→ again we use the trick with the  $m$ -th roots to get

$$\|m\| \geq m^c \cdot \sqrt[m]{B}, \quad m \rightarrow \infty \text{ we get } \sqrt[m]{B} \rightarrow 1$$

Therefore  $\|m\| \leq m^c$  &  $\|m\| \geq m^c \Rightarrow \|m\| = m^c$  and  $\|\cdot\|$  is modified abs.-norm.

②  $\forall m \in \mathbb{N} : \|m\| \leq 1$  &  $\exists m \in \mathbb{N} : m \geq 2, \|m\| < 1$   $\Rightarrow$  let  $m_0 \geq 2$  be min. such  $m$

claim:  $m_0 = p$  is a prime number and  $\|\cdot\|$  is a  $p$ -adic norm

↳ if  $m_0 = a \cdot b$ ,  $1 < a, b < m_0$ , then  $1 > \|m_0\| = \|a \cdot b\| = \|a\| \cdot \|b\| = 1 \cdot 1 = 1$  ⚡

know:  $\|p\| =: c \in (0, 1)$  ...  $p \neq 0 \Rightarrow \|p\| \neq 0$  &  $\|p\| < 1$

claim:  $\|x\|$  is the  $p$ -adic norm  $c^{\text{ord}_p(x)}$

•  $q \neq p$  prime: we need  $\|q\| = c^{\text{ord}_p(q)} = c^0 = 1$

↳ because  $q \in \mathbb{N} : \|q\| \leq 1$  ... suffice  $\|q\| < 1$

⇒ take large  $m \in \mathbb{N}$  s.t.  $\|p\|^m, \|q\|^m < \frac{1}{2}$

Lemma 3:  $\exists a, b \in \mathbb{Z}$  s.t.  $a \cdot q^m + b \cdot p^m = 1$  ... Note:  $a \in \mathbb{Z} \Rightarrow \|a\| \leq 1$

$$\Rightarrow 1 = \|1\| = \|a q^m + b p^m\| \stackrel{\Delta\text{-ineq}}{\leq} \|a\| \cdot \|q\|^m + \|b\| \cdot \|p\|^m < 1 \cdot \frac{1}{2} + 1 \cdot \frac{1}{2} = 1 \quad \text{⚡}$$

•  $x \in \mathbb{Q}$  not prime: we need  $\|x\| = c^{\text{ord}_p(x)}$ ,  $c = \|p\|$

$$x = q_1 \cdot q_2 \cdot \dots \cdot q_m \quad \left\{ \begin{array}{l} q_i = p \Rightarrow \|q_i\| = c \\ q_i \neq p \Rightarrow \|q_i\| = 1 \end{array} \right\} \quad \|x\| = \|q_1\| \cdot \|q_2\| \cdot \dots \cdot \|q_m\| = \underline{\underline{c^{\text{ord}_p(x)}}}$$



## • Metric Spaces Revision

Def: We say that  $(a_n) \subset (X, d)$  has the limit  $a \in X \equiv$

$$(\forall \varepsilon > 0)(\exists n_0): n \geq n_0 \Rightarrow d(a_n, a) < \varepsilon$$

Notation: We write  $\lim_{n \rightarrow \infty} a_n = a$  or  $a_n \rightarrow a \rightarrow B(a, \varepsilon) = \{x \in X \mid d(a, x) < \varepsilon\}$

Def:  $M \subseteq (X, d)$  is open in  $X \equiv (\forall a \in M)(\exists \varepsilon > 0): B(a, \varepsilon) \subseteq M$ .

Def:  $M \subseteq (X, d)$  is closed in  $X \equiv \forall (a_n) \subset M: a_n \rightarrow a \Rightarrow a \in M$

☉  $\emptyset$  and  $X$  are both open & closed in  $X$

Proposition:  $M$  is open/closed in  $X \Leftrightarrow X \setminus M$  is closed/open in  $X$ .

Def:  $M \subseteq (X, d)$  is bounded in  $X \equiv (\exists a \in M)(\exists r > 0): M \subseteq B(a, r)$

Def:  $M \subseteq (X, d)$  is compact in  $X \equiv$  every sequence of  $M$  has a convergent subsequence

$$(\forall (a_n) \subset M): \exists (a_{n_k}) \subset (a_n): a_{n_k} \rightarrow a \in M$$

Theorem (Bolzano-Weierstrass): Closed bounded intervals  $[a, b] \subseteq \mathbb{R}$  are compact.

☉ In every metric space, every finite set is compact.

☉  $A, B$  compact  $\Rightarrow A \cap B$  and  $A \cup B$  compact

$A, B$  open  $\Rightarrow A \cap B$  and  $A \cup B$  open

$A, B$  closed  $\Rightarrow A \cap B$  and  $A \cup B$  closed

$A, B$  bounded  $\Rightarrow A \cap B$  and  $A \cup B$  bounded

☉  $M \subseteq (X, d)$  compact &  $A \subseteq M$  closed  $\Rightarrow A$  compact in  $X$ .

Theorem:  $M \subseteq (X, d)$  compact  $\Rightarrow M$  bounded & closed

Theorem:  $M \subseteq \mathbb{E}_n$  compact  $\Leftrightarrow M$  bounded & closed

Pf:  $\Leftarrow$ : Enclose  $M$  into a ball  $[-a, a]^n \dots M$  is bounded

$\hookrightarrow [-a, a]$  is compact &  $A, B$  compact  $\rightarrow A \times B$  compact  $\Rightarrow [-a, a]^n$  compact

$\rightarrow M \subseteq [-a, a]^n$  is closed  $\rightarrow$  compact

Proposition:  $M \subseteq (X, d)$ ,  $A \subseteq M$  is open/closed in  $M$

$$\Leftrightarrow \exists \tilde{A} \subseteq X \text{ open/closed in } X \text{ \& } A = \tilde{A} \cap M$$

↳ proof in exercises video 3

Proposition:  $M \subseteq (X, d)$ ,  $A \subseteq M$  is closed in  $X \Rightarrow A$  is closed in  $M$

$A \subseteq M$  is compact in  $X \Leftrightarrow A$  is compact in  $M$

Def: For m.s.  $(X_1, d_1), \dots, (X_n, d_n)$  define their product

$$\prod_i (X_i, d_i) = (X_1, d_1) \times \dots \times (X_n, d_n) := \left( \prod_i X_i, d \right)$$

where  $\prod_i X_i = X_1 \times \dots \times X_n$  and  $d(\tilde{x}, \tilde{y}) := \max_i d_i(x_i, y_i)$ .

Def: Metrics  $d_1, d_2$  on  $X$  are strongly equivalent  $\equiv$

$$\exists \alpha, \beta > 0: \alpha \cdot d_1(x, y) \leq d_2(x, y) \leq \beta \cdot d_1(x, y)$$

Fact: So called topological properties are preserved under changing equivalent metrics

- convergence of sequences
  - continuity of functions
  - open/closed/bounded/compact sets
- etc.

Theorem: The following metrics are strongly equivalent:

- Euclidean:  $e_n(\tilde{x}, \tilde{y}) := \sqrt{\sum_i |x_i - y_i|^2}$  ...  $L^2$
- Manhattan:  $d_1(\tilde{x}, \tilde{y}) := \sum_i |x_i - y_i|$  ...  $L^1$
- Chebyshev:  $d_\infty(\tilde{x}, \tilde{y}) := \max_i |x_i - y_i|$  ...  $L^\infty$
- general  $L^p$  metric:  $L^p(\tilde{x}, \tilde{y}) := \left( \sum_i |x_i - y_i|^p \right)^{\frac{1}{p}}$ ,  $p \geq 1$

Pf: We will show that Chebyshev is equivalent to  $L^p$  for any  $p$

$$1. \max_i |x_i - y_i| \leq \left( \sum_i |x_i - y_i|^p \right)^{\frac{1}{p}} \leq \beta \cdot \max_i |x_i - y_i| \Rightarrow \alpha = 1, \beta = n^{\frac{1}{p}}$$

$$\odot \left( \sum_{i=1}^n |x_i - y_i|^p \right)^{\frac{1}{p}} \leq \left( \sum_{i=1}^n d_\infty(\tilde{x}, \tilde{y})^p \right)^{\frac{1}{p}} = \left( n \cdot (d_\infty(\tilde{x}, \tilde{y}))^p \right)^{\frac{1}{p}} = n^{\frac{1}{p}} \cdot d_\infty(\tilde{x}, \tilde{y})$$

Corollary: In the definition of a product space, we could have used any  $L^p$  metric.

$$\hookrightarrow \text{Euclidean: } d(\tilde{x}, \tilde{y}) = \sqrt{\sum_i |d_i(x_i, y_i)|^2}$$

⊗  $E_m \times E_m = E_{m+m} \dots (\mathbb{R}^n, e_n) \times (\mathbb{R}^m, e_m) = (\mathbb{R}^{n+m}, e_{n+m})$

↳ equal up to a formality → vectors of  $E_{m+m}$  are  $v \in \mathbb{R}^{n+m} (x_1, \dots, x_{n+m})$   
 ↘ vectors of  $E_m \times E_m$  are  $v \in \mathbb{R}^n \times \mathbb{R}^m ((x_1 \dots x_n)(y_1 \dots y_m))$

Theorem: The product of compact spaces is compact.  $(X, d_X) \times (Y, d_Y)$

Pf: We have  $(a_n) \subset X \times Y$  and want a convergent subsequence

1. pick  $(a_{n_k})_k \subset (a_n)_n$  s.t. the  $x$ -part  $(x_{n_k})_k$  converges in  $X$

2. pick  $(a_{n_{k_j}})_j \subset (a_{n_k})_k$  s.t. the  $y$ -part  $(y_{n_{k_j}})_j$  converges in  $Y$  ■

## • Continuous functions

Def: The function  $f: (X, d_X) \rightarrow (Y, d_Y)$  is continuous at  $a \in X$   $\equiv$

$$(\forall \varepsilon > 0)(\exists \delta > 0): (\forall x \in X): d_X(a, x) < \delta \Rightarrow d_Y(f(a), f(x)) < \varepsilon$$

Def:  $f$  is continuous  $\equiv$  it is continuous at  $\forall a \in X$ .

Def: For  $f: X \rightarrow Y$  define

• image of  $A \subseteq X$ :  $f[A] := \{f(x) \in Y \mid x \in A\}$

• preimage of  $B \subseteq Y$ :  $f^{-1}[B] := \{x \in X \mid f(x) \in B\}$

⊗  $f: (X, d_X) \rightarrow (Y, d_Y)$  is continuous  $\Leftrightarrow$

$$(\forall a \in X)(\forall \varepsilon > 0)(\exists \delta > 0): \underline{f[B_X(a, \delta)] \subseteq B_Y(f(a), \varepsilon)}$$

Theorem (Heine):  $f: (X, d_X) \rightarrow (Y, d_Y)$  is continuous at  $a \in X \Leftrightarrow$

$$\forall (a_n) \subset X, \underline{a_n \rightarrow a} \Rightarrow \underline{f(a_n) \rightarrow f(a)} \quad \lim_{n \rightarrow \infty} f(a_n) = f(\lim_{n \rightarrow \infty} a_n)$$

Idea: The image of a convergent sequence converges to the image of the limit

Pf:  $\Rightarrow$ : claim:  $(\forall \varepsilon > 0)(\exists \underline{m_0}): (n \geq m_0 \Rightarrow d_Y(f(a_n), f(a)) < \varepsilon)$

↳ continuity of  $f$  for this  $\varepsilon$ :  $(\exists \delta > 0): d_X(a_n, a) < \delta \Rightarrow d_Y(f(a_n), f(a)) < \varepsilon$

↳ convergence of  $(a_n)$  for this  $\delta$ :  $(\exists \underline{m_0}): (n \geq m_0 \Rightarrow d_X(a_n, a) < \delta)$

$\Leftarrow$ : for contradiction:  $\exists \varepsilon > 0$  s.t.  $(\forall \delta) (\exists x \in X): d_X(x, a) < \delta \ \& \ d_Y(f(x), f(a)) \geq \varepsilon$

↳ for every  $\delta = \frac{1}{n}$  we have  $x_n \rightarrow a$  ⇒ create sequence

⊗  $x_n \rightarrow a$  but  $f(x_n) \not\rightarrow f(a)$  ■

Lemma: Let  $f: (X, d_X) \rightarrow (Y, d_Y)$  be continuous. Then

$$A \subseteq X \text{ compact} \Rightarrow f[A] \subseteq Y \text{ compact}$$

Pf: Let  $(y_n) \subset f[A]$  we want a convergent subsequence with  $\lim \in f[A]$

↳ define  $(x_n) \subset A$  s.t.  $f(x_n) = y_n$

↳  $A$  compact  $\Rightarrow$  we have  $(x_{n_k})_k \subseteq (x_n)_n$  with limit  $a \in A$

→  $f$  continuous so using Heine:  $f(x_{n_k}) = (y_{n_k})_k$  converges to  $f(a) \in f[A]$  ■

Theorem: Let  $f: (X, d) \rightarrow \mathbb{R}$  be continuous and  $A \subseteq X$  compact.

Then  $f$  attains both a min. and max. value on  $A$ .

Pf:  $f[A] \subseteq \mathbb{R}$  is compact  $\Rightarrow$  bounded  $\Rightarrow$  has a infimum  $m \in \mathbb{R}$  and sup.  $M \in \mathbb{R}$

↳ we need to show  $m, M \in f[A]$  ... let's show  $M \in f[A]$

→  $M = \sup f[A] \Rightarrow \exists (a_n) \subset A$  s.t.  $\lim_{n \rightarrow \infty} f(a_n) = M$

→  $A$  is compact  $\Rightarrow \exists (a_{n_k})_k \subseteq (a_n)_n$  s.t.  $(a_{n_k})_k \rightarrow a \in A$

→  $f$  is continuous  $\Rightarrow f(a_{n_k}) \rightarrow f(a) \in f[A]$

→ but  $f(a_n)_n$  converges to  $M$  &  $f(a_{n_k})_k$  is a subsequence of  $f(a_n)_n$

$\Rightarrow \lim_{k \rightarrow \infty} f(a_{n_k}) = \lim_{n \rightarrow \infty} f(a_n) \Rightarrow M = f(a) \in f[A]$  ■

Theorem: Equivalent definitions of continuity of  $f: (X, d_X) \rightarrow (Y, d_Y)$

①  $(\forall a \in X)(\forall \varepsilon > 0)(\exists \delta > 0): f[B(a, \delta)] \subseteq B(f(a), \varepsilon)$  ...  $\varepsilon$ - $\delta$  definition

②  $\forall (a_n) \subset X, a_n \rightarrow a: f(a_n) \rightarrow f(a)$  ... Heine's definition

③  $\forall B \subseteq Y$  open:  $f^{-1}[B]$  open

... topological definition

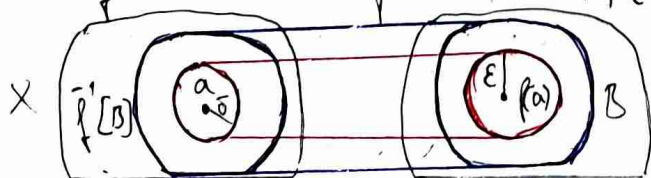
④  $\forall B \subseteq Y$  closed:  $f^{-1}[B]$  closed

Pf: We know ①  $\Leftrightarrow$  ②, let's show ①  $\Leftrightarrow$  ③.

$\Rightarrow$ : Let  $B \subseteq Y$  open and  $a \in f^{-1}[B]$ . We need to find  $\delta > 0$  s.t.  $B(a, \delta) \subseteq f^{-1}[B]$ .

↳  $B$  open &  $f(a) \in B \Rightarrow \exists \varepsilon > 0$  s.t.  $B(f(a), \varepsilon) \subseteq B$

↳  $f$  continuous  $\Rightarrow$  for this  $a \in X, \varepsilon > 0 \exists \delta > 0$  s.t.  $f[B(a, \delta)] \subseteq B(f(a), \varepsilon) \subseteq B$



↳  $f[B(a, \delta)] \subseteq B$

$\Rightarrow B(a, \delta) \subseteq f^{-1}[B]$

$\Leftarrow$ : Let  $a \in X$ ,  $\varepsilon > 0$ , we need  $\delta > 0$  s.t.  $f[B(a, \delta)] \subseteq B(f(a), \varepsilon)$

$\rightarrow$  the open ball  $B(f(a), \varepsilon)$  is open: (no shit Sherlock)

$\Rightarrow$  using ③ we have  $f^{-1}[B(f(a), \varepsilon)] =: A$  open as well

⊙  $a \in A$  &  $A$  open  $\Rightarrow \exists \delta > 0: B(a, \delta) \subseteq A$

$\Rightarrow$  therefore  $f[B(a, \delta)] \subseteq f[A] = B(f(a), \varepsilon)$  ■

Proposition: Let  $(X, d_X)$  and  $(Y, d_Y)$  be m.s. and  $M \subseteq X$ . Then

$f: (M, d_X) \rightarrow (Y, d_Y)$  is continuous  $\Leftrightarrow$

$(\forall B \subseteq Y \text{ open})(\exists A \subseteq X \text{ open}): f^{-1}[B] = M \cap A$

Pf: Recall  $R \subseteq M \subseteq X$  open in  $M \Leftrightarrow \exists \tilde{R} \subseteq X$  open in  $X$  s.t.  $R = \tilde{R} \cap M$ .

$\therefore f^{-1}[B] \subseteq M \subseteq X$  open in  $M \Leftrightarrow \exists A \subseteq X$  open in  $X$  s.t.  $f^{-1}[B] = A \cap M$

$\Rightarrow$  we are essentially saying:  $(\forall B \subseteq Y \text{ open}): (f^{-1}[B] \subseteq M \text{ open in } M)$

$\hookrightarrow$  topological definition of continuity ■

Proposition: Let  $(X, d_X)$  and  $(Y, d_Y)$  be m.s. and  $M \subseteq X$  be compact.

And let  $f: (M, d_X) \rightarrow (Y, d_Y)$  be continuous and injective.

Then the inverse  $f^{-1}: (f[M], d_Y) \rightarrow (M, d_X)$  is also continuous.

Pf: We will use the topological definition of continuity ④.

$\hookrightarrow f^{-1}$  continuous  $\Leftrightarrow$

$(\forall A \subseteq M \text{ closed in } M): (f^{-1})^{-1}[A] = f[A] \text{ is closed in } f[M]$

$\rightarrow M$  is compact &  $A \subseteq M$  closed  $\Rightarrow A$  is compact in  $M$

$\rightarrow$  continuous image of a compact set is compact  $\rightarrow f[A]$  is compact in  $f[M]$

$\rightarrow$  every compact set is closed  $\Rightarrow f[A]$  is closed in  $f[M]$  ■

Def:  $f: (X, d_X) \rightarrow (Y, d_Y)$  is a homeomorphism  $\equiv$

①  $f$  is a bijection

②  $f$  and  $f^{-1}$  are continuous

Def:  $(X, d_X)$  and  $(Y, d_Y)$  are homeomorphic  $\equiv \exists$  homeomorphism  $f: X \rightarrow Y$ .

Def: Metrics  $d_1, d_2$  are equivalent on  $X \equiv \text{id}: (X, d_1) \rightarrow (X, d_2), x \mapsto x$  is a homeomorphism.

Proposition: Strongly equivalent metrics are equivalent.

• The Heine-Borel Theorem  $\rightarrow$  all  $X_i$  open

Def: Let  $A \subseteq (M, d)$ . We call  $\{X_i\}_{i \in I}$  an open cover of  $A \equiv A \subseteq \bigcup_{i \in I} X_i$

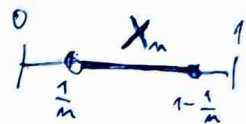
Def:  $A \subseteq (M, d)$  is topologically compact  $\equiv$  every open cover  $\{X_i\}_{i \in I}$  of  $A$  has a finite subcover  $\{X_j\}_{j \in J}$ ,  $J \subseteq I$  finite.

Example:

•  $[0, 1]$  is topologically compact ... we can always create a finite subcover

•  $(0, 1)$  is not topologically compact

$\Rightarrow$  consider sets  $\{X_n\}_{n \in \mathbb{N}}$ ,  $X_n = (\frac{1}{n}, 1 - \frac{1}{n})$



$\rightarrow$  clearly  $\bigcup_{n \in \mathbb{N}} X_n = (0, 1)$ , but there is no finite subcover

Theorem (Heine-Borel) Let  $A \subseteq (M, d)$ . Then:  $A$  compact  $\Leftrightarrow$   $A$  top. compact.

Proof: WLOG assume  $A = M$ .  $\oplus$

$\Rightarrow$ : let  $(M, d)$  be compact and let  $M = \bigcup X_i$  be its open cover.

goal: find finite subcover

Lemma: For  $\forall \delta > 0$   $\exists$  finite cover of  $M$  with open balls of radius  $\delta$

$\hookrightarrow \exists$  finite  $S_\delta \subseteq M$  s.t.  $\bigcup_{a \in S_\delta} B(a, \delta) = M$

Pf: Suppose that this doesn't hold for some  $\delta > 0$ , that is

for  $\forall$  finite  $S \subseteq M$ :  $M - (\bigcup_{a \in S} B(a, \delta)) \neq \emptyset$

Claim:  $\exists (a_n) \subset M$  s.t.  $m < n \Rightarrow d(a_m, a_n) \geq \delta$

$\Rightarrow$   $\{a_n\}$  with compactness  $\oplus$  - there is no convergent subsequence

$\hookrightarrow$  choose  $a_1 \in M$  arbitrarily. Now suppose we already have

$a_1, \dots, a_n$  and we will choose  $a_{n+1}$

$\Rightarrow$  let  $S := \{a_1, \dots, a_n\}$  and choose  $a_{n+1} \in M - (\bigcup_{a \in S} B(a, \delta)) \neq \emptyset$   $\oplus$

Lemma: Suppose  $\{X_i\}_{i \in I}$  doesn't have a finite subcover of  $M$ . Then for  $\forall n \in \mathbb{N}$ :

$\exists b_n \in S_{\frac{1}{n}}$  s.t.  $\forall i \in I$ :  $B(b_n, \frac{1}{n}) \not\subseteq X_i$   $\rightarrow$  there is a ball which isn't completely covered by any  $X_i$

Pf: Suppose that this doesn't hold for some  $n_0 \in \mathbb{N}$  and that for  $\forall b \in S_{\frac{1}{n_0}}$

$\exists i_b \in I$  s.t.  $B(b, \frac{1}{n_0}) \subseteq X_{i_b}$ . But then consider the finite ball cover

$M = \bigcup_{b \in S_{\frac{1}{n_0}}} B(b, \frac{1}{n_0}) \rightsquigarrow J := \{i_b \mid b \in S_{\frac{1}{n_0}}\} \Rightarrow \{X_j\}_{j \in J}$  finite subcover  $\nexists$   $\oplus$

Now to show " $\Rightarrow$ " suppose  $\{X_i\}$  doesn't have a finite subcover, so by the lemma we have a sequence  $(b_m) \subset M$  of ball centers.

$\Rightarrow M$  compact  $\rightarrow (b_m)$  has a convergent subsequence  $(b_k) \subset (b_m)$

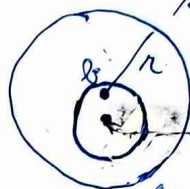
$\hookrightarrow$  denote the limit  $b := \lim_{k \rightarrow \infty} b_k \in M$

$\rightarrow$  because  $\{X_i\}$  cover  $M$ ,  $\exists j$  s.t.  $b \in X_j$

$\rightarrow X_j$  open  $\Rightarrow \exists r > 0$  s.t.  $B(b, r) \subset X_j$   $\otimes$  ... near a contradiction with the property of  $b_m$  ... lemma

$\Rightarrow$  we will take a large enough  $k$  s.t.

$$\frac{1}{2} < \frac{r}{2} \quad \& \quad d(b, b_k) < \frac{r}{2}$$



$\hookrightarrow$  by the definition of  $b_m$

$\rightarrow$  to get the contradiction, consider the ball  $B(b_k, \frac{1}{2}) \not\subset X_j$

$$\hookrightarrow x \in B(b_k, \frac{1}{2}) : d(x, b) \leq \underbrace{d(x, b_k)}_{< \frac{1}{2}} + \underbrace{d(b_k, b)}_{< \frac{r}{2}} < \frac{r}{2} + \frac{r}{2} = r$$

$\Rightarrow$  therefore  $B(b_k, \frac{1}{2}) \subset B(b, r) \subset X_j$   $\otimes$

Meaning that there has to be a finite subcover of  $\{X_i\}$

$\Leftarrow$ : let  $(M, d)$  be top. compact and let  $(a_n) \subset M$ . We want convergent  $(a_k) \subset (a_n)$ .

Lemma: Let  $(a_n) \subset M$ . Then  $\exists b \in M$  s.t.  $\forall r > 0: A_r := (a_n) \cap B(b, r)$  is infinite.

Corollary: We can clearly select a subsequence  $(a_{n_k})_k \subset (a_n)_n$  with limit  $= b$ .

$\rightarrow$  we will choose  $\forall n_k$  s.t.  $d(b, a_{n_k}) < \frac{1}{k}$

$\hookrightarrow$  suppose we already have  $a_{n_1}, a_{n_2}, \dots, a_{n_k}$  and now we want  $a_{n_{k+1}}$

$\rightarrow$  pick any  $a_i \in A_{\frac{1}{k+1}}$  s.t.  $i > n_k$  ... we can  $\because A_{\frac{1}{k+1}}$  is infinite

$\Rightarrow M$  is compact

Proof: Suppose  $(\forall b \in M)(\exists r_k > 0)$  s.t.  $A_k := (a_n) \cap B(b, r_k)$  is finite

$\rightarrow$  now consider the ball covering (we take every point of  $M$  as a center)

$M = \bigcup_{b \in M} B(b, r_b)$  and choose a finite subcovering ( $M$  top. compact)

given by the finite ball center set  $N \subset M$

$$\Rightarrow M = \bigcup_{b \in N} B(b, r_b) =: NB \quad \left( \bigcup_{b \in N} B(b, r_b) \right) \cap (a_n)$$

$\rightarrow$  consider what happens with  $A_b \dots \bigcup_{b \in N} A_b$  is finite  $\because$  finite union of finite sets

$\Rightarrow$  but  $(a_n)$  is infinite  $\Rightarrow \exists a_j \in (a_n)$  s.t.  $a_j \notin NB = M$   $\otimes$

$\hookrightarrow$  and only finitely many  $a_i$  are covered by  $NB$

## Connected sets

Def:  $M \subseteq (X, d)$  is arc connected  $\equiv \forall a, b \in M$

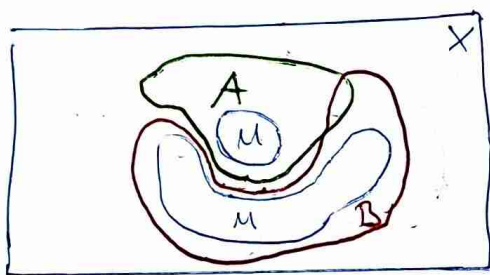
$\exists \varphi: [a, b] \rightarrow M$  continuous s.t.  $\varphi(a) = a, \varphi(b) = b$ .

Def:  $M \subseteq (X, d)$  is clopen  $\equiv$  it is closed and open

☹  $\emptyset$  and  $X$  are clopen  $\leftarrow$  trivial clopen sets

Def:  $M \subseteq (X, d)$  is connected  $\equiv$  it cannot be cut, meaning

$\nexists A, B \subseteq X$  open s.t.  $M \subseteq A \cup B$  &  $M \cap A \neq \emptyset$  &  $M \cap B \neq \emptyset$  &  $M \cap A \cap B = \emptyset$



$\rightarrow M$  is disconnected

$\rightarrow$  cut by  $A, B$

☹  $A, B$  can intersect outside  $M$

Theorem:  $(X, d)$  is connected  $\Leftrightarrow$  the only clopen subsets are  $\emptyset$  and  $X$

$M \subseteq (X, d)$  is connected  $\Leftrightarrow$  the only clopen subsets of  $(M, d)$  are  $\emptyset$  and  $M$ .

Equivalently:  $(X, d)$  is connected  $\Leftrightarrow \nexists$  nonempty clopen  $A, B \subseteq X$  s.t.  
 $X = A \cup B$  &  $A \cap B = \emptyset$

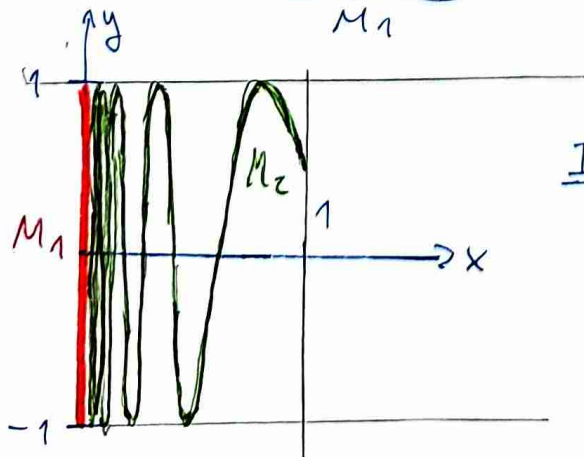
Example:  $A \subseteq \mathbb{R}$  is connected  $\Leftrightarrow$  it is a closed interval ...  $A = [a, b]$

Theorem:  $M$  arc connected  $\Rightarrow M$  connected

$M$  connected  $\nRightarrow M$  arc connected

$M$  connected & open  $\Rightarrow M$  arc connected

Example:  $M = \underbrace{\{0\} \times [-1, 1]}_{M_1} \cup \underbrace{\{(t, \sin \frac{1}{t}) \mid 0 < t \leq 1\}}_{M_2} \subseteq \mathbb{R}^2$



Intuition:

$M$  is connected

$M$  is not arc connected

Theorem: Let  $(X, d_1), (Y, d_2)$  be MS and  $f: M \subseteq X \rightarrow Y$  be continuous.  
 $M$  connected  $\Rightarrow f[M] \subseteq Y$  connected

Example: The complex unit circle is connected

$$S := \{z \in \mathbb{C} \mid |z| = 1\} \Rightarrow f: [0, 2\pi] \rightarrow \mathbb{C}, \quad f(t) = \cos t + i \sin t$$

☺  $f$  is continuous and  $f([0, 2\pi]) = S$

$\Rightarrow$  because  $[0, 2\pi]$  is connected, so is  $f([0, 2\pi]) = S$

## The Fundamental Theorem of Algebra

Lemma 1:  $(\forall x > 0)(\forall n \in \mathbb{N})(\exists y > 0): x = y^n$

$$\rightarrow y = \sqrt[n]{x}$$

we can deduce explicit formulas

Lemma 2:  $(\forall z \in \mathbb{C})(\exists u \in \mathbb{C}): z = u^2$

$$\rightarrow z = r \cdot e^{i\theta} \Rightarrow u_1 = \sqrt{r} \cdot e^{i\frac{\theta}{2}}$$

Lemma 3:  $(\forall z \in S)(\forall n \text{ odd})(\exists u \in S): z = u^n$

$$\rightarrow z = r \cdot e^{i(\theta + 2\pi)} \Rightarrow u_2 = \sqrt[n]{r} \cdot e^{i(\frac{\theta}{n} + \pi)}$$

Pf: Let  $z$  be on the unit circle, we do not want to use  $\sin$  and  $\cos$ , because they are transcendental functions, so  $z = re^{i\theta} \Rightarrow u = \sqrt[n]{r} e^{i\frac{\theta}{n}}$  is forbidden - using for complex tools.

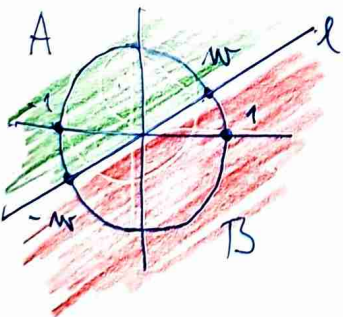
$\Rightarrow$  instead let  $z \in S$ ,  $n$  be odd and we will show that the map

$f: S \rightarrow S, \quad f(x) = x^n$ , which is clearly continuous, is surjective

$\Rightarrow$  therefore  $f^{-1}(z)$  is the  $n$  we are looking for

$\rightarrow$  for contradiction assume  $\exists w \in S \setminus f[S] \dots w$  has no  $n$ -th root

$\rightarrow$  because  $n$  is odd, we have  $-w \in S \setminus f[S] \dots$  if  $-w = f(w)$ , then  $w = f(-w)$



$\Rightarrow$  consider the line  $l \subseteq \mathbb{C}$  going through  $w$  and  $-w$

☺  $l$  divides  $\mathbb{C} \rightsquigarrow \mathbb{C} = A \cup B$ ,  $A, B$  open halfplanes

claim:  $A$  and  $B$  cut  $f[S]$  and make it disconnected

•  $f[S] \subseteq A \cup B \dots$  true  $\because f[S] \subseteq S$  &  $S \cap (A \cup B) = S \setminus \{w, -w\}$

•  $(\pm 1)^n = (\pm 1) \Rightarrow \pm 1 \in f[S]$  &  $\pm 1$  lie in different halfplanes

$$\Rightarrow f[S] \cap A \neq \emptyset \neq f[S] \cap B$$

•  $f[S] \cap A \cap B = \emptyset \because A \cap B = \emptyset$

$\rightarrow$  but  $f[S]$  is the continuous image of the connected set  $S$ , so  $f[S]$  must also be connected  $\zeta$



Theorem:  $\mathbb{C}$  contains all  $n$ -th roots

$$(\forall z \in \mathbb{C})(\forall n \in \mathbb{N})(\exists u \in \mathbb{C}): z = u^n$$

Proof: We will convert this to lemma 3. Note  $z=0$  is trivial  $\Rightarrow$  let  $z \neq 0$

① WLOG  $n$  odd: if  $n$  even, then by lemma 2 exists  $v \in \mathbb{C}$  s.t.  $z = v^2$

$\Rightarrow$  we solve the problem for  $v$  and  $\frac{n}{2} \Rightarrow$  eventually odd  $n$

② WLOG  $z \in S$ : if  $z \notin S$ , then  $z = d z'$ ,  $z' \in S$ ,  $d \in \mathbb{R}^+$

$\rightarrow$  we solve the problem for  $z' = v^n$   
 $\rightarrow$  by lemma 1 exists  $\beta \in \mathbb{R}^+$  s.t.  $d = \beta^n$   $\left. \vphantom{\begin{matrix} \rightarrow \text{we solve the problem for } z' = v^n \\ \rightarrow \text{by lemma 1 exists } \beta \in \mathbb{R}^+ \text{ s.t. } d = \beta^n \end{matrix}} \right\} z = \beta^n \cdot v^n = (\beta v)^n$   $\square$

Theorem (Fundamental Thm of Algebra): Every non-const. complex polynomial has a root.

Proof: Let  $p(z) = a_0 + a_1 z + a_2 z^2 + \dots + a_n z^n$ ,  $n \geq 1$ ,  $a_n \neq 0$

The function  $f(z) := |p(z)| : \mathbb{C} \rightarrow \mathbb{R}_0^+$  is continuous.

We will prove  $f(u) = 0$  for some  $u \in \mathbb{C}$ , then also  $p(u) = 0$  and  $u$  is a root of  $p$

Plan: ①  $f$  attains a minimal value ② that minimum is 0

① let  $K > 0$  be so large that

$$\frac{K^n |a_n|}{2} > |a_0| \quad \text{and} \quad \sum_{j=0}^{n-1} |a_j| K^{j-n} < \frac{|a_n|}{2}$$

Then for  $\forall z \in \mathbb{C}$  we have the estimate that if  $|z| > K$ , then

$$\begin{aligned} f(z) &= |p(z)| = |a_0 + a_1 z + a_2 z^2 + \dots + a_n z^n| = \\ &= |z^n| \cdot |a_n + a_0 z^{-n} + a_1 z^{1-n} + \dots + a_{n-1} z^{-1}| = |z^n| \cdot \left| a_n + \sum_{j=0}^{n-1} a_j z^{j-n} \right| \end{aligned}$$

$$\begin{aligned} |a_n + r| &\geq |a_n| - |r| \\ |a_n + r| &\geq |a_n| - \sum_{j=0}^{n-1} |a_j| \cdot |z|^{j-n} > |z|^n \left( |a_n| - \frac{|a_n|}{2} \right) > |a_0| \end{aligned}$$

Therefore  $|z| > K: f(z) > |a_0| = |p(0)| = f(0)$

$\Rightarrow$  We define the rectangle  $R = \{a + bi \mid -K \leq a, b \leq K\} \subseteq \mathbb{C}$ .

•  $z \in \mathbb{C} \setminus K \Rightarrow |z| > K \Rightarrow f(z) > f(0)$

•  $R$  is compact  $\Rightarrow f$  attains a minima on  $R \Rightarrow \exists u \in R, f(u)$  min. on  $R$

$\hookrightarrow$  since  $0 \in R: f(u) \leq f(0) \Rightarrow \forall z \in \mathbb{C}: f(u) \leq f(z) \Rightarrow f(u)$  min on  $\mathbb{C}$

② claim:  $f(u) = 0$

→ we rewrite the polynomial  $p(z)$  as  $p(z) = \sum_{j=0}^n b_j (z-u)^j$ ,  $b_j \in \mathbb{C}$ ,  $b_n = a_n$

☞  $f(u) = |p(u)| = |b_0| \dots$  need  $b_0 = 0$

→ suppose that  $b \neq 0 \Rightarrow |b_0| > 0$

⇒ we find the first non-zero coefficient  $b_k$  in  $p(z) \dots$

$$p(z) = b_0 + b_k (z-u)^k + \underbrace{b_{k+1} (z-u)^{k+1} + \dots + b_n (z-u)^n}_{q(z)}$$

$b_0 \neq 0, b_k \neq 0$

We use the theorem about roots in  $\mathbb{C}$  and solve  $\alpha \in \mathbb{C}$  s.t.  $\alpha^k = -\frac{b_0}{b_k}$

☞  $\lim_{z \rightarrow u} \frac{q(z)}{\frac{b_k}{2} (z-u)^k} = 0 \dots q(z)$  has higher powers  $\Rightarrow$  goes to 0 quicker

Now we solve  $v = u + \delta \cdot \alpha$ ,  $\delta > 0$  very small, so  $v-u = \delta \cdot \alpha \rightarrow 0$

$$\Rightarrow |q(v)| < \frac{|b_k|}{2} |z-v|^k = \frac{|b_k|}{2} |\delta \alpha|^k = \frac{|b_k|}{2} \cdot \delta^k \cdot \left| -\frac{b_0}{b_k} \right| = \delta^k \cdot \frac{|b_0|}{2}$$

We get the contradiction that  $f(v) < f(u)$ :

$$f(v) = |p(v)| = |b_0 + b_k \alpha^k \delta^k + q(v)|$$

$$\alpha^k b_k = -b_0 \quad : \quad = |b_0 - b_0 \delta^k + q(v)| = |b_0(1 - \delta^k) + q(v)|$$

$$\Delta\text{-ineq:} \quad \leq |b_0| \cdot (1 - \delta^k) + |q(v)| \quad \leftarrow \in (0,1)$$
$$\leq |b_0| \cdot (1 - \delta^k) + \delta^k \frac{|b_0|}{2} = |b_0| \left( 1 - \frac{\delta^k}{2} \right) < |b_0|$$

⇒ we have  $f(v) < |b_0| = f(u)$  ☹

☐

# Complete Spaces

Def: The sequence  $(a_n)$  is Cauchy  $\equiv (\forall \epsilon > 0)(\exists n_0) : n, m \geq n_0 \Rightarrow d(a_n, a_m) < \epsilon$

👁 Every convergent sequence is Cauchy.

👁 Not every Cauchy sequence is convergent

$\hookrightarrow \mathbb{Q}$ ,  $(a_n) = (1, 1.4, 1.41, 1.414, \dots) \rightsquigarrow \sqrt{2} \notin \mathbb{Q}$

Def: The metric  $(M, d)$  is complete  $\equiv$  every Cauchy  $(a_n) \subset M$  converges.

The set  $X \subseteq M$  is complete  $\equiv$  the subspace  $(X, d)$  is complete.

## Properties:

①  $X \subseteq Y \subseteq (M, d)$ :  $X$  complete in  $(Y, d) \iff X$  complete in  $(M, d)$

②  $(M_1, d_1), (M_2, d_2)$  complete  $\Rightarrow (M_1, d_1) \times (M_2, d_2)$  complete

③  $(M, d)$  complete &  $X \subseteq M$  closed  $\Rightarrow$   $X$  complete

$\hookrightarrow (a_n) \subset X$  Cauchy  $\Rightarrow$  converges in  $M$ , but  $X$  is closed so converges to  $\lim a_n = a \in X \Rightarrow X$  complete

④  $(M, d)$  compact  $\Rightarrow (M, d)$  complete

$\hookrightarrow$  proof in the back - vol 4

⑤  $(M, d)$  complete  $\not\Rightarrow (M, d)$  compact ... Take  $\mathbb{R}$

$\Rightarrow$  closed ...  $\nexists$  convergent  $(a_n)$  is Cauchy

$\not\Rightarrow$  bounded ...  $\mathbb{R}$

⑥  $\mathbb{R}$  is complete  $\iff$  axiom of suprema

⑦  $(M, d)$  finite  $\Rightarrow (M, d)$  complete ... finite  $\Rightarrow$  compact  $\Rightarrow$  complete

⑧  $M_1, M_2$  complete  $\Rightarrow M_1 \cap M_2, M_1 \cup M_2$  complete

- countable union doesn't have to be complete
- infinite intersection is always complete

## Dense and Sparse Sets

Def:  $X \subseteq (M, d)$  is dense in  $M \equiv (\forall a \in M)(\forall r > 0) : B(a, r) \cap X \neq \emptyset$   
→ every ball in  $M$  intersects with  $X$  ...  $\mathbb{Q}, \mathbb{R} - \mathbb{Q}$  in  $\mathbb{R}$

Def:  $X \subseteq (M, d)$  is sparse in  $M \equiv (\forall a \in M)(\forall R > 0) :$

$$(\exists b \in B(a, R))(\exists r > 0) : B(b, r) \subseteq B(a, R) \text{ \& } B(b, r) \cap X = \emptyset$$

→ every ball in  $M$  contains a subball disjoint from  $X$  ...  $\mathbb{Z}$  in  $\mathbb{R}$

Properties:  $\nexists X \text{ not sparse} \Rightarrow X \text{ dense} !$

$$\textcircled{1} X \subseteq (M, d) \text{ dense} \Leftrightarrow (\forall a \in M) : \exists (x_n) \subset X \text{ s.t. } x_n \rightarrow a$$

$$\textcircled{2} X \subseteq Y \text{ dense in } Y \text{ \& } Y \subseteq M \text{ dense in } M \Rightarrow X \text{ dense in } M$$

$$\textcircled{3} A, B \subseteq (M, d) \text{ sparse} \Rightarrow A \cap B, A \cup B \text{ sparse}$$

- infinite intersection is sparse ... the set doesn't get bigger
- infinite union doesn't have to be sparse

$$\textcircled{4} A, B \subseteq (M, d) \text{ dense} \Rightarrow A \cup B \text{ dense} \dots \text{obviously}$$

$$\nRightarrow A \cap B \text{ dense}$$

↳ \&  $A$  open  $\Rightarrow A \cap B$  dense ... at least one needs to be open

## Closure of a Set

Def: The closure of  $M \subseteq (X, d)$  can be equivalently defined as

$$\overline{M} := \bigcap \{A \subseteq X \mid A \text{ closed \& } M \subseteq A\} \quad M := \{x \in X \mid \exists (x_n) \subset M : (x_n) \rightarrow x\}$$

$$\downarrow \overline{M} := \{x \in X \mid d(x, M) = 0\} \quad M := \{x \in X \mid \forall \varepsilon > 0 : B(x, \varepsilon) \cap M \neq \emptyset\}$$

Def:  $d(x, M) := \inf \{d(x, a) \mid a \in M\}$ ,  $d(A, B) := \inf \{d(a, b) \mid a \in A, b \in B\}$

Properties:

→ we need compactness?

$$\textcircled{1} A \text{ closed, } B \text{ compact} \Rightarrow (d(A, B) = 0 \Leftrightarrow A \cap B \neq \emptyset)$$

$$\textcircled{2} \overline{M} \text{ is closed} \quad \textcircled{3} M = \overline{M} \Leftrightarrow M \text{ closed} \quad \textcircled{4} \overline{\emptyset} = \emptyset, \overline{X} = X$$

$$\textcircled{5} \overline{\overline{M}} = \overline{M}, M \subseteq \overline{M}, \overline{A \cap B} = \overline{A} \cap \overline{B}, \overline{A \cup B} = \overline{A} \cup \overline{B}$$

## Baire's Theorem

Notation:  $\overline{B}(a, r) := \overline{B}(a, r)$  ... closed ball

⊗  $r < R \Rightarrow \overline{B}(a, r) \subsetneq \overline{B}(a, R)$

Theorem: Let  $(X, d_X), (Y, d_Y)$  be MSs. and  $M \subseteq X$  be dense

Let  $f, g: X \rightarrow Y$  be continuous and let  $f|_M = g|_M$ . Then  $f = g$ .

Intuition: The global behavior of a continuous function is fully determined by its behavior on any dense subset

$\Rightarrow$  if we know  $f$  on  $\mathbb{Q}$ , we know  $f$  on  $\mathbb{R}$

Proof: Let  $x \in X$  be arbitrary ... we want  $f(x) = g(x)$ .

$M$  dense  $\Rightarrow \exists (a_n) \subset M$  s.t.  $\lim a_n = x$

Heine's def. of continuity:  $f(x) = \lim f(a_n) = \lim g(a_n) = g(x)$  □

Recall: A countable union of sparse sets can be non-sparse ( $\neq$  dense)

$\Rightarrow$  it is possible to escape sparsity

Baire: but it is impossible to reach completeness

Theorem (Baire): No complete metric space is a countable union of sparse sets.

$$(M, d) \text{ complete} \quad \& \quad M = \bigcup_{i=1}^{\infty} X_i \quad \Rightarrow \quad \exists X_j \text{ not sparse}$$

Proof: For contradiction assume that all  $X_i$  are sparse in  $M$ .

$\rightarrow$  we will construct a sequence of nested closed balls  $(\overline{B}_n)$  with centers  $(c_n) \subset M$  converging to  $a \in M$  s.t.  $\forall i: a \notin X_i \Rightarrow a \notin \bigcup X_i$  ⊗

$\rightarrow$  let  $B(b, 1)$  be arbitrary

$\rightarrow X_1$  is sparse  $\Rightarrow \exists$  subball  $B(c_1, s_1) \subseteq B(b, 1)$  disjoint from  $X_1$

$\Rightarrow$  set  $\overline{B}_1 := \overline{B}(c_1, r_1)$  where  $r_1 = \min(\frac{s_1}{2}, \frac{1}{2}) \leq \frac{1}{2}$

⊗  $\overline{B}_1 \subsetneq B(c_1, s_1) \Rightarrow \overline{B}_1 \cap X_1 = \emptyset$

$\rightarrow$  suppose that we have already defined the closed balls  $\overline{B}_1 \supsetneq \overline{B}_2 \supsetneq \dots \supsetneq \overline{B}_n$  s.t. for  $\forall i: \overline{B}_i \cap X_i = \emptyset$  &  $r_i \leq \frac{1}{2^i}$

→ since  $X_{n+1}$  is sparse  $\Rightarrow \exists$  subball  $B(c_{n+1}, r_{n+1}) \subseteq B(c_n, r_n)$   
disjoint from  $X_{n+1}$

$\Rightarrow$  define  $\bar{B}_{n+1} := \bar{B}(c_{n+1}, r_{n+1})$  where  $r_{n+1} := \min(\frac{r_n}{2}, \frac{1}{2^{n+1}}) \leq \frac{1}{2^{n+1}}$

⊙  $\bar{B}_{n+1} \not\subseteq B(c_{n+1}, r_{n+1}) \Rightarrow \bar{B}_{n+1} \cap X_{n+1} = \emptyset$  &  
 $\Rightarrow \bar{B}_{n+1} \not\subseteq \bar{B}_n$

⊙ the sequence of the centers  $(c_n) \subset M$  is Cauchy  
 $m \geq n \Rightarrow \bar{B}_m \not\subseteq \bar{B}_n \Rightarrow d(c_m, c_n) \leq r_n \leq \frac{1}{2^n}$  ← arbitrarily small

→  $(M, d)$  is complete  $\Rightarrow (c_n)$  converges to some  $a \in M$

→ since all the balls are nested:  $\bar{B}_1 \supseteq \bar{B}_2 \supseteq \dots \supseteq \bar{B}_n \supseteq \dots$

the limit of the centers  $a \in \bar{B}_i$  for  $\forall i$  ... because the balls are closed sets

$\Rightarrow$  for  $\forall i: a \in \bar{B}_i \Rightarrow a \notin X_i$

$\Rightarrow$  always contain the limit

$\Rightarrow a$  lies in none of the sets  $X_i$  &



## Isolated Points

Def:  $a \in (M, d)$  is isolated  $\equiv \exists r > 0$  s.t.  $B(a, r) = \{a\}$

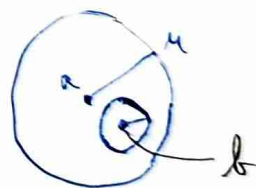
Lemma:  $a \in M$  is not isolated  $\Leftrightarrow \{a\}$  is sparse in  $M$ .

Pf:  $\Rightarrow$ : Suppose  $\forall r > 0: B(a, r) \supseteq \{a, b\}, b \in M$

claim: every ball in  $M$  has a subball without  $a$

$\Leftarrow$ : let  $r > 0$ , then  $B(a, r)$  has a subball without  $a$

$\Rightarrow$  the center of the subball  $\neq a$  & is in  $B(a, r)$



Theorem: Every complete metric space without isolated points is uncountable.

Proof: Suppose that  $(M)$  was countable, then

$M = \bigcup_{a \in M} \{a\}$  is a countable union

Since each  $a \in M$  is not isolated  $\Rightarrow$  all  $\{a\}$  are sparse

$\Rightarrow$  contradiction with Baire's theorem &



## Non-differentiable Continuous Functions

Def: Let  $I = [\alpha, \beta]$ . Denote  $C[I] := \{f: I \rightarrow \mathbb{R} \mid f \text{ continuous}\}$

Def (Punctured neighborhood):  $x \in \mathbb{R}, \delta > 0: P(x, \delta) := (x - \delta, x + \delta) \setminus \{x\}$

Def:  $f: I \rightarrow \mathbb{R}$  is differentiable at  $x \in I \equiv$  it has a finite derivative  $f'(x) \in \mathbb{R}$

Theorem (Wild functions exist): From now on let  $I = [0, 1]$ .

There is a function  $f \in C[I]$  s.t. for  $(\forall x \in I)(\forall \delta > 0)$ :

$$\sup \left\{ \left| \frac{f(y) - f(x)}{y - x} \right| \mid y \in P(x, \delta) \cap I \right\} = +\infty$$

👁  $f$  is continuous on  $I$  but it is not differentiable at any  $x \in I$ .

Proof Idea: ↙ maxim metric

① Show that  $C := (C[I], \|f - g\|_\infty)$  is a complete metric space

② Define function sets  $A_n \subseteq C[I]$  s.t.

$$A_n = \left\{ f \in C[I] \mid (\exists x \in I)(\forall y \in I \setminus \{x\}) : \left| \frac{f(y) - f(x)}{y - x} \right| \leq n \right\}$$

③ Show that  $\forall A_n$  is sparse in  $C$

④ Apply Baire's Theorem:  $C$  is complete &  $A_n$  sparse  $\Rightarrow$

$$\exists f \in C[I] \setminus \bigcup_{n=1}^{\infty} A_n$$

⑤ Show that if  $f$  has the property that for  $\forall x \in I$ :

$$\sup \left\{ \left| \frac{f(y) - f(x)}{y - x} \right| \mid y \in I \setminus \{x\} \right\} = +\infty$$

Then  $f$  has the property described in the theorem and we are done ■

Def: The function maxim metric on  $C[I]$  is defined as

$$\|f - g\|_\infty := \sup \{ |f(x) - g(x)| \mid x \in I \}$$

👁 This is a metric ... we use the  $\Delta$ -ineq for the absolute value

$$\Rightarrow |a - b| \geq |a| - |b| \quad \because |a| \leq |b| + |a - b|$$

$\parallel$   
 $b + a - b$

Theorem: The metric space  $(C[I], \|f-g\|_\infty)$  is complete.

Proof: Let  $(f_n) \subset C[I]$  be a Cauchy sequence, that is

$$(\forall \varepsilon > 0)(\exists n_0) : n, m \geq n_0 \Rightarrow \|f_n - f_m\| < \varepsilon \quad (*)$$

Therefore for  $\forall x \in I$  is the sequence  $(f_n(x)) \subset \mathbb{R}$  also Cauchy  
 $\rightarrow$  because  $\mathbb{R}$  is complete, it is also convergent and we can define a new function

$$f: I \rightarrow \mathbb{R}, \quad f(x) := \lim_{n \rightarrow \infty} f_n(x)$$

  $f$  has the property that point-wise  $f_n \rightarrow f$  **(\*\*)**

claim:  $f_n \rightarrow f$  uniformly, that is  $\|f - f_n\| \rightarrow 0$

$\Rightarrow$  let  $\varepsilon > 0$  be given. claim:  $\exists N$  s.t. for  $\forall x \in I$ :  $n \geq N \Rightarrow |f_n(x) - f(x)| < \varepsilon$

• take  $n_0$  s.t. **(\*)** holds with  $\frac{\varepsilon}{2}$

• take  $n \geq n_0$  s.t.  $|f_n(x) - f(x)| < \frac{\varepsilon}{2}$  **(\*\*)**  $\leftarrow$  specific  $x \in I$

$\rightarrow$  now for  $\forall n \geq n_0$  we have

$$\begin{array}{ccccccc} |f_n(x) - f(x)| & \leq & |f_n(x) - f_m(x)| & + & |f_m(x) - f(x)| & < & \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon \\ a - b & & a - z & & z - b & & \end{array}$$

$\rightarrow$  we can set  $N := n_0$  and this works for  $\forall x \in I$

$\rightarrow$  we have shown that  $(f_n)$  converges to some function  $f$ , but for completeness we need  $f \in C[I]$  ...  $f$  is continuous

claim:  $f$  is continuous in  $I$

$\Rightarrow$  let  $x_0 \in I$  and  $\varepsilon > 0$  be given.

$\rightarrow$  we need:  $\exists \delta > 0$  s.t.  $\forall x \in I$ :  $|x - x_0| < \delta \Rightarrow |f(x) - f(x_0)| < \varepsilon$

• take  $n_0$  s.t.  $n \geq n_0 \Rightarrow \|f - f_n\| \leq \frac{\varepsilon}{3}$   $\square$  ...  $\|f - f_n\| \rightarrow 0$

•  $f_{n_0}$  is continuous  $\Rightarrow$  take  $\delta > 0$  s.t.

$$\forall x \in I : |x - x_0| < \delta \Rightarrow |f_{n_0}(x) - f_{n_0}(x_0)| < \frac{\varepsilon}{3} \quad \boxplus$$

$$\Rightarrow \text{we have: } \begin{array}{ccccccc} |f(x) - f(x_0)| & \leq & |f(x) - f_{n_0}(x)| & + & |f_{n_0}(x) - f_{n_0}(x_0)| & + & |f_{n_0}(x_0) - f(x_0)| < \varepsilon \\ a - b & & a - z_1 & & z_1 - z_2 & & z_2 - b \end{array}$$

$$\square < \varepsilon/3 \quad \boxplus < \varepsilon/3 \quad \boxminus < \varepsilon/3$$



## Series Recap

Def: A series  $\sum a_n = \sum_{n=1}^{\infty} a_n$  is a sequence  $(a_n) \subset \mathbb{R}$  to which we assign the partial sums  $(s_n) \subset \mathbb{R}$ ,  $s_n = a_1 + \dots + a_n$ .

The sum of a series  $\sum a_n$  is  $\lim_{n \rightarrow \infty} s_n$ , if this limit exists

- a series is called  $\begin{cases} \text{convergent} \equiv \lim s_n \text{ exists and is finite} \\ \text{divergent} \equiv \lim s_n \text{ doesn't exist or is infinite} \end{cases}$

Theorem (necessary condition of convergence): If  $\sum a_n$  converges, then  $(a_n) \rightarrow 0$

Pf: Otherwise  $s_n$  never stabilises

## Examples

- $\sum \frac{1}{n} = +\infty$ ,  $\sum \frac{1}{n(n+1)} = 1$ ,  $\sum \frac{1}{n^2} = ? \dots \frac{\pi^2}{6}$
- $q \in (-1, 1) \Rightarrow \sum_{n=0}^{\infty} q^n = \frac{1}{1-q}$

## Riemann Rearrangement Theorem

Def:  $\sum a_n$  is called a Riemann series  $\equiv$

①  $(a_n) \rightarrow 0$  ... necessary condition

②  $\sum a_n^+ = +\infty$ ,  $(a_n^+) \subset (a_n)$  is subsequence of positive terms

③  $\sum a_n^- = -\infty$ ,  $(a_n^-) \subset (a_n)$  is subsequence of negative terms

Theorem (Riemann): Let  $\sum a_n$  be a Riemann series. Then for  $\forall S \in \mathbb{R}^* = \mathbb{R} \cup \{\pm\infty\}$

there is a way to rearrange the sequence  $(a_n)$

$\rightarrow$  formally, there is a bijection  $\pi: \mathbb{N} \rightarrow \mathbb{N}$  s.t.

$$\sum_{n=1}^{\infty} a_{\pi(n)} = S \quad \dots \text{by reordering the RS we can get any sum}$$

Example: Alternating harmonic series  $\sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n} = \ln(2)$  is Riemann.

Def:  $\sum a_n$  is absolutely convergent  $\equiv \sum |a_n|$  is convergent

Theorem: Every convergent series is either

① absolutely convergent

② a Riemann series

$\swarrow$  conditionally convergent

# Fourier Series - for details see notes from Fourier Analysis

Def:  $f: [a, b] \rightarrow \mathbb{R}$  is piece-wise smooth (p-w.  $C^1$ )  $\equiv$

- ① it has only finitely many discontinuities
- ② on each interval of continuity it is  $C^1$
- ③ at discontinuities, it has finite one-sided limits and derivatives

Def: For a  $l$ -periodic function  $f$  we define its Fourier series as the function

$$\underline{F_f(x) := \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos\left(\frac{2\pi n x}{l}\right) + \sum_{n=1}^{\infty} b_n \sin\left(\frac{2\pi n x}{l}\right)}$$

Where (for arbitrary  $x_0$ )

$$a_0 = \frac{2}{l} \int_{x_0}^{x_0+l} f(x) dx, \quad a_n = \frac{2}{l} \int_{x_0}^{x_0+l} f(x) \cos\left(\frac{2\pi n x}{l}\right) dx, \quad b_n = \frac{2}{l} \int_{x_0}^{x_0+l} f(x) \sin\left(\frac{2\pi n x}{l}\right) dx$$

Theorem (Dirichlet): Let  $f: \mathbb{R} \rightarrow \mathbb{R}$  be  $l$ -periodic.

If  $f$  is piece-wise smooth on one period, then for  $\forall a \in \mathbb{R}$

- $f$  continuous at  $a \Rightarrow F_f(a) = f(a)$
- $f$  has discontinuity at  $a \Rightarrow F_f(a) = \frac{1}{2}(f(a+0) + f(a-0))$  ↖ one-sided limits

Theorem (Bessel's inequality): If  $f$  has a Fourier series, then

$$\frac{1}{l} \int_{x_0}^{x_0+l} |f(x)|^2 dx = \left(\frac{a_0}{2}\right)^2 + \sum_{n=1}^{\infty} \frac{a_n^2 + b_n^2}{2}$$

Theorem (Basel problem):  $\zeta(2) = \sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6}$

Proof: Consider  $f(x) = x^2$ ,  $x \in [-\pi, \pi]$ ,  $f(x+2\pi) = f(x)$

$$\rightarrow f \text{ even} \Rightarrow f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos\left(\frac{2\pi n x}{l}\right) \quad \xrightarrow{\frac{2\pi n x}{l} = nx} \quad l = 2\pi$$

$$\bullet a_0 = \frac{1}{\pi} \int_{-\pi}^{\pi} x^2 dx = \frac{1}{\pi} \left[ \frac{x^3}{3} \right]_{-\pi}^{\pi} = \frac{2}{3} \pi^2$$

$$\bullet a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} x^2 \cos(nx) dx = \frac{2}{\pi} \left[ \frac{x^2}{n} \sin(nx) + \frac{2x}{n^2} \cos(nx) - \frac{2}{n^3} \sin(nx) \right]_0^{\pi} \\ = \frac{2}{\pi} \left[ 0 + \frac{2\pi}{n^2} \cos(\pi n) \right] = \frac{4}{n^2} \cdot (-1)^n$$

$$\rightarrow f(\pi) = \pi^2 = F_f(\pi) = \frac{\pi^2}{3} + \sum_{n=1}^{\infty} \frac{4}{n^2} (-1)^n \cos(\pi n) \Rightarrow \frac{2\pi^2}{3} = \sum_{n=1}^{\infty} \frac{4}{n^2} = 4 \zeta(2) \Rightarrow \underline{\underline{\zeta(2) = \frac{\pi^2}{6}}}$$

Note:

$$\underline{f \text{ odd}} \Rightarrow \underline{a_n = 0}$$

$$\underline{f \text{ even}} \Rightarrow \underline{b_n = 0}$$

|         |                                       |               |
|---------|---------------------------------------|---------------|
|         | $\frac{1}{2}$                         | $\frac{1}{2}$ |
| $+ x^2$ | $\rightarrow \cos(nx)$                |               |
| $- 2x$  | $\rightarrow \frac{1}{n} \sin(nx)$    |               |
| $+ 2$   | $\rightarrow -\frac{1}{n^2} \cos(nx)$ |               |
| $- 0$   | $\rightarrow -\frac{1}{n^3} \sin(nx)$ |               |

# Random Walks in $\mathbb{Z}^d$

## Definitions:

• a graph is  $(V, E)$ ,  $E \subseteq \binom{V}{2}$

$$\rightarrow N(v) := \{u \in V \mid uv \in E\}$$

•  $G$  is  $k$ -regular  $\equiv \forall$  vertex has  $k$  neighbors

•  $G$  is locally finite  $\equiv \forall$  vertex has finitely many neighbors

• a walk  $w$  in  $G$  with start  $v_0$  is any

•  $w = (v_0, v_1, \dots, v_n) \rightsquigarrow |w| = n$

•  $w = (v_0, v_1, \dots)$  s.t.  $\forall v_i v_{i+1} \in E$

• a recurrent walk revisits the start  $\dots \exists i \neq 0 : v_i = v_0$

## Def:

$$d_n(v_0, G) := \# \text{ walks } w \text{ with start } v_0 \text{ and } |w| = n$$

$$a_n(v_0, G) := \# \text{ recurrent walks } w \text{ with start } v_0 \text{ and } |w| = n$$

👁 If  $G$  is  $k$ -regular, then for  $\forall v_0 : d_n(v_0, G) = k^n$

Def: An automorphism of the graph  $G$  is a bijection  $f: V \rightarrow V$  s.t.

$$(\forall u, v \in V) : uv \in E \Leftrightarrow f(u)f(v) \in E$$

Def:  $G$  is vertex transitive  $\equiv (\forall u, v \in V) (\exists \text{ automorphism } f) : f(u) = v$ .

Intuition: All vertices behave identically w.r.t. the edge relation

Proposition: The number of walks in a vertex transitive graph doesn't depend on the start (all vertices behave the same).

$\Rightarrow$  if  $G$  is transitive and locally finite, then  $\forall u, v$ :  $d_n(u, G) = d_n(v, G)$   
 $a_n(u, G) = a_n(v, G)$

Notation: In transitive graphs we can denote the number of walks and number of recurrent walks of length  $n$  from any start simply as

$$\underline{a_n(G)} := a_n(v_0, G), \quad \underline{d_n(G)} := d_n(v_0, G)$$

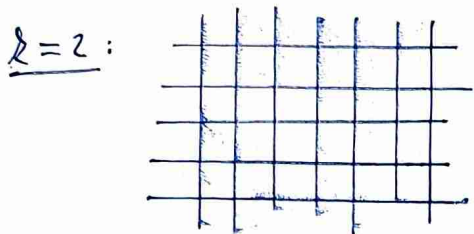
👁 The infinite path  $P := (\mathbb{Z}, \{e_{m, m+1} \mid m \in \mathbb{Z}\})$  is a transitive graph

👁 every transitive locally finite graph is  $k$ -regular for some  $k \in \mathbb{N}$

Def: We can generalize the path graph into an infinite square mesh as

$$\underline{\mathbb{Z}^k} := (\mathbb{Z}^k, \{ \{\tilde{u}, \tilde{v}\} \mid \sum_{i=1}^k |u_i - v_i| = 1 \}) \quad , \quad \tilde{x} = (u_1, \dots, u_k)$$

$\hookrightarrow \tilde{u}, \tilde{v} \in E \equiv$  they have all coordinates the same except for one, in which they differ by 1



$\hookrightarrow k$  coordinates can differ in 2 directions

☞  $\mathbb{Z}^k$  is vertex transitive and  $2k$ -regular  $\Rightarrow d_n(\mathbb{Z}^k) = (2k)^n$

Theorem (G. Pólya 1921): For  $k=1$  and  $k=2$  it holds that

$$\lim_{n \rightarrow \infty} \frac{a_n(\mathbb{Z}^k)}{d_n(\mathbb{Z}^k)} = 1 \quad \dots \text{a long random walk will almost surely revisit the start at some point}$$

But for  $k \geq 3$  it holds

$$\lim_{n \rightarrow \infty} \frac{a_n(\mathbb{Z}^k)}{d_n(\mathbb{Z}^k)} < 1 \quad \dots \text{a long random walk never returns to the start with nonzero probability}$$

Theorem (weak Abel's thm): If a power series

$$\hookrightarrow P[\text{escape}] \sim 1 - \frac{1}{2k}, \quad k \rightarrow \infty$$

$$A(x) = \sum_{n=0}^{\infty} a_n x^n \in \mathbb{R}[[x]]$$

has a radius of convergence  $\geq \rho \in \mathbb{R}^+$  ... it converges for  $\forall x \in [0, \rho)$

and all  $a_n \geq 0$ , then we can define  $A(\rho)$  as

$$A(\rho) := \lim_{x \rightarrow \rho^-} A(x) = \sum_{n=0}^{\infty} a_n \rho^n \in [0, \infty) \cup \{+\infty\}$$

$\hookrightarrow$  equality holds no matter if  $A(\rho)$  is finite or  $+\infty$

Proof: for  $\forall N \in \mathbb{N}$  we have

$$\sum_{n=0}^N a_n \rho^n = \lim_{x \rightarrow \rho^-} \sum_{n=0}^N a_n x^n \leq \lim_{x \rightarrow \rho^-} A(x) = \lim_{x \rightarrow \rho^-} \sum_{n=0}^{\infty} a_n x^n \leq \sum_{n=0}^{\infty} a_n \rho^n$$

The limit transition  $N \rightarrow +\infty$  gives

$$\sum_{n=0}^{\infty} a_n \rho^n \leq \lim_{x \rightarrow \rho^-} A(x) \leq \sum_{n=0}^{\infty} a_n \rho^n \quad \Rightarrow \text{they are equal} \quad \square$$

Proof of Polya's theorem for  $k=2$  - we will not show the general case

→ we will WLOG consider walks starting in the origin  $\sigma$

⇒ let  $k=2$  and  $w = (v_0, v_1, \dots, v_m)$ ,  $v_0 = \sigma$ ,  $|w| = m$

•  $d_m = \# \text{ walks } w$ ,  $d_0 = 1$

•  $a_m = \# \text{ walks } w \text{ s.t. } \exists j \neq 0 : v_j = \sigma$ ,  $a_0 = 0$

•  $b_m := \# \text{ walks } w \text{ s.t. } v_m = \sigma$ ,  $b_0 = 1$

•  $c_m := \# \text{ walks } w \text{ s.t. } v_m = \sigma \text{ \& } \forall 0 < i < m : v_i \neq \sigma$ ,  $c_0 := 0$

👁  $c_m \leq b_m \leq d_m$ ,  $a_m \leq d_m$ ,  $d_m = 4^m$

→ we now split recurrent walks ( $a_m$ ) into groups based on the first  $v_j = \sigma$

$$a_m = \sum_{j=0}^m \overset{c_0=0}{c_j} d_{m-j} = \sum_{j=0}^m c_j 4^{m-j} = 4^m \sum_{j=0}^m \frac{c_j}{4^j} = d_m \cdot \sum_{j=0}^m \frac{c_j}{4^j}$$

$$\Rightarrow \sum_{j=0}^m \frac{c_j}{4^j} = \frac{a_m}{d_m} \leq 1, \text{ we want } \frac{a_m}{d_m} \rightarrow 1 \text{ as } m \rightarrow \infty$$

$$\Rightarrow \text{it is sufficient to prove that } \sum_{j=0}^{\infty} \frac{c_j}{4^j} = 1 \quad \text{⊗}$$

→ we will use generating functions and formal power series

$$B(x) := \sum_{n=0}^{\infty} b_n x^n, \quad C(x) := \sum_{n=0}^{\infty} c_n x^n$$

→ when we look at the structural equation of  $B$ , we can see that

$\mathcal{C}$  = walks that revisit  $\sigma$  only once - at the end

$\mathcal{C}^2$  = walks that revisit  $\sigma$  exactly 2 times, one of which is at the end

$\mathcal{B}$  = walks that visit  $\sigma$  at least once, one of the visits — " —

$$\Rightarrow \mathcal{B} = \{\emptyset\} + \mathcal{C} + \mathcal{C}^2 + \mathcal{C}^3 + \dots \quad \text{Note: } \{\emptyset\} \text{ counts } w = (v_0) \in \mathcal{B} \notin \mathcal{C}^k$$

$$\Rightarrow B(x) = 1 + C(x) + C(x)^2 + \dots = \frac{1}{1-C(x)}$$

$$\Rightarrow \text{plug in } x/4: \quad C\left(\frac{x}{4}\right) = \sum_{n=0}^{\infty} \frac{c_n}{4^n} x^n, \quad B\left(\frac{x}{4}\right) = \sum_{n=0}^{\infty} \frac{b_n}{4^n} x^n$$

→ because  $c_n \leq b_n \leq d_n = 4^n$ , both of these have  $R_{\text{conv}} \geq 1$

$$\Rightarrow C\left(\frac{x}{4}\right), B\left(\frac{x}{4}\right) \text{ converge at least for } \forall x \in [0, 1)$$

→ we want to show  $\otimes$ :  $\sum_{j=0}^{\infty} \frac{C_m}{4^m} = C\left(\frac{1}{4}\right) = 1$

↳ Abels theorem says that  $C\left(\frac{1}{4}\right) = \lim_{x \rightarrow 1^-} C\left(\frac{x}{4}\right)$

$$\lim_{x \rightarrow 1^-} C\left(\frac{x}{4}\right) = 1$$

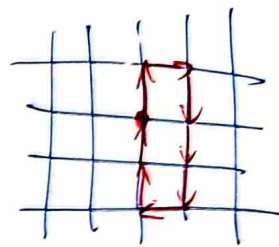
⇒ it suffices to show that  $\lim_{x \rightarrow 1^-} B\left(\frac{x}{4}\right) = \lim_{x \rightarrow 1^-} \frac{1}{1 - C\left(\frac{x}{4}\right)} = +\infty$

→ Abels theorem once again says that

$$\lim_{x \rightarrow 1^-} B\left(\frac{x}{4}\right) = B\left(\frac{1}{4}\right) = \sum_{n=0}^{\infty} \frac{b_n}{4^n}$$

→ in order to show  $B\left(\frac{1}{4}\right) = +\infty$ , we will determine  $b_n$

👁  $n$  odd  $\Rightarrow b_n = 0$



→ even walk lengths:  $|w| = 2n$

👁  $k$  steps right  $\Rightarrow k$  steps left

$\Rightarrow n-k$  steps up &  $n-k$  steps down

$\Rightarrow$  # walks  $b_m$  with exactly  $k$  steps right =

$$= \binom{2n}{k, k, n-k, n-k} = \frac{(2n)!}{k! k! (n-k)! (n-k)!} = \frac{(2n)!}{n! n!} \cdot \left( \frac{n!}{k! (n-k)!} \right)^2 = \binom{2n}{n} \cdot \binom{n}{k}^2$$

$$\Rightarrow b_{2n} = \sum_{k=0}^n \binom{2n}{n} \cdot \binom{n}{k}^2 = \binom{2n}{n} \cdot \sum_{k=0}^n \binom{n}{k}^2 = \binom{2n}{n} \cdot \binom{2n}{n} = \binom{2n}{n}^2$$

→ we can now use the well known formula  $\binom{2n}{n} \sim \frac{4^n}{\sqrt{\pi n}} \Rightarrow b_{2n} \sim \frac{4^{2n}}{\pi n}$

$$\Rightarrow B\left(\frac{1}{4}\right) = \sum_{n=0}^{\infty} \frac{b_n}{4^n} = \sum_{n=0}^{\infty} \frac{b_{2n}}{4^{2n}} = \sum_{n=0}^{\infty} \frac{1}{n} = \frac{1}{1} \sum_{n=0}^{\infty} \frac{1}{n} = +\infty$$

↳ harmonic series

→ Summary:

• we have shown  $B\left(\frac{1}{4}\right) = +\infty$

• because  $B(x) = \frac{1}{1 - C(x)}$ , this implies  $C\left(\frac{1}{4}\right) = 1$

$$\bullet \text{ so } \sum_{k=0}^n \frac{C_k}{4^k} = \frac{a_n}{d_n} \rightarrow 1$$



# Complex Analysis

- normed field  $\mathbb{C}_{OF} = (\mathbb{C}, 0, 1, +, \cdot, |\cdot|)$  ,  $|z| = |a+bi| = \sqrt{a^2+b^2}$
- metric space  $(\mathbb{C}, |z_1 - z_2|)$  is isometric to  $\mathbb{R}^2$  and therefore complete

## Notation:

- $U, U_0, U_1, \dots$  nonempty open subsets of  $\mathbb{C}$
- $\mathcal{U}_{<\varepsilon}(z_0) = \{z \in \mathbb{C} \mid |z - z_0| < \varepsilon\}$  ,  $\mathcal{U}_{<\varepsilon}^*(z_0) = \mathcal{U}_{<\varepsilon}(z_0) \setminus \{z_0\}$

Def: The derivative of  $f: U \rightarrow \mathbb{C}$  at  $z_0 \in \mathbb{C}$  is

$$f'(z_0) := \lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0} . \text{ If } f'(z_0) \text{ exists, } f \text{ is } \underline{\text{complex-differentiable at } z_0} .$$

$$\text{Where } \lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0} = L \equiv (\forall \varepsilon > 0)(\exists \delta > 0)(\forall z \in U):$$

$$0 < |z - z_0| < \delta \Rightarrow \left| \frac{f(z) - f(z_0)}{z - z_0} - L \right| \leq \varepsilon$$

Def:  $f: U \rightarrow \mathbb{C}$  is holomorphic on  $U$  ,  $f \in \mathcal{H}[U] \equiv \forall z \in U: f'(z) \in \mathbb{C}$  exists

Def:  $f: \mathbb{C} \rightarrow \mathbb{C}$  is entire (áplna)  $\equiv f \in \mathcal{H}[\mathbb{C}]$

## Properties of derivatives

→ let  $f, g: U \rightarrow \mathbb{C}$  ,  $h: U_0 \rightarrow \mathbb{C}$  be holomorphic and  $\alpha, \beta \in \mathbb{C}$

$$\textcircled{1} \alpha f + \beta g \in \mathcal{H}(U)$$

$$(\alpha f + \beta g)' = \alpha f' + \beta g'$$

$$\textcircled{2} f \cdot g \in \mathcal{H}(U)$$

$$(fg)' = f'g + fg'$$

$$\textcircled{3} \text{ if } g \neq 0 \text{ on } U, \text{ then } f/g \in \mathcal{H}(U)$$

$$(f/g)' = \frac{f'g - fg'}{g^2}$$

$$\textcircled{4} \text{ if } h[U_0] \subseteq U, \text{ then } f(h) \in \mathcal{H}(U_0)$$

$$(f(h))' = f'(h) \cdot h'$$

## Examples:

$$\bullet \underline{(z^n)' = n \cdot z^{n-1}} , \quad (\alpha)' = 0$$

Def:  $f: U \rightarrow \mathbb{C}$  is analytic on  $U \equiv (\forall z_0 \in U) (\exists \eta_{<\epsilon}(z_0) \subseteq U)$  we have

$$\forall z \in \eta_{<\epsilon}(z_0): f(z) = \sum_{n=0}^{\infty} a_n (z-z_0)^n, \text{ for some } (a_n) \subset \mathbb{C}$$

$\Rightarrow$  the function locally behaves as a power series

Theorem:  $f: U \rightarrow \mathbb{C}$  analytic  $\Rightarrow f \in C^{\infty}[U]$  ... continuous  $f^{(n)}(z)$  for  $\forall n$

Pf: We can for  $\forall z_0 \in U$  take some open disc  $B \subseteq U$  containing  $z_0$ , differentiate the power series and use:  $f$  differentiable  $\Rightarrow f$  continuous  $\blacksquare$

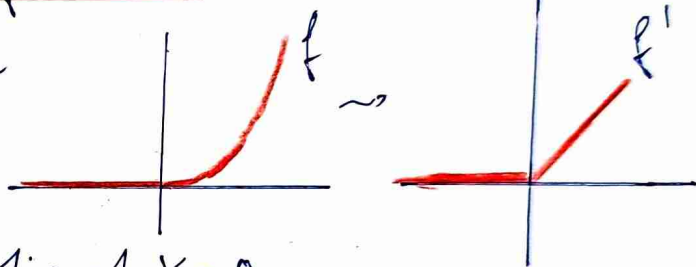
Theorem:  $f: U \rightarrow \mathbb{C}$  holomorphic  $\Rightarrow$  analytic,

$\hookrightarrow$  this is the main result of complex analysis

Corollary:  $f: U \rightarrow \mathbb{C}$  holomorphic  $\Rightarrow f \in C^{\infty}[U]$ .  $\rightarrow$  continuous derivatives of all orders

Note: This doesn't hold in  $\mathbb{R}$ , consider

$$f: \mathbb{R} \rightarrow \mathbb{R}, \quad f(x) = \begin{cases} x^2, & x \geq 0 \\ 0, & x < 0 \end{cases}$$



$\rightarrow f$  doesn't have the second derivative at  $x_0 = 0$

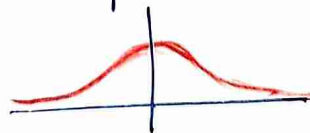
$\rightarrow$  but all analytic functions have derivatives of all orders

Def:  $f: U \rightarrow \mathbb{C}$  is bounded  $\equiv \exists m \geq 0$  s.t.  $\forall z \in U: |f(z)| \leq m$

Theorem (Liouville):  $f: \mathbb{C} \rightarrow \mathbb{C}$  entire & bounded  $\Rightarrow f$  is constant.

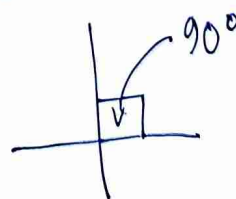
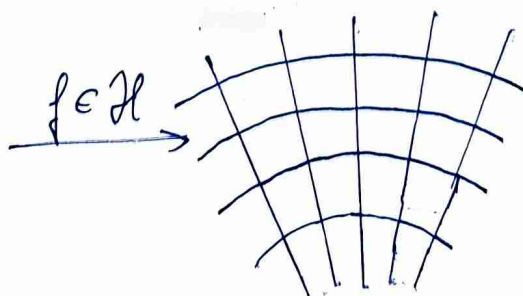
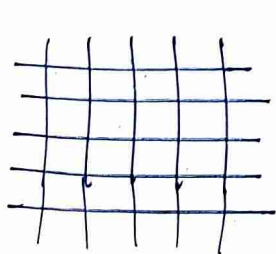
Note: This is again not true for real functions

$$f: \mathbb{R} \rightarrow \mathbb{R}, \quad f(x) = e^{-x^2}$$



is entire & bounded

Intuition: Holomorphic, nonconstant functions preserve angles

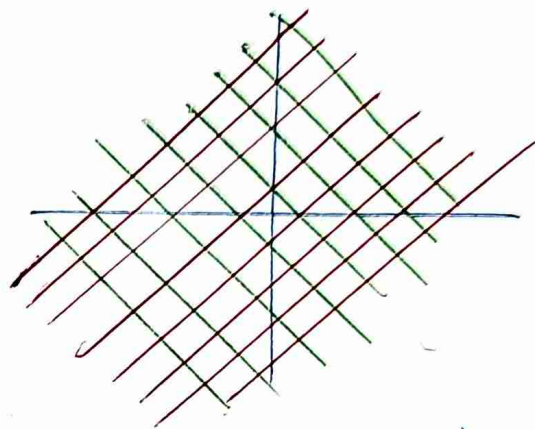


Ex: Moiré moiré  $\{ \operatorname{Re}(f) = C \}$ ,  $\{ \operatorname{Im}(f) = C \}$

$$\textcircled{1} \underline{f(z) = e^{i\frac{\pi}{4}} z} = (\cos(\frac{\pi}{4}) + i \sin(\frac{\pi}{4})) \cdot z = \frac{\sqrt{2}}{2} (1+i) (x+iy) = \frac{\sqrt{2}}{2} (x+iy + ix-y) \\ = \underbrace{\frac{\sqrt{2}}{2} (x-y)}_{\operatorname{Re}} + i \underbrace{\frac{\sqrt{2}}{2} (x+y)}_{\operatorname{Im}}$$

$$\operatorname{Re} = \cos 1 \Leftrightarrow \underline{x-y = \cos 1}$$

$$\operatorname{Im} = \cos 1 \Leftrightarrow \underline{x+y = \cos 1}$$

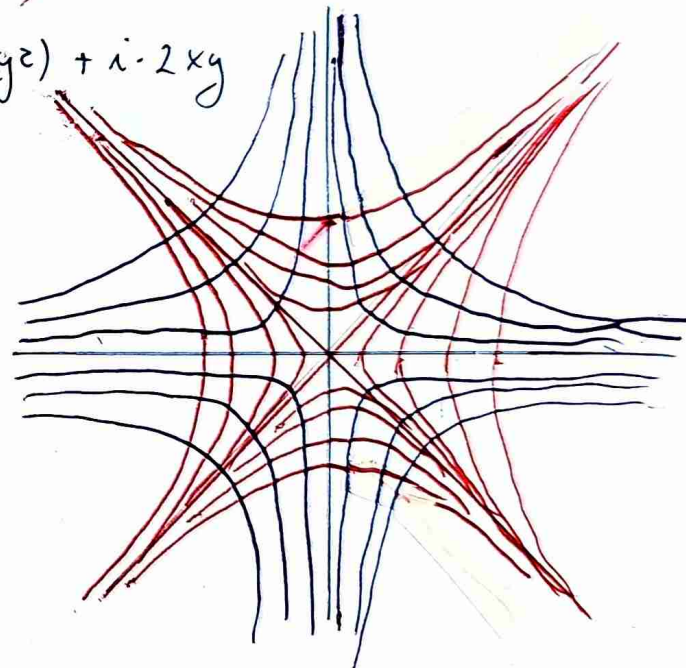
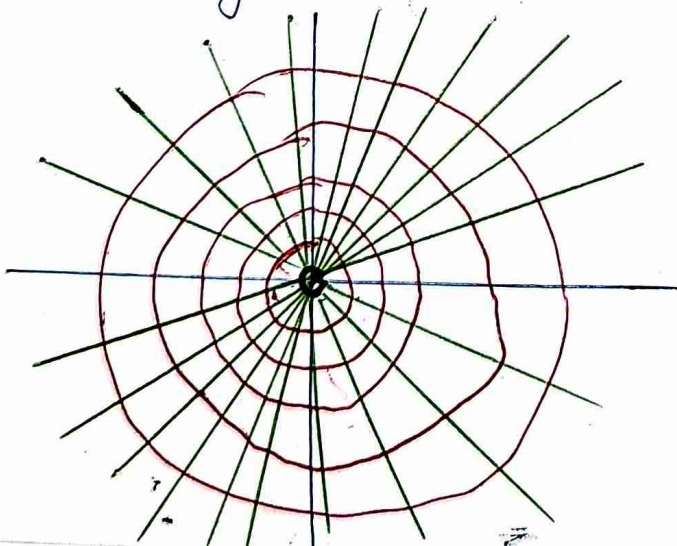


$$\textcircled{1} \underline{f(z) = z^2} = (x+iy)^2 = x^2 + 2ixy - y^2 = (x^2 - y^2) + i \cdot 2xy$$

$$\underline{\operatorname{Re} = \cos 1 \Leftrightarrow y^2 = x^2 + C \Leftrightarrow |y| = \sqrt{x^2 + C}}$$

$$\operatorname{Im} = \cos 1 \Leftrightarrow 2xy = C \Leftrightarrow y = \frac{C}{x}$$

$$\textcircled{2} \underline{f(z) = \operatorname{Arg}(z)} = \ln|z| + i\varphi$$



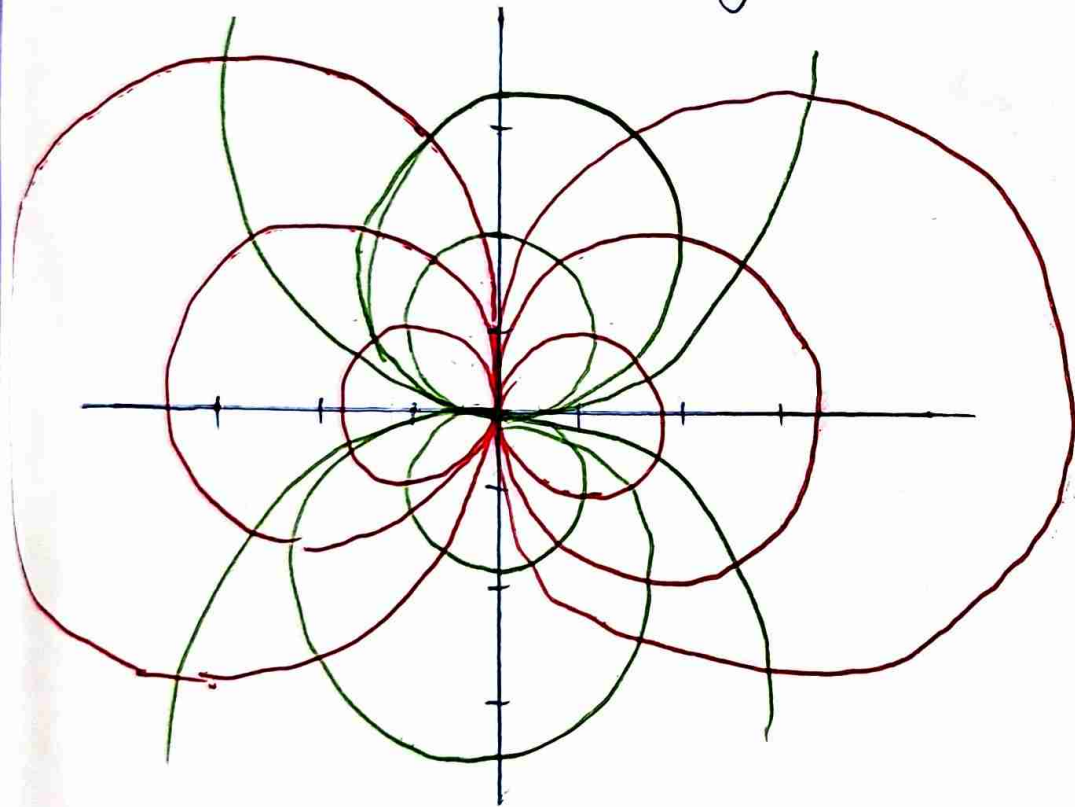
$\operatorname{Re} \dots \ln|z| = C \dots z$  na kruhu  
 $\operatorname{Im} \dots \varphi = C \dots$  slijz' argument

$$1) \quad f(z) = \frac{1}{z}, \quad z \neq 0$$

$$f(z) = \frac{1}{x+iy} = \frac{1}{x+iy} \cdot \frac{x-iy}{x-iy} = \frac{x-iy}{x^2+y^2} = \frac{x}{x^2+y^2} - i \frac{y}{x^2+y^2}$$

$$\operatorname{Re} = \cos t \Leftrightarrow x^2 + y^2 = c \cdot x \Leftrightarrow (x^2 + 2cx + c^2) - c^2 + y^2 = 0 \Leftrightarrow \underline{(x+c)^2 + y^2 = c^2}$$

$$\operatorname{Im} = \cos t \Leftrightarrow x^2 + y^2 = cy \Leftrightarrow x^2 + (y+c)^2 = c^2$$



Conjekture: Když se protne — a —, tak to je vždy kolmé.

# Fundamental Theorem of Algebra Revisited

Theorem: (Liouville  $\Rightarrow$  FTA):  $P(z)$  polynomial with  $\deg \geq 1 \Rightarrow \exists z_0 \in \mathbb{C}: P(z_0) = 0$

Proof: For contradiction assume  $\forall z_0 \in \mathbb{C}: P(z_0) \neq 0$

$\Rightarrow f(z) := \frac{1}{P(z)}$  is  $\mathcal{H}(\mathbb{C})$  ... entire

claim:  $f(z)$  is bounded

corollary: Liouville:  $f(z)$  is constant  $\Rightarrow P(z)$  is constant  $\Rightarrow$  has  $\deg = 1 \nmid$

$\hookrightarrow |P(z)| \sim z^m$  for  $|z| \rightarrow \infty$ , where  $m = \deg(P) \geq 1$

$\Rightarrow |P(z)| \rightarrow +\infty$  and  $|f(z)| \rightarrow 0$  for  $|z| \rightarrow \infty$

$\Rightarrow \exists R > 0$  s.t.  $|f(z)| < 1$  for  $\forall |z| > R$

☞ but also  $\exists m > 0$  s.t.  $|f(z)| \leq m$  for  $\forall |z| \leq R$

$\hookrightarrow B = \{z \in \mathbb{C} \mid |z| \leq R\}$  is compact &  $|f(z)|: \mathbb{C} \rightarrow \mathbb{R}$  is continuous

$\Rightarrow$  it attains maxima on  $B$  ■

Theorem (max. modulus principle):  $f \in \mathcal{H}(U) \Rightarrow |f|$  doesn't have strict local maxima

$(\forall z_0 \in U)(\forall \delta > 0): \exists z \in \eta_{<\delta}(z_0)$  s.t.  $|f(z)| \geq |f(z_0)|$

Idea why this might hold:

Lemma: Let  $f$  be analytic at  $z_0$ , then one of the following occurs:

①  $f$  is locally constant around  $z_0$  ...  $\exists \varepsilon > 0: \forall z \in \eta_{<\varepsilon}(z_0): f(z) = f(z_0)$

②  $f$  is locally strictly different from  $z_0$  ...  $\exists \varepsilon > 0: \forall z \in \eta_{<\varepsilon}(z_0): f(z) \neq f(z_0)$

Proof:  $f(z) = \sum_{n=0}^{\infty} a_n(z-z_0)^n$  near  $z_0$

a)  $\forall n \geq 1: a_n = 0 \Rightarrow f(z) = a_0 = f(z_0) \Rightarrow$  ①

b)  $\exists n \geq 1: a_n \neq 0 \Rightarrow$  let  $k$  be smallest such  $n$

$\Rightarrow f(z) = a_0 + a_k(z-z_0)^k + \sum_{n=k+1}^{\infty} a_n(z-z_0)^n = a_0 + \underbrace{(z-z_0)^k}_{\neq 0} \left[ \underbrace{a_k}_{f'(z_0)} + \sum_{n=1}^{\infty} a_{k+n}(z-z_0)^n \right]$   
 $\hookrightarrow g(z_0) = a_k \neq 0$  for  $z \neq z_0$   $g(z)$

$\rightarrow g(z)$  is analytic at  $z_0 \Rightarrow$  continuous around  $z_0 \Rightarrow$  non-zero in some  $\eta_{<\varepsilon}(z_0)$  ■

## Curves in $\mathbb{C}$

→ final goal: prove

← Liouville's theorem

$$f \in \mathcal{H}(\mathbb{C}) \Rightarrow f \text{ analytic in } \mathbb{C}$$

↗ less general than  $f \in \mathcal{H}(U) \Rightarrow \text{analytic in } U$

Def: A continuous  $\gamma: [\alpha, \beta] \rightarrow \mathbb{C}$  is a curve with

- starts  $\gamma(\alpha) \in \mathbb{C}$ , end  $\gamma(\beta) \in \mathbb{C}$
- image  $\langle \gamma \rangle := \gamma([\alpha, \beta]) = \{\gamma(t) \mid t \in [\alpha, \beta]\}$
- length  $|\gamma| = \int_{\alpha}^{\beta} |\gamma'(t)| dt$

↖ standard formula for length of a parametric curve

Note:  $\gamma(t) = x(t) + iy(t) \Rightarrow \int_{\alpha}^{\beta} |\gamma'(t)| dt = \int_{\alpha}^{\beta} \sqrt{x'(t)^2 + y'(t)^2} dt$

Def: The curve  $\gamma: [\alpha, \beta] \rightarrow \mathbb{C}$  is

- simple  $\equiv \gamma$  is injective ...  $t_1 \neq t_2 \Rightarrow \gamma(t_1) \neq \gamma(t_2)$

- closed  $\equiv \gamma(\alpha) = \gamma(\beta)$

- simple closed  $\equiv$  closed &  $\gamma|_{[\alpha, \beta)}$  is injective

↳ also Jordan curve

Intuition:  $\gamma'(t) \sim$  velocity vector of the curve parametrization

↳ the same  $\langle \gamma \rangle$  can have different parametrizations with different velocities of how they move through the curve

Def: The curve  $\gamma: [\alpha, \beta] \rightarrow \mathbb{C}$  is

↗ it doesn't stop

- regular  $\equiv \gamma$  is differentiable &  $\forall t \in (\alpha, \beta): \gamma'(t) \neq 0$

- smooth  $\equiv \gamma \in C^1$  ... continuous derivative

- contour  $\equiv$  piece-wise smooth ... up to finitely many discontinuities

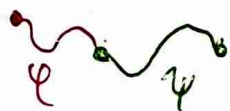
Def (opposite curve): For the curve  $\gamma: [\alpha, \beta] \rightarrow \mathbb{C}$  we define

$-\gamma$ :  $[\alpha, \beta] \rightarrow \mathbb{C}$  as  $-\gamma(t) := \gamma(\alpha + \beta - t) \Rightarrow -\gamma: \begin{matrix} \alpha \mapsto \gamma(\beta) \\ \beta \mapsto \gamma(\alpha) \end{matrix}$

Def (curve composition): For curves  $\gamma: [\alpha, \beta] \rightarrow \mathbb{C}$ ,  $\psi: [\gamma, \delta] \rightarrow \mathbb{C}$  with

$\gamma(\beta) = \psi(\gamma)$  define the curve  $\gamma \oplus \psi$  by concatenating them together.

$\gamma \oplus \psi: [\alpha, \beta + (\delta - \gamma)] \rightarrow \mathbb{C}$ ,  $t \mapsto \begin{cases} \gamma(t), & t \in [\alpha, \beta] \\ \psi(t - \beta + \gamma), & t \in [\beta, \beta + (\delta - \gamma)] \end{cases}$

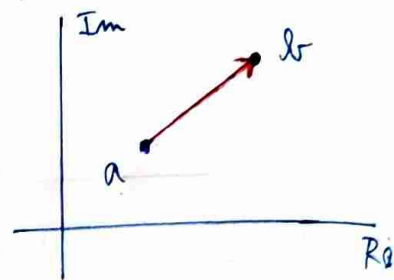


## Segments and rectangles

Def: The curve  $\gamma$  is a segment  $\equiv \gamma(t)$  is a linear function

Def: For  $a, b \in \mathbb{C}$  we define the segment  $\overrightarrow{ab}$  as

$$\gamma: [0, 1] \rightarrow \mathbb{C}, \quad \gamma(t) := a + t(b-a)$$



### Properties

① for the opposite segment it holds  $-\overrightarrow{ab} = \overrightarrow{ba}$

② length of the segment is  $|\overrightarrow{ab}| = |b-a|$

$$\hookrightarrow |\overrightarrow{ab}| = \int_0^1 |\gamma'(t)| dt = \int_0^1 |b-a| dt = [|b-a|t]_0^1 = |b-a|$$

Notation: When talking about segments we often mean the image

$\Rightarrow \overrightarrow{ab} \dots$  curve,  $\langle ab \rangle$  image

Def: A partition of the segment  $\gamma: [\alpha, \beta] \rightarrow \mathbb{C}$  is any  $\mu = (a_0, a_1, \dots, a_k) \subset \langle \gamma \rangle$  s.t.

$$\exists \alpha = t_0 < t_1 < \dots < t_k = \beta \quad \text{s.t.} \quad \forall i: \gamma(t_i) = a_i$$

Note: For segment  $\overrightarrow{ab}$  we have partition  $\mu = (a_0, a_1, \dots, a_k)$  with  $a_0 = a, a_k = b$

It defines subsegments  $\overrightarrow{a_{i-1}a_i}$  for  $i \in [k]$

Def: The norm of the partition is the max. sub-segment length

$$\|\mu\| := \max_{i \in [k]} |\overrightarrow{a_{i-1}a_i}|$$

We have  $\sum_{i=1}^k |\overrightarrow{a_{i-1}a_i}| = |\overrightarrow{ab}|$

Def (Cauchy sums): Let  $\vec{\mu}$  be a segment and  $\mu = (a_0, a_1, \dots, a_k)$  its partition.

For  $f: \langle \mu \rangle \rightarrow \mathbb{C}$  we define

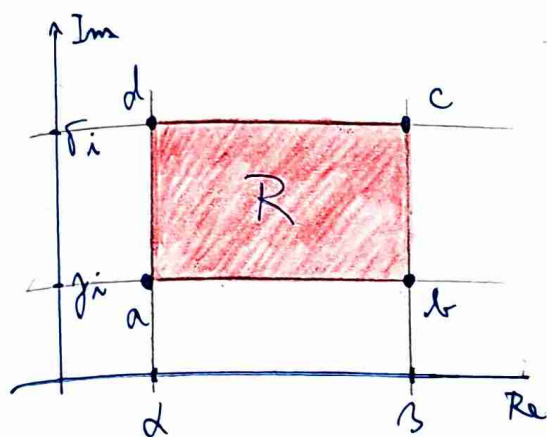
$$\bullet C(f, \mu) := \sum_{i=1}^k (a_i - a_{i-1}) f(a_i) \quad \dots \text{Cauchy sum} \in \mathbb{C}$$

$$\bullet C'(f, \mu) := \sum_{i=1}^k (a_i - a_{i-1}) f(a_{i-1}) \quad \dots \text{modified Cauchy sum} \in \mathbb{C}$$

$$\text{ } |C(f, \mu)|, |C'(f, \mu)| \leq |\vec{\mu}| \cdot \sup_{z \in \langle \mu \rangle} |f(z)|$$

$\hookrightarrow$  replace  $f(a_i)$  and  $f(a_{i-1})$  by the max possible value  $= \sup |f(z)|$

Def: The real numbers  $\alpha < \beta$ ,  $\gamma < \delta$  determine the rectangle



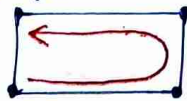
$$R = \{z \in \mathbb{C} \mid \alpha \leq \operatorname{Re}(z) \leq \beta \text{ \& \> } \gamma \leq \operatorname{Im}(z) \leq \delta\}$$

•  $R$  is a square  $\equiv \beta - \alpha = \delta - \gamma$

• canonical vertices  $= (a, b, c, d) \in \mathbb{C}^4$

$$d = \alpha + \delta i \quad c = \beta + \delta i$$

$$a = \alpha + \gamma i \quad b = \beta + \gamma i$$



• The boundary of  $R$  is  $\partial R := \langle ab \rangle \cup \langle bc \rangle \cup \langle cd \rangle \cup \langle da \rangle$

• The interior of  $R$  is  $\operatorname{Int}(R) := R \setminus \partial R$

• The perimeter of  $R$  is  $\operatorname{Per}(R) := |ab| + |bc| + |cd| + |da|$

## Integrals and their existence

Def: For a segment  $\vec{u}$  and a (usually continuous)  $f: \langle u \rangle \rightarrow \mathbb{C}$  we define  $\int_u f$ .

If for every sequence  $(p_n)$  of partitions  $p_n$  of  $\vec{u}$  with  $\lim_{n \rightarrow \infty} \|p_n\| = 0$  the limit of the corresponding Cauchy sums

$$L = \lim_{n \rightarrow \infty} C(f, p_n) \in \mathbb{C} \text{ exists, we say that}$$

$f$  has the integral  $L$  over  $\vec{u}$  and write  $\int_u f = L$ .

Note: We could have also used a Riemann integral style definition using

$$R(f, p, q) = \sum_{i=1}^{\ell} (a_i - a_{i-1}) f(b_i) \quad \text{where } p = (a_1, \dots, a_\ell) \\ q = (b_1, \dots, b_\ell), \quad b_i \in \langle a_{i-1}, a_i \rangle$$

For continuous functions  $f$  are the definitions using  $C(f, p)$  and  $R(f, p, q)$  equivalent, but for discontinuous it's better to use the Riemann definition

Def: For a rectangle  $R$  with vertices  $(a, b, c, d)$  and  $f: \partial R \rightarrow \mathbb{C}$  we define

$$\int_{\partial R} f := \int_{\vec{ab}} f + \int_{\vec{bc}} f + \int_{\vec{cd}} f + \int_{\vec{da}} f$$

Theorem: Suppose that  $\vec{u}$  is a segment and  $R$  is a rectangle

①  $f: \langle u \rangle \rightarrow \mathbb{C}$  continuous  $\Rightarrow \int_u f$  exists

②  $f: \partial R \rightarrow \mathbb{C}$  continuous  $\Rightarrow \int_{\partial R} f$  exists

Theorem: For  $f, g$  continuous it holds that

①  $\int_u (\alpha f + \beta g) = \alpha \int_u f + \beta \int_u g$

②  $|\int_u f| \leq |\vec{u}| \cdot \max_{z \in \langle u \rangle} |f(z)|$  ,  $|\int_{\partial R} f| \leq \text{Per}(R) \cdot \max_{z \in \partial R} |f(z)|$

③  $\int_{ba} f = - \int_{ab} f$

④  $\int_{ab} f = \int_{ac} f + \int_{cb} f$  ,  $c \in \langle ab \rangle \setminus \{a, b\}$   $\leftarrow$  interior point

continuous on compact  $\Rightarrow \text{sup} = \text{max}$

## Contour Integrals

$\rightarrow$  piece-wise  $C^1$

Def: Let  $\varphi: [\alpha, \beta] \rightarrow \mathbb{C}$  be a contour,  $U \subseteq \mathbb{C}$  be open and containing  $\varphi \dots \langle \varphi \rangle \subseteq U$

For  $f: U \rightarrow \mathbb{C}$  define the integral of  $f$  along the curve  $\varphi$  as

$$\int_{\varphi} f := \int_{\alpha}^{\beta} f(\varphi(t)) \cdot \varphi'(t) dt \quad \rightarrow \quad \int f(z) dz = \left| \begin{matrix} z = \varphi(t) \\ dz = \varphi'(t) dt \end{matrix} \right| = \int f(\varphi(t)) \varphi'(t) dt$$

If  $\varphi$  is closed, we write  $\oint_{\varphi} f$  instead

👁 The Cauchy sum integrals for segments we have defined previously evaluate to exactly this for continuous  $f$  ... just plug in  $\varphi$  and use Cauchy  $\int$  = Riemann  $\int$   $\leftarrow$  for continuous  $f$

Lemma: If  $f: \mathbb{C} \rightarrow \mathbb{C}$  has primitive function  $F: \mathbb{C} \rightarrow \mathbb{C}$ , then

$$\int_{ab} f = \underline{F(b) - F(a)}$$

Proof: Since  $F' = f$ ,  $F$  is holomorphic  $\Rightarrow F' = f$  is continuous

$\Rightarrow$  we can use the contour integral formula with  $\varphi: [0, 1] \rightarrow \mathbb{C}$ ,  $\varphi(t) = a + (b-a)t$

Theorem (ML bound):  $f$  continuous  $\Rightarrow \int_{\varphi} f \leq |\varphi| \cdot \max_{z \in \langle \varphi \rangle} |f(z)|$

Proof:  $\langle \varphi \rangle$  compact  $\Rightarrow f$  attains a maxima on  $\langle \varphi \rangle$ , call it  $M$

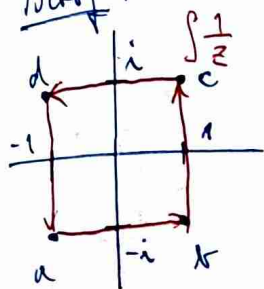
$$\int_{\varphi} f = \int_{\alpha}^{\beta} f(\varphi(t)) \varphi'(t) dt \leq \int_{\alpha}^{\beta} |f(\varphi(t))| \cdot |\varphi'(t)| dt \leq M \cdot \int_{\alpha}^{\beta} |\varphi'(t)| dt = M \cdot |\varphi|$$

Not all  $\oint$  are  $= 0$

vertices  $\pm 1, \pm i$

Theorem: Let  $S$  be the unit square. Then  $\oint_S \frac{1}{z} \neq 0$

Proof: We will show this from the Cauchy sum definition and then using  $\oint$



→ canonical vertices  $a, b, c, d$

→ consider the  $n$ -equipartition (equal subsegments) of  $\vec{ab}$

$$\gamma_{ab} = (a_0, a_1, \dots, a_n), \quad a_j = a + (b-a) \cdot \frac{j}{n}$$

→ equal lengths  $\Rightarrow a_j - a_{j-1} = \frac{b-a}{n}$

⊙ multiplying  $z \in \mathbb{C}$  by  $i$  rotates it counterclockwise by 90 degrees

$$\Rightarrow \gamma_{bc} = i \cdot \gamma_{ab}, \quad \gamma_{cd} = i \cdot \gamma_{bc}, \quad \gamma_{da} = i \cdot \gamma_{cd}$$

$$\odot C(f, \gamma_{ab}) = C(f, \gamma_{bc}) = C(f, \gamma_{cd}) = C(f, \gamma_{da})$$

$$\begin{aligned} \hookrightarrow C(f, \gamma_{ab}) &= \sum_{j=1}^n (a_j - a_{j-1}) \cdot f(a_j) = \sum_{j=1}^n \frac{b-a}{n} \cdot \frac{1}{a + (b-a)j/n} = \frac{1}{n} \cdot \frac{b-a}{a} = 1 \\ &= \sum_{j=1}^n \frac{(ib-a)}{n} \cdot \frac{1}{ia + (ib-a)j/n} = \sum_{j=1}^n \frac{c-b}{n} \cdot \frac{1}{b + (c-b)j/n} = C(f, \gamma_{bc}) \end{aligned}$$

claim:  $\text{Im}(C(f, \gamma_{ab})) \geq 1$

(corollary: We let  $n \rightarrow \infty$  and get  $\text{Im}(\oint) = 4 \cdot \text{Im}(C(f, \gamma_{ab})) \geq 4 \Rightarrow \oint \neq 0$ )

→ plug in  $a = -1-i, b = 1-i \Rightarrow b-a = 2 \Rightarrow a_j = \frac{2j}{n} - 1 - i$

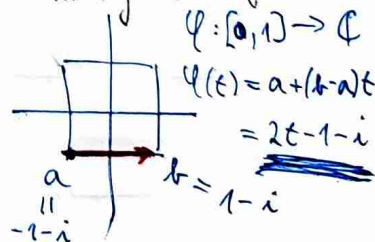
$$\Rightarrow C(f, \gamma_{ab}) = \sum_{j=1}^n \frac{2}{n} \cdot \frac{1}{2j/n - 1 - i} \cdot \frac{2j/n - 1 + i}{2j/n - 1 + i} = \frac{2}{n} \sum_{j=1}^n \frac{2j/n - 1 + i}{(2j/n - 1)^2 + 1}$$

$$\Rightarrow \text{Im}(C) = \frac{2}{n} \sum_{j=1}^n \frac{1}{(2j/n - 1)^2 + 1} \geq \frac{2}{n} \sum_{j=1}^n \frac{1}{2} = 1$$

→ in fact,  $S$  can be any simple closed contour containing the origin

Theorem  $\oint_{\partial S} \frac{1}{z} = 2\pi i$ , where  $S$  = unit square

Pf: As observed in the previous proof,  $\oint_{\partial S} \frac{1}{z} = 4 \cdot \int_{\gamma_{ab}} \frac{1}{z}$  where



$$4 \int_{\gamma_{ab}} \frac{1}{z} = 4 \int_0^1 \frac{\psi'(t)}{\psi(t)} dt = 4 \int_0^1 \frac{2 dt}{2t - 1 - i} = \left[ \ln(2t - 1 - i) \right]_{t=0}^{t=1} = 4 \int_{-1-i}^{1-i} \frac{dn}{n-i} \cdot \frac{n+i}{n+i}$$

$$= 4 \int_{-1}^1 \frac{n+i}{n^2+1} dn = 2 \int_{-1}^1 \frac{2n}{n^2+1} dn + 4i \int_{-1}^1 \frac{1}{n^2+1} dn$$

$$\begin{aligned} &= 2 \left[ \ln(n^2+1) \right]_{-1}^1 + 4i \left[ \arctan(n) \right]_{-1}^1 = 2 \cdot (\ln(2) - \ln(2)) + 4i (\arctan(1) - \arctan(-1)) \\ &= 4i \cdot 2\arctan(1) = 8i \cdot \frac{\pi}{4} = 2\pi i \end{aligned}$$

→ arctg is odd

For nice functions  $\oint = 0$

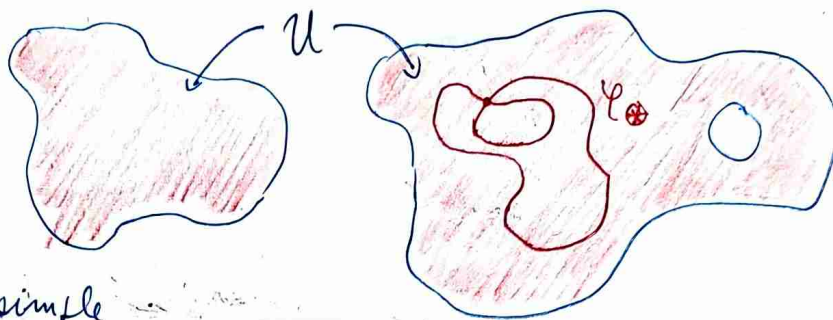
Theorem (Cauchy-Goursat): Let  $f: U \rightarrow \mathbb{C}$  be holomorphic on  $U$ .

If  $\gamma$  is a Jordan contour (piece-wise  $C^1$ ) s.t.  $\langle \gamma \rangle \cup \text{Int}(\gamma) \subseteq U$ . Then

$$\oint_{\gamma} f = 0$$

Note: Since  $\int_{\gamma \oplus \gamma} f = \int_{\gamma} f + \int_{\gamma} f$

⊗ we don't need  $\gamma$  to be simple

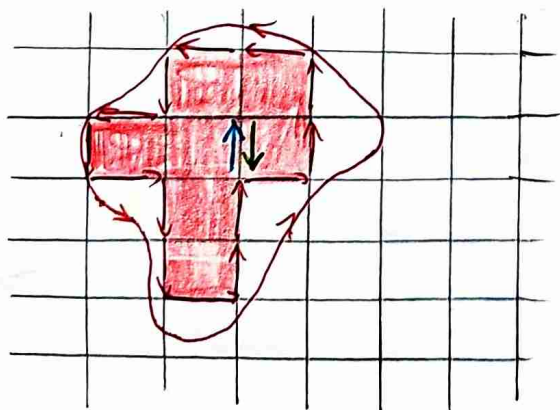


History:

- we need this theorem to prove the Cauchy integral formula
- and we need the Cauchy integral formula to show:  $f \in \mathcal{H}[U] \Rightarrow f \in C^{\infty}[U]$
- ⇒ so we cannot assume:  $f'$  exists  $\Rightarrow f'$  continuous
  - ↳ it holds, but it would be a cyclic proof
- Cauchy originally proved this theorem with the assumption:  $f'$  is continuous
- Goursat later showed that it's enough to assume that  $f'$  exists.

Proof idea:

- ① show that C-G holds when  $\gamma$  is a rectangle - we will show this
- ② approximate  $\gamma$  with a very fine rectangular mesh
- ③ show that  $\oint_R f$  doesn't depend on the position of the rectangle  $R$
- ④ we approximate  $\oint_{\gamma} f$  using the rectangles inside  $\gamma$



→ WLOG assume  $\gamma$  is simple ⊗

$M := \text{Rectangles inside } \text{Int}(\gamma)$

$$\oint_{\gamma} f \approx \sum_{R \in M} \oint_{\partial R} f$$

→ the touching boundaries   
cancel and only the outside boundary is left

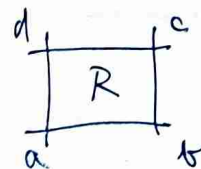
$$\hookrightarrow \int_{\partial U} f = - \int_{\partial U} f$$

Theorem (C-G. for  $\mathbb{R}$ ): Let  $f \in \mathcal{H}[U]$  and  $R \subseteq U$  be a rectangle. Then  $\oint_{\partial R} f = 0$ .

Proof: This will be long

Lemma 1: It is easy when  $f$  has a primitive function  $F' = f$ .

Pf: Recall:  $\int_a^b f = F(b) - F(a)$



$$\Rightarrow \oint_{\partial R} f = \int_{a \rightarrow b} + \int_{b \rightarrow c} + \int_{c \rightarrow d} + \int_{d \rightarrow a} = F(b) - F(a) + F(c) - F(b) + F(d) - F(c) + F(a) - F(d) = 0 \quad \square$$

Def: The diameter of the set  $X \subseteq \mathbb{C}$  is  $\text{Diam}(X) := \sup \{|x-y| \mid x, y \in X\} \in \mathbb{R}_0^+ \cup \{\infty\}$ .

Lemma 2: Let  $A_n \neq \emptyset$  be closed sets s.t.  $\mathbb{C} \supseteq A_1 \supseteq A_2 \supseteq \dots$  and  $\lim_{n \rightarrow \infty} \text{Diam}(A_n) = 0$ .

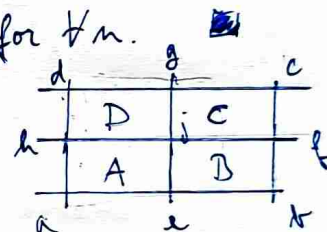
Then  $\bigcap_{n=1}^{\infty} A_n \neq \emptyset$ .

Proof: Because  $\text{Diam}(A_n) \rightarrow 0$ , it is easy to see that there exists a sequence

$(a_n) \subset \mathbb{C}$  s.t.  $\forall a_i \in A_i$  and  $(a_n) \rightarrow a \in \mathbb{C}$

$\rightarrow$  because all  $A_n$  are closed, this  $a \in A_n$  for  $\forall n$ . \(\square\)

Def: For a rectangle  $R$  we define its quarters  $\rightarrow$



for each quarter  $Q$  we have

- $\text{Per}(Q) = \frac{1}{2} \text{Per}(R)$

- $\text{Diam}(Q) = \frac{1}{2} \text{Diam}(R) = \max \{|\beta - \alpha|, |\delta - \gamma|\}$

$\rightarrow$  rectangle defined by  $\alpha < \beta, \gamma < \delta$

$$R = \{z \mid \text{Re}(z) \in [\alpha, \beta], \text{Im}(z) \in [\gamma, \delta]\}$$

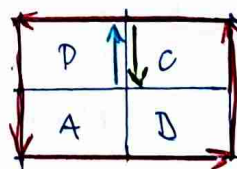
Proof of C-G: We first define a series of nested rectangles  $R = R_0 \supseteq R_1 \supseteq R_2 \supseteq \dots$

s.t.  $\forall n: R_{n+1}$  is a quarter of  $R_n$  and  $|\oint_{\partial R_{n+1}} f| \geq \frac{1}{4} |\oint_{\partial R} f|$  \(\otimes\)

$\rightarrow$  suppose that  $R_0, R_1, \dots, R_n$  have already been defined, we want  $R_{n+1}$

$\rightarrow$  let  $A, B, C, D$  be the quarters of  $R_n$

$\oint_{\partial R_n} f = \oint_{\partial A} f + \oint_{\partial B} f + \oint_{\partial C} f + \oint_{\partial D} f$



the touching sides cancel

$\rightarrow$  we will pick a quarter such that  $\otimes$  holds

$$|\oint_{\partial R_n} f| \leq |\oint_{\partial A} f| + |\oint_{\partial B} f| + |\oint_{\partial C} f| + |\oint_{\partial D} f|$$

$$\Rightarrow \exists \text{ quarter } Q \text{ s.t. } |\oint_{\partial Q} f| \geq \frac{1}{4} |\oint_{\partial R_n} f| \Rightarrow \text{choose } R_{n+1} := Q$$

→ so now we have  $U \supseteq R \supseteq R_1 \supseteq R_2 \supseteq \dots$  s.t.  $|\oint_{\partial R_{m+1}} f| \geq \frac{1}{4} |\oint_{\partial R_m} f|$   $\oplus$

→ because all  $R_m$  are closed and nonempty, by lemma 2:

$$\exists z_0 \in U: z_0 \in \bigcap_{m=0}^{\infty} R_m$$

→ we will show that for  $\forall \varepsilon > 0: |\oint_{\partial R} f| \leq \varepsilon \cdot \text{Per}(R)^2 \xrightarrow{\varepsilon \rightarrow 0} 0$ .

→ let  $\varepsilon > 0$  be given.

Recall:  $f'$  exists  $\Rightarrow f$  continuous. We use continuity at  $f(z_0)$

$\Rightarrow \exists \delta > 0$  s.t.  $\eta := \eta_{<\delta}(z_0) \subseteq U$  and on  $\eta$  we have

$|f(z) - f(z_0)|$  arbitrarily small (based on  $\varepsilon$ )

$\Rightarrow$  we can do a linear approximation of  $f$  on  $\eta$  as

$$f(z) = \underbrace{f(z_0) + f'(z_0)(z - z_0)}_{g(z)} + \underbrace{\mu(z)(z - z_0)}_{h(z)}, \quad \mu: \eta \rightarrow \mathbb{C} \quad |\mu(z)| \leq \varepsilon$$

point is that we can shrink  $\eta$  so that  $|\mu(z)|$  is arbitrarily bounded

$\odot$   $g(z)$  is continuous and linear

$\odot$   $h(z)$  is continuous on  $\eta$   $\because h(z) = f(z) - g(z)$  continuous

→ now let  $n$  be so large that  $R_n \subseteq \eta$  ... here we are using  $\text{Diam}(R_n) \rightarrow 0$

$$\Rightarrow \oint_{\partial R_n} f = \oint_{\partial R_n} g + \oint_{\partial R_n} h = \oint_{\partial R_n} h$$

$\odot$  using lemma 1 ...  $g$  is linear  $\Rightarrow$  has primitive function  $\Rightarrow \oint g = 0$

→ now we estimate

→ length of boundary → max value

$$|\oint_{\partial R_n} f| = |\oint_{\partial R_n} h| \leq \text{Per}(R_n) \cdot \max_{z \in \partial R_n} |h(z)|$$

$$= \text{Per}(R_n) \cdot \max_{z \in \partial R_n} |\mu(z) \cdot (z - z_0)| \quad \dots |\mu(z)| \leq \varepsilon \text{ on } \eta \text{ and } R_n \subseteq \eta$$

$$\leq \text{Per}(R_n) \cdot \varepsilon \cdot \max_{z \in \partial R_n} |z - z_0| \leq \text{Per}(R_n) \cdot \varepsilon \cdot \text{Diam}(R_n) \quad \leftarrow R_j \text{ are nested squares}$$

$$= \varepsilon \cdot \frac{\text{Per}(R)}{2^n} \cdot \frac{\text{Diam}(R)}{2^n} \leq \varepsilon \cdot \frac{1}{4^n} \cdot \text{Per}(R)^2 \quad \leftarrow \text{Diam}(R) \leq \text{Per}(R)$$

→ now we use  $\oplus$

$$\Rightarrow |\oint_{\partial R_n} f| \geq \frac{1}{4^n} |\oint_{\partial R} f| \Rightarrow |\oint_{\partial R} f| \leq \varepsilon \cdot \text{Per}(R)^2 \xrightarrow{\varepsilon \rightarrow 0} 0$$



# Cauchy integral formula

Lemma: Let  $R \subseteq \mathbb{C}$  be a rectangle and  $A \subseteq \text{Int}(R)$  be compact.

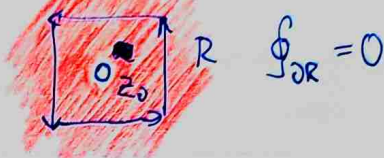
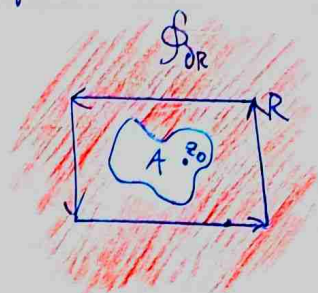
Let  $f, g: \mathbb{C} \setminus A \rightarrow \mathbb{C}$  be holomorphic. Then

$$\textcircled{1} \oint_{\partial R} (\alpha f + \beta g) = \alpha \oint_{\partial R} f + \beta \oint_{\partial R} g$$

$\textcircled{2}$  if  $A = \{z_0\}$  and  $f$  is bounded on some  $\mathcal{N}_{<\epsilon}(z_0)$ , then

$$\oint_{\partial R} f = 0$$

$\textcircled{3}$  if  $z_0 \in \text{Int}(R)$ , then  $\oint_{\partial R} \frac{1}{z - z_0} = 2\pi i$



Proof:  $\textcircled{1}$  linearity of  $\oint_{\partial R} f$  holds in general

$\textcircled{2}$  let  $(R_n)$  be rectangles with  $z_0 \in R_n$  and  $\text{Diam}(R_n) \rightarrow 0$

$$\oint_{\partial R_n} f \leq \text{Per}(R_n) \cdot \max_{z \in \partial R_n} |f(z)| \xrightarrow{\text{Per} \rightarrow 0} 0 \implies \oint_R f = 0$$

$\textcircled{3}$  let  $S$  be the unit square and  $a+S$  a shifted copy with center at  $a$

$$\oint_{\partial R} \frac{1}{z-a} \stackrel{\textcircled{2}}{=} \oint_{\partial(a+S)} \frac{1}{z-a} = \oint_{\partial S} \frac{1}{z} = 2\pi i \dots \text{we have shown before}$$

Lemma  $\textcircled{2}$  (Independence of  $\oint_{\partial R} f$  on  $R$ ): Let  $R, P \subseteq \mathbb{C}$  be rectangles and let  $A \subseteq \text{Int}(R) \cap \text{Int}(P)$  be compact. Let  $f: \mathbb{C} \setminus A \rightarrow \mathbb{C}$  be holomorphic. Then

$$\oint_{\partial R} f = \oint_{\partial P} f$$

Proof:

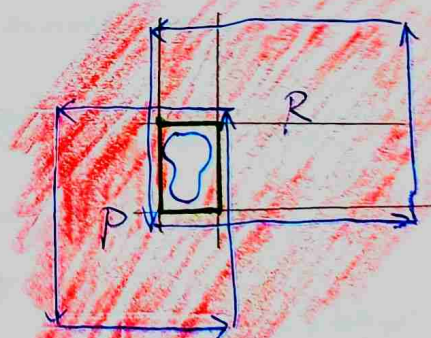
$\textcircled{1}$  There  $\exists$  rectangle  $T \subseteq \text{Int}(R) \cap \text{Int}(P)$  containing  $A$

$\Rightarrow$  we extend the edges of  $T$  to divide  $R$  into 9 rectangles  $R_1, R_2, \dots, R_8, T$

$$\oint_{\partial R} f = \oint_{\partial T} f + \sum_{j=1}^8 \oint_{\partial R_j} f = \oint_{\partial T} f$$

$\circ$  because  $R_j$  do not contain any holes  $\rightarrow \text{C.G.}: \oint = 0$

$\rightarrow$  similarly  $\oint_{\partial P} f = \oint_{\partial T} f$

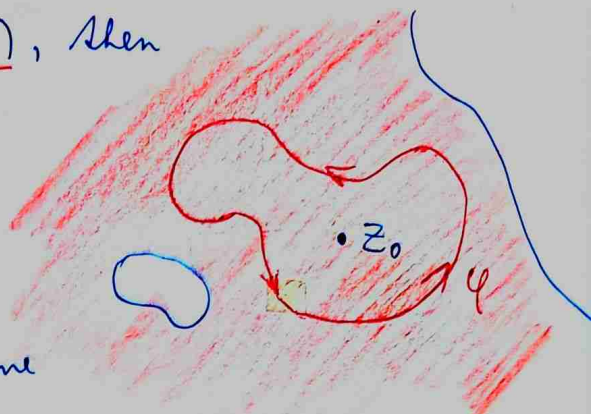


Fact: In fact  $\oint$  is completely independent on the curve  $\gamma$  as long as we transform it in a continuous manner - such curves are called homotopic

Theorem (Cauchy's formula): Let  $f \in \mathcal{H}[U]$  and  $\gamma$  be a simple closed contour.

If  $\langle \gamma \rangle \cup \text{Int}(\gamma) \subseteq U$  and  $z_0 \in \text{Int}(\gamma)$ , then

$$\underline{f(z_0) = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(z)}{z - z_0}}$$



Proof: For  $U = \mathbb{C}$  and  $\gamma = R$  rectangle

→ since  $f'(z_0)$  exists,  $\frac{f(z) - f(z_0)}{z - z_0}$  is bounded in some punctured neighborhood  $\mathcal{U}_{\epsilon}^{\circ}(z_0)$  and by the lemma on the previous page

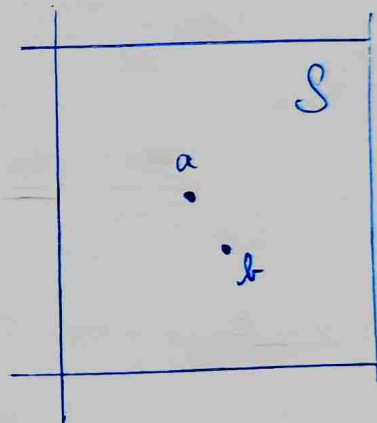
$$0 = \oint_{\partial R} \frac{f(z) - f(z_0)}{z - z_0} = \oint_{\partial R} \frac{f(z)}{z - z_0} - f(z_0) \underbrace{\oint_{\partial R} \frac{1}{z - z_0}}_{2\pi i} \Rightarrow f(z_0) = \frac{1}{2\pi i} \oint_{\partial R} \frac{f(z)}{z - z_0} \quad \square$$

Proof of Liouville's Theorem

Theorem:  $f: \mathbb{C} \rightarrow \mathbb{C}$  entire & bounded  $\Rightarrow f$  constant

Proof: Suppose  $|f(z)| \leq M$ . Let  $a, b \in \mathbb{C}$ , we will make a sufficiently large square  $S \subseteq \mathbb{C}$  with side lengths  $s$  s.t.  $a, b \in \text{Int}(S)$  & for  $\forall z \in \partial S$ :

$$|z - a|, |z - b| \geq \frac{1}{3}s = \frac{1}{12} \text{Per}(S)$$



By the Cauchy formula:

$$f(a) - f(b) = \frac{1}{2\pi i} \oint_{\partial S} \frac{f(z)}{z - a} - \frac{1}{2\pi i} \oint_{\partial S} \frac{f(z)}{z - b} = \frac{a - b}{2\pi i} \oint_{\partial S} \frac{f(z)}{(z - a)(z - b)}$$

→ we again use the maximum-length estimate

$$|f(a) - f(b)| \leq \text{Per}(S) \cdot \max_{z \in \partial S} \frac{|f(z)|}{|z - a||z - b|} \leq \text{Per}(S) \cdot \frac{M}{\text{Per}(S)^2 / 144} = \frac{144M}{4s} = \frac{36M}{s}$$

→ we now let  $s \rightarrow \infty$  and get  $f(a) - f(b) \rightarrow 0$  □

Proof of entire  $\Rightarrow$  analytic - we will not show holomorphic  $\Rightarrow$  analytic

→ let  $f: \mathbb{C} \rightarrow \mathbb{C}$  be entire, let  $z_0 \in \mathbb{C}$  and create a sufficiently large rectangle  $R$  containing both  $\bar{\sigma}$  and  $z_0$  s.t. for  $\forall z \in \partial R$

$$\left| \frac{z_0}{z} \right| = \frac{|z_0|}{|z|} \leq \frac{1}{2} \quad \text{and} \quad |z - z_0| \geq 1 \quad \text{④}$$

→ for any  $m \in \mathbb{N}$  we have using the Cauchy formula

$$f(z_0) = \frac{1}{2\pi i} \oint_{\partial R} \frac{f(z)}{z - z_0} = \frac{1}{2\pi i} \oint_{\partial R} \frac{f(z)}{z} \cdot \frac{1}{1 - \frac{z_0}{z}} dz$$

→ now we use the formula  $\frac{1}{1-x} = 1+x+x^2+\dots+x^m + \frac{x^{m+1}}{1-x}$  for  $x = \frac{z_0}{z}$

$$\begin{aligned} f(z_0) &= \frac{1}{2\pi i} \oint_{\partial R} \frac{f(z)}{z} \cdot \left( \sum_{k=0}^m \left(\frac{z_0}{z}\right)^k + \frac{(z_0/z)^{m+1}}{1 - z_0/z} \right) dz \\ &= \sum_{k=0}^m \underbrace{\left( \frac{1}{2\pi i} \oint_{\partial R} \frac{f(z)}{z^{k+1}} dz \right)}_{a_m} z_0^k + \underbrace{\frac{1}{2\pi i} \oint_{\partial R} \frac{f(z)}{z - z_0} \cdot \left(\frac{z_0}{z}\right)^{m+1} dz}_{I_{m+1}} \end{aligned}$$

→ now we again use the max-length estimate for  $I_{m+1}$ : for  $m \rightarrow \infty$

$$|I_{m+1}| \leq \text{Per}(R) \cdot \max_{z \in \partial R} |f(z)| \cdot \underbrace{\frac{1}{|z - z_0|}}_{\leq 1} \cdot \underbrace{\left|\frac{z_0}{z}\right|^{m+1}}_{\leq \frac{1}{2}} \leq \text{Per}(R) \cdot \frac{1}{2^{m+1}} \cdot \max_{z \in \partial R} |f(z)|$$

→ because  $f$  is holomorphic, it is continuous and because  $\partial R$  is compact,  $f$  attains a maximum value on  $\partial R \Rightarrow \max_{z \in \partial R} |f(z)|$  is bounded

$\Rightarrow$  for  $m \rightarrow \infty$  we get  $|I_{m+1}| \rightarrow 0$  and

$$f(z_0) = \sum_{k=0}^{\infty} a_k z_0^k, \text{ where } a_k = \frac{1}{2\pi i} \oint_{\partial S} \frac{f(z)}{z^{k+1}} = \frac{1}{2\pi i} \oint_{\partial S} \frac{f(z)}{z^{k+1}}, \text{ where } S \text{ is any rectangle containing the origin} \quad \square$$

Theorem (General Cauchy formula): Let  $f \in \mathcal{H}(U)$  and  $\gamma$  be a simple closed contour.

If  $\langle \gamma \rangle \cup \text{Int}(\gamma) \subseteq U$  and  $z_0 \in \text{Int}(\gamma)$ , then

$$\underline{f^{(n)}(z_0) = \frac{n!}{2\pi i} \oint_{\gamma} \frac{f(z)}{(z - z_0)^{n+1}}}$$

Proof: Now we know that holomorphic  $\Rightarrow$  analytic, so near  $z_0$  we have

$$f(z) = \sum_{n=0}^{\infty} a_n (z - z_0)^n \quad \Rightarrow \quad a_n = \frac{f^{(n)}(z_0)}{n!}, \text{ we claim: } a_n = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(z)}{(z - z_0)^{n+1}}$$

$$\begin{aligned} \Rightarrow \frac{1}{2\pi i} \oint_{\gamma} \frac{f(z)}{(z - z_0)^{n+1}} &= \frac{1}{2\pi i} \oint_{\gamma} \frac{\sum_{k=0}^{\infty} a_k (z - z_0)^k}{(z - z_0)^{n+1}} = \frac{1}{2\pi i} \oint_{\gamma} \sum_{k=0}^{\infty} a_k (z - z_0)^{k-n-1} \\ &= \frac{1}{2\pi i} \left( \underbrace{\sum_{k=0}^{n-1} a_k \oint_{\gamma} (z - z_0)^{k-n-1}}_{\neq 0} + \underbrace{a_n \oint_{\gamma} \frac{1}{z - z_0}}_{\neq 0 = 2\pi i} + \underbrace{\sum_{k=n+1}^{\infty} a_k \oint_{\gamma} (z - z_0)^{k-n-1}}_{\text{C.G.: } \oint = 0} \right) = a_n \end{aligned}$$

→ WLOG assume  $\gamma$  is a circle centered at  $z_0$  with small radius  $r$ :  $\gamma: [0, 2\pi] \mapsto z_0 + r \cdot e^{it}$

$$\oint_{\gamma} \frac{1}{(z - z_0)^k} = \int_0^{2\pi} \frac{i r e^{it}}{(r e^{it})^k} dt = \frac{i}{r^{k-1}} \int_0^{2\pi} e^{it(k-1)} dt \quad \begin{cases} k=1: \int_0^{2\pi} 1 dt = 2\pi i \\ k>1: \int_0^{2\pi} [e^{i2\pi} - e^{i \cdot 0}] = 0 \end{cases}$$

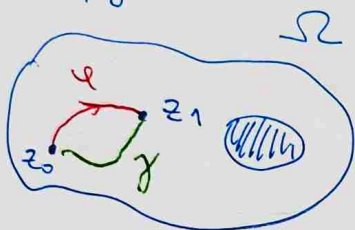
When is  $\int_\gamma f = \int_\varphi f$ ?

Suppose  $\Omega \subseteq \mathbb{C}$  is a domain (open, connected),  $f \in \mathcal{H}[\Omega]$ , } When?  
and we have contours  $\gamma, \varphi \subseteq \Omega$ , both  $z_0 \rightarrow z_1$ .  $\int_\gamma f = \int_\varphi f$  ~~⊗~~

①  $\Omega$  simply connected

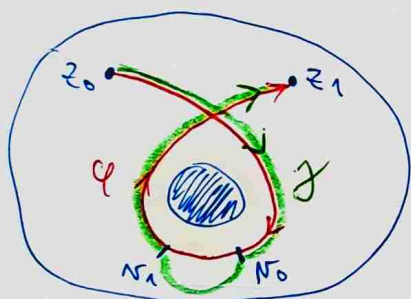
→ then  $f$  has an antiderivative  $F$  and  $\int_\gamma f = \int_\varphi f = F(z_1) - F(z_0)$   
 $\Rightarrow$  ~~⊗~~ holds

②  $\exists$  simply connected  $\Omega' \subseteq \Omega$  containing  $\varphi, \gamma$



→ this is clearly credible for ①  
 $\Rightarrow$  ~~⊗~~ holds

③  $\gamma, \varphi$  almost same



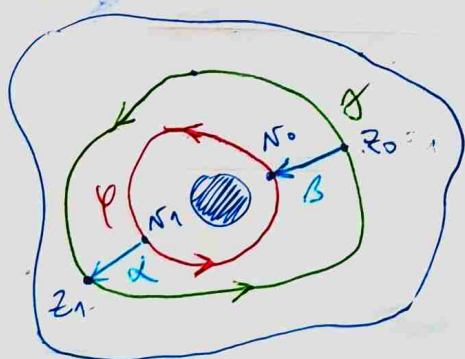
$$\varphi = \varphi_1(z_0, n_0) \oplus \varphi_2(n_0, n_1) \oplus \varphi_3(n_1, z_1)$$

$$\gamma = \gamma_1(z_0, n_0) \oplus \gamma_2(n_0, n_1) \oplus \gamma_3(n_1, z_1)$$

👁 using ②:  $\int_{\varphi_2} f = \int_{\gamma_2} f$

because  $\int_\varphi + \int_\gamma = \int_{\varphi \oplus \gamma} \Rightarrow$  ~~⊗~~ holds

④  $\gamma, \varphi$  Jordan curves sharing interior holes - not even touching



$$\gamma = \gamma_1(z_0, z_1) \oplus \gamma_2(z_1, z_0)$$

$$\varphi = \varphi_1(n_0, n_1) \oplus \varphi_2(n_1, n_0)$$

👁  $\int_{\gamma_1} = \int_\beta \oplus \varphi_1 \oplus \alpha$

👁  $\int_{\gamma_2} = \int_{(-\alpha)} \oplus \varphi_2 \oplus (-\beta)$

because ②

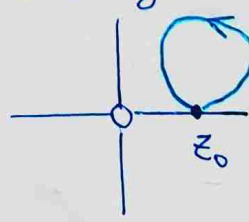
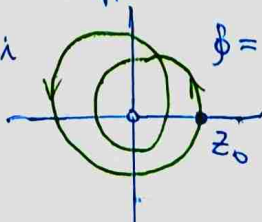
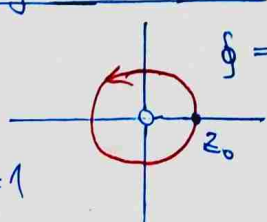
$\Rightarrow$  ~~⊗~~ holds

$$\Rightarrow \int_\gamma = \int_{\gamma_1} + \int_{\gamma_2} = \int_\beta + \int_{\varphi_1} + \int_\alpha - \int_\alpha + \int_{\varphi_2} - \int_\beta = \int_{\varphi_1} + \int_{\varphi_2} = \int_\varphi$$

⑤  $\gamma, \varphi$  touching closed curves, but different holes or winding number  $\Rightarrow$  ~~⊗~~ breaks

$$\Omega = \mathbb{C} \setminus \{0\}$$

$$f(z) = \frac{1}{z}, z_0 = 1$$



$$g = 0$$

## Homotopic curves $\rightarrow$ open & connected

Def: Let  $\Omega$  be a domain and  $\gamma_0, \gamma_1 \subseteq \Omega$  closed curves in  $\Omega$ .  
We say that  $\gamma_0$  and  $\gamma_1$  are (loop) homotopic  $\equiv$

$\exists$  map  $H(t, u)$ ,  $H: [0, 1] \times [0, 1] \rightarrow \Omega$  s.t.

① for  $\forall u \in [0, 1]$ , is the map  $\varphi_u: [0, 1] \rightarrow \Omega$ ,  $\varphi_u(t) = H(t, u)$   
a closed curve in  $\Omega$  and  $\langle \varphi_0 \rangle = \langle \gamma_0 \rangle$ ,  $\langle \varphi_1 \rangle = \langle \gamma_1 \rangle$

②  $H(t, u)$  is continuous in  $u$  & same orientation  $\Leftarrow$

Def: Let  $\Omega$  be a domain and  $\gamma_0, \gamma_1 \subseteq \Omega$  curves with the same endpoints.  
We say that  $\gamma_0$  and  $\gamma_1$  are (end-to-end) homotopic  $\equiv$

$\exists$  map  $H(t, u)$ ,  $H: [0, 1] \times [0, 1] \rightarrow \Omega$  s.t.

① for  $\forall u \in [0, 1]$ , is the map  $\varphi_u: [0, 1] \rightarrow \Omega$ ,  $\varphi_u(t) = H(t, u)$   
a curve in  $\Omega$  with the same endpoints and orientation as  $\gamma_0$  and  $\gamma_1$   
and  $\langle \varphi_0 \rangle = \langle \gamma_0 \rangle$  and  $\langle \varphi_1 \rangle = \langle \gamma_1 \rangle$

②  $H(t, u)$  is continuous in  $u$

Intuition: Two curves are homotopic in  $\Omega \equiv \exists$  continuous deformation  
between them that stays entirely within  $\Omega$ .

Fact: Let  $\Omega$  be a domain,  $\gamma, \ell$  homotopic in  $\Omega$ ,  $f \in \mathcal{H}[\Omega]$ . Then

$$\underline{\int_{\gamma} f = \int_{\ell} f} \quad \dots \text{ or } \oint_{\gamma} f = \oint_{\ell} f \text{ if they are closed.}$$

# The Complex Logarithm

→ let's first try the square root - define as an inverse of  $z \mapsto z^2$

⇒ consider  $f: z \mapsto z^2$ ,  $f^{-1}: z \mapsto \sqrt{z}$

→ look what happens in the unit circle

$f^{-1}$ : halving angles  
 $f$ : doubling angles

Theorem: If  $f \in \mathcal{H}[\mathcal{U}(z_0)]$  and  $f'(z_0) \neq 0$ , then  $f^{-1} \in \mathcal{H}[\mathcal{U}(z_0)]$ .

Proof: Let  $f$  be holomorphic on some  $\mathcal{U}(z_0) \Rightarrow$  it is analytic at  $z_0$

⇒ near  $z_0$ :  $f(z) = \sum a_n(z-z_0)^n$

Well known results of formal power series:

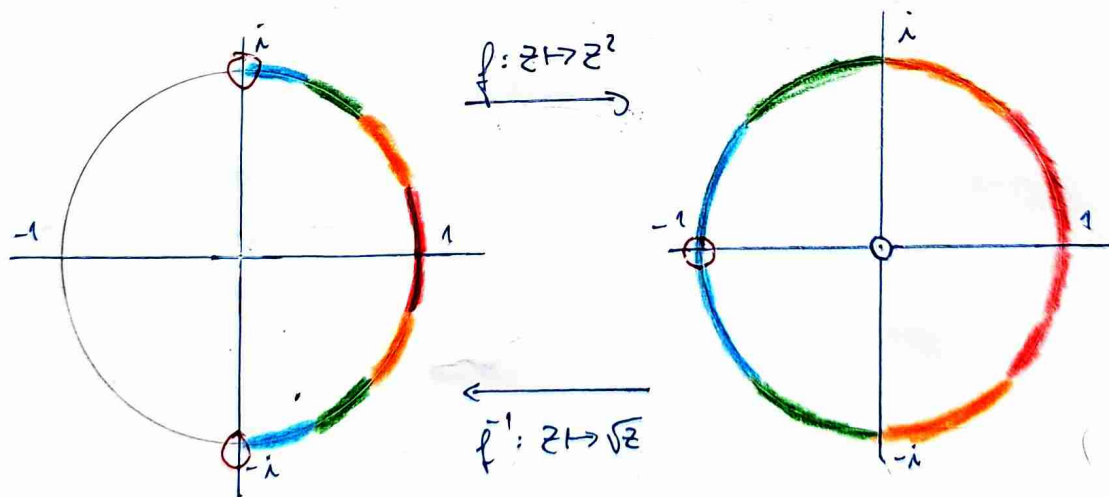
• A necessary condition for a FPS  $A(x) = \sum a_n x^n$  to have a composition inverse is  $a_1 \neq 0$

⦿  $f'(z_0) = a_1 \Rightarrow f'(z_0) \neq 0$  is necessary for  $f^{-1}$  to be analytic at  $z_0$  and we know analytic  $\Leftrightarrow$  holomorphic

Consequence: We want  $\sqrt{z}$  to be holomorphic ... an analytic continuation of  $\sqrt{x}: \mathbb{R} \rightarrow \mathbb{R}$

⇒ necessary condition:  $f'(z) = (z^2)' = 2z \neq 0 \Rightarrow z \neq 0$

⇒ we need to exclude  $z_0=0$  from the definition domain of  $\sqrt{z}$



Problem: Clearly  $f(i) = f(-i) = -1$ , but what should  $f'(-1) = \sqrt{-1}$  be?

Fact:  $x \mapsto \sqrt{x}$  has no analytic continuation to any domain that contains any Jordan curve around the origin

⇒ we need to choose a "simple" domain - for example  $\Omega = \mathbb{C} \setminus (-\infty, 0]$

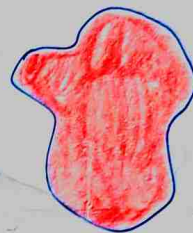
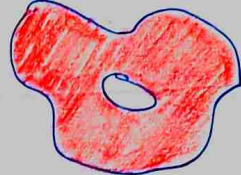
and define:  $z = r e^{i\theta} \Rightarrow \sqrt{z} := \sqrt{r} \cdot e^{i\frac{\theta}{2}}$

What is happening here?

Def:  $\Omega \subseteq \mathbb{C}$  is a domain  $\equiv$  it is open and connected

Def:  $\Omega \subseteq \mathbb{C}$  is a simply connected domain  $\equiv$  it is a domain and

- informally: doesn't contain any holes
- formally:  $(\mathbb{C} \cup \{\infty\}) \setminus \Omega$  is connected
- differently: for  $\forall$  Jordan curve  $\gamma \subseteq \Omega$ :  $\text{Int}(\gamma) \subseteq \Omega$



Def: We can define the complex logarithm on any SCD  $\Omega$  s.t.  $0 \notin \Omega$  as

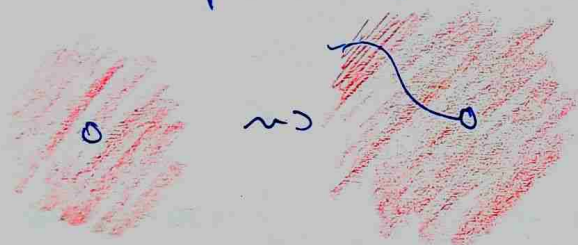
$$L(z_0) := \begin{cases} 0, & z_0 = 1 \\ \int_{\gamma} \frac{1}{z} \end{cases}, \quad \text{where } \gamma \in \Omega \text{ is any contour going } 1 \rightarrow z_0$$

Note: Usually  $\Omega = \mathbb{C} \setminus (-\infty, 0]$

Why does this work?

$\rightarrow \frac{1}{z}$  not defined at 0 so we need to exclude 0 from  $\Omega$

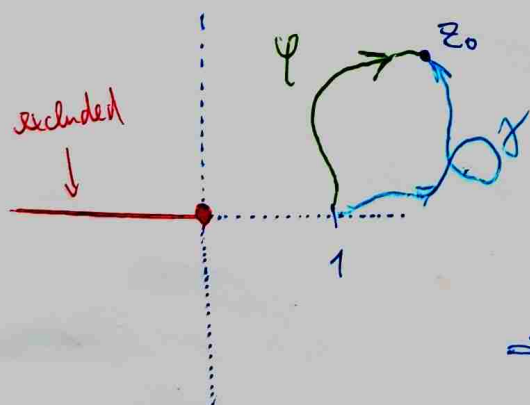
$\rightarrow$  in order for the definition to be valid, we need  $\Omega$  to be simply connected



$\Rightarrow$  we need to exclude some path going from 0 to infinity  $\leftarrow$  branch cut

claim: When  $\Omega \not\ni 0$  is a SCD, then the definition is correct

$\rightarrow$  let  $\gamma, \gamma' \subseteq \Omega$  be two different  $1 \rightarrow z_0$  curves: need  $\int_{\gamma} \frac{1}{z} = \int_{\gamma'} \frac{1}{z}$



$\Rightarrow$  define  $\Psi := \gamma \oplus (-\gamma')$  ... closed contour

Cauchy-Goursat: because  $\frac{1}{z} \in \mathcal{H}[\Omega]$  and

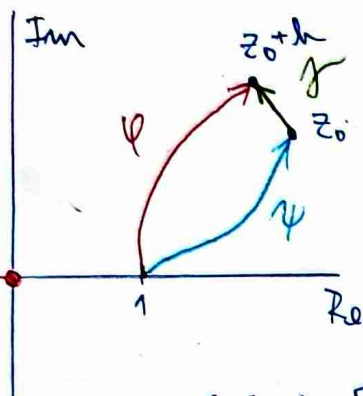
$\otimes \text{Int}(\Psi) \subseteq \Omega$  we have  $\oint_{\Psi} \frac{1}{z} = 0$

$$\Rightarrow \oint_{\Psi} \frac{1}{z} = \int_{\gamma} \frac{1}{z} + \int_{-\gamma'} \frac{1}{z} = \int_{\gamma} \frac{1}{z} - \int_{\gamma'} \frac{1}{z} = 0 \Rightarrow \underline{\underline{\int_{\gamma} \frac{1}{z} = \int_{\gamma'} \frac{1}{z}}}$$

$\otimes \Psi$  isn't guaranteed to be a Jordan curve, but any closed curve can be composed of Jordan curves

Correctness of  $L(z)$ : If  $\Omega \neq \emptyset$  is SCD, then  $L(z) \in \mathcal{H}[\Omega]$  and  $L'(z) = \frac{1}{z}$ .

$$L'(z_0) = \lim_{h \rightarrow 0} \frac{L(z_0+h) - L(z_0)}{h}$$



👁  $L(z_0+h) - L(z_0) = \int_{\varphi} - \int_{\psi} = \int_{\gamma}$

$$\hookrightarrow \gamma = \underbrace{\varphi \oplus (-\psi) \oplus (-\gamma) \oplus \gamma}_{\text{Cancel: } \oint = 0} \quad \underbrace{\int_{\gamma}}_{\int_{\gamma}}$$

$$\Rightarrow \text{let } \gamma: [0,1] \rightarrow \mathbb{C}, \gamma(t) = z_0 + th \Rightarrow \int_{\gamma} \frac{1}{z} = \int_0^1 \frac{h}{z_0 + th} dt$$

$$\Rightarrow \frac{L(z_0+h) - L(z_0)}{h} = \frac{1}{h} \int_0^1 \frac{h}{z_0 + th} dt = \int_0^1 \frac{dt}{z_0 + th} \xrightarrow{h \rightarrow 0} \int_0^1 \frac{dt}{z_0} = \frac{1}{z_0} \quad \square$$

Theorem: Suppose  $f: \Omega \rightarrow \mathbb{C}$  is holomorphic and  $\Omega$  is a simply connected domain.

Then  $f$  has a primitive function on  $\Omega \dots \exists F(z) \in \mathcal{H}[\Omega]$  s.t.  $F' = f$ .

Proof: This is a direct generalization of what we just did.

① pick any  $s \in \Omega$

② define for  $z_0 \in \Omega$ :  $F(z_0) := \begin{cases} 0, & z_0 = s \\ \int_{\gamma} f, & z_0 \neq s \end{cases}$ ,  $\gamma = \text{any } s \rightarrow z_0 \text{ contour contained in } \Omega$

③ repeat what we did for the logarithm

$$\hookrightarrow F = L, \quad f = \frac{1}{z} \quad \square$$

Correctness of  $L(z)$ :  $\exp(L(z)) = z$

$\rightarrow$  define  $y(z) := \exp(L(z))$ , we will show  $y(z) = z$

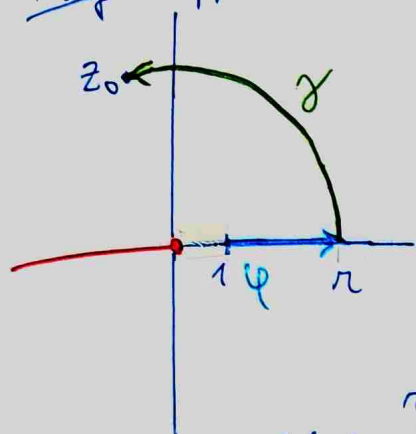
$$y'(z) = \exp(L(z)) \cdot L'(z) = y(z) \cdot \frac{1}{z}$$

👁 separable differential equation and  $y(z) = z$  is a solution...  $1 = z \cdot \frac{1}{z} \checkmark$

Initial condition: we defined  $L(1) = 0 \dots f(1) = \exp(L(1)) = \exp(0) = 1 \checkmark$

Theorem (Log principle value): When  $\Omega = \mathbb{C} \setminus (-\infty, 0]$  and  $z \in \Omega$ , then  
 $L(z) = \ln|z| + \arg(z)$ , where  $\arg(z) \in (-\pi, \pi)$

Proof: Suppose  $z_0 = r \cdot e^{i\theta}$ ,  $\theta \in (-\pi, \pi)$  ... this covers every  $z \in \Omega$



$$\varphi: [0, 1] \rightarrow \mathbb{C}, \quad \varphi(t) = 1 + (r-1)t$$

$$\gamma: [0, \theta] \rightarrow \mathbb{C}, \quad \gamma(t) = r e^{it}$$

$$u = (r-1)t \\ du = (r-1) dt$$

$$L(z_0) = \int_{\varphi \oplus \gamma} \frac{1}{z} = \int_{\varphi} \frac{1}{z} + \int_{\gamma} \frac{1}{z} = \int_0^1 \frac{(r-1)dt}{1+(r-1)t} + \int_0^\theta \frac{i r e^{it}}{r e^{it}} dt$$

$$\Rightarrow L(z_0) = \int_0^{r-1} \frac{du}{1+u} + \int_0^\theta i dt = \left[ \ln|1+u| \right]_0^{r-1} + i\theta = \ln|r| + i\theta$$

$$\downarrow \\ r = |z_0| > 0$$

## Matrix functions

### ① matrix logarithm

→ let  $\Omega = \mathbb{C} \setminus (-\infty, 0]$ ,  $a \in \Omega$  and  $\gamma: [0, 1] \rightarrow \mathbb{C}$ ,  $\gamma(t) = 1 + t(a-1)$

$$L(a) = \int_{\gamma} \frac{1}{z} = \int_0^1 \frac{a-1}{1+t(a-1)} dt$$

$$\rightarrow A \in \mathbb{C}^{n \times n} \Rightarrow \underline{\text{Log}(A) := \int_0^1 (A - I_n)(I_n + t(A - I_n))^{-1} dt}$$

☞ for this to be valid we need  $I_n + t(A - I_n)$  to be invertible for  $\forall t \in [0, 1]$

↳ Fact: this holds  $\Leftrightarrow \sigma(A) \cap (-\infty, 0] = \emptyset$  ...  $\sigma(A) =$  eigenvalues of A

### Remark:

$$\textcircled{*} \ln(1+z) = z - \frac{z^2}{2} + \frac{z^3}{3} - \frac{z^4}{4} + \dots = \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n} \cdot z^n$$

$$\Rightarrow \ln(I_n + A) := \sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n} \cdot A^n$$

problem:  $\textcircled{*}$  has radius of convergence = 1

⇒ this works only for A with spectral radius  $\rho(A) < 1$

$$\hookrightarrow \max \{ |\lambda| \mid \lambda \in \sigma(A) \}$$

## ② complex exponential - using Cauchy's formula

Cauchy:  $\Omega \subseteq \mathbb{C}$  simply connected domain,  $f(z) \in \mathcal{H}[\Omega]$ ,

$\gamma \subseteq \Omega$  Jordan curve and  $\text{Int}(\gamma) \subseteq \Omega$ . If  $a \in \text{Int}(\gamma)$ , then

$$f(a) = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(z)}{z-a}$$

exponential:

$$e^a = \frac{1}{2\pi i} \oint_{\gamma} \frac{e^z}{z-a}, \quad a \in \text{Int}(\gamma) \subseteq \Omega$$

matrix exp:

$$\underline{\exp(A) := \frac{1}{2\pi i} \oint_{\gamma} e^z (z \cdot I_m - A)^{-1} dz}, \quad \sigma(A) \subseteq \text{Int}(\gamma) \subseteq \Omega$$

general:

$$f(A) := \frac{1}{2\pi i} \oint_{\gamma} f(z) (z \cdot I_m - A)^{-1} dz, \quad \sigma(A) \subseteq \text{Int}(\gamma) \subseteq \Omega$$

## Singularities and poles

Def: Let  $f \in \mathcal{H}[U]$ . Then  $f$  has an isolated singularity at  $z_0 \in \mathbb{C} \equiv z_0 \notin U$  &  $\exists \varepsilon > 0$  s.t.  $\mathcal{U}_{<\varepsilon}^*(z_0) \subseteq U$ .  
 $\hookrightarrow$  pierced neighborhood

Example:

$$f(z) = \frac{1}{1 - \exp(z)}, \quad A := \{z \in \mathbb{C}, e^z = 1\} = \{2\pi i \cdot k \mid k \in \mathbb{Z}\}$$

$\hookrightarrow f(z) \in \mathcal{H}[\mathbb{C} \setminus A]$  and points in  $A$  are isolated singularities of  $f$

Def: Let  $z_0$  be an isolated singularity of  $f \in \mathcal{H}[U]$ . We say  $z_0$  is a

- pole of order  $d \in \mathbb{N}_0$   $\equiv f(z) \cdot (z - z_0)^d$  has an analytic continuation to  $U + z_0$ .
- essential singularity otherwise  $\hookrightarrow$  pole of order 0 = removable singularity

Def: We say that  $f^*: U^* \rightarrow \mathbb{C}$  is an analytic continuation of  $f: U \rightarrow \mathbb{C} \equiv$

①  $f \in \mathcal{H}[U]$  and  $f^* \in \mathcal{H}[U^*]$

②  $U \subseteq U^*$  and  $z \in U \Rightarrow f^*(z) = f(z)$

Examples:

①  $f(z) = \frac{\sin(z)}{z} : \mathbb{C} \setminus \{0\} \rightarrow \mathbb{C}$

removable singularity  
 $\nearrow$

$$\frac{\sin(z)}{z} = 1 - \frac{z^2}{3} + \frac{z^4}{5} - \dots \Rightarrow 0 \text{ is a pole of order } 0$$

②  $f(z) = \frac{z-3}{(z-2)^2(z-1)^3} : \mathbb{C} \setminus \{1, 2\} \rightarrow \mathbb{C}$

$\Rightarrow z = \text{pole of order } 2$

$1 = \text{pole of order } 3$

③  $f(z) = \exp\left(\frac{1}{z}\right) : \mathbb{C} \setminus \{0\} \rightarrow \mathbb{C}$

$\Rightarrow 0 = \text{essential singularity}$

$\hookrightarrow$  not obvious

Fact: If  $f$  has a pole of order  $d \geq 1$  at  $z_0$ , then  $\lim_{z \rightarrow z_0} |f(z)| = +\infty$

Theorem (Little Picard Theorem):  $f$  entire & non-constant  $\Rightarrow f[\mathbb{C}] = \mathbb{C} \setminus K, |K| \leq 1$ .

Intuition: Liouville:  $f$  entire & non-constant  $\Rightarrow f$  unbounded

$\hookrightarrow$  Picard says that it attains all values except at most one

Theorem (Great Picard Theorem):  $f \in \mathcal{H}[U]$  has essential singularity at  $z_0 \in U$ , then for  $\forall \varepsilon > 0$  denote  $\mathcal{V} := U \cap \mathcal{U}_{<\varepsilon}^*(z_0)$  and  $f[\mathcal{V}] = \mathbb{C} \setminus K, |K| \leq 1$ .

Corollary: If  $z_0$  is an isolated singularity of  $f \in \mathcal{H}[U]$  and  $f$  is bounded on some  $\mathcal{N}_{<\varepsilon}^*(z_0)$ , then  $z_0$  is removable (pole of order 0).

Def: Let  $f \in \mathcal{H}[U]$  and denote  $U^* := U \cup \{z \in \mathbb{C} \setminus U \mid z \text{ is a pole of } f\}$ .

Then we say that  $f$  is meromorphic on  $U^*$ .

Intuition: Holomorphic on  $U^*$  except for some isolated poles.

Example: Rational functions are meromorphic on  $\mathbb{C}$

$$\hookrightarrow f(z) = \frac{P(z)}{Q(z)}, \quad P, Q = \text{polynomials}$$

Fact:  $f \in \mathcal{H}[U]$  is meromorphic on  $U^* \Leftrightarrow f$  can be written as  $f(z) = \frac{h(z)}{g(z)}$ , where  $g, h \in \mathcal{H}[U^*]$  and  $h$  is not identically zero on  $U^*$ .

Fact: If  $f \in \mathcal{H}[U]$  is meromorphic on  $U^*$  and the set of poles  $K = U^* \setminus U$  is finite, then  $\exists$  rational function  $\pi: \mathbb{C} \setminus K \rightarrow \mathbb{C}$  and  $g \in \mathcal{H}[U^*]$  s.t.

$$\underline{f(z) = \pi(z) + g(z)} \quad \text{for } \forall z \in U$$

## Taylor and Laurent series

• Taylor series:  $f$  holomorphic on some  $\mathcal{N}_{<\varepsilon}^*(z_0)$ , then on  $\mathcal{N}$

$$f(z) = \sum_{n=0}^{\infty} a_n (z-z_0)^n, \quad a_n = \frac{1}{n!} f^{(n)}(z_0)$$

$$\underline{\text{Cauchy \& formula}}: a_n = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(z)}{(z-z_0)^{n+1}}, \quad \langle \gamma \rangle \subseteq \mathcal{N}, \quad \gamma \text{ Jordan curve}$$

• Laurent series:  $f$  holomorphic on some  $\mathcal{N}_{<\varepsilon}^*(z_0)$ , then on  $\mathcal{N}^*$

$$f(z) = \sum_{n=-\infty}^{\infty} a_n (z-z_0)^n, \quad a_n = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(z)}{(z-z_0)^{n+1}}, \quad \langle \gamma \rangle \subseteq \mathcal{N}^*, \quad \gamma \text{ Jordan}$$

Fact: The Laurent series always exists and the terms  $(a_n)$  are unique.

Corollary: When  $z_0$  is a removable singularity of  $f$ , then Laurent = Taylor

$\hookrightarrow$  Taylor is a valid L. series and it is unique

Remark: The negative powers part of a Laurent series is called its principle part

# The Simple Residue Theorem

→ simple closed  
→ piece-wise C<sup>1</sup>

Theorem: Let  $\gamma \subseteq \mathbb{C}$  be a positively oriented (counterclockwise) Jordan curve.  
Suppose  $f \in \mathcal{H}(U)$  has only finitely many isolated singularities inside  $\gamma$ ,  
 $z_1, \dots, z_k \in \text{Int}(\gamma)$  and denote  $U^* = U \cup \{z_1, \dots, z_k\}$ . If

- ①  $\langle \gamma \rangle \subseteq U$  ...  $\gamma$  doesn't go through any singularities of  $f$
- ②  $\text{Int}(\gamma) \subseteq U^*$  ...  $f$  is defined on some region containing  $\gamma$  up to the singularities

then

$$\oint_{\gamma} f = 2\pi i \sum_{k=1}^n \text{Res}(f, z_k),$$

where  $\text{Res}(f, z_k)$  is the coefficient  $a_{-1}$  in the Laurent series expansion around  $z_k$ . Suppose  $f$  holomorphic in  $\eta_{\epsilon}^*(z_k)$ , then

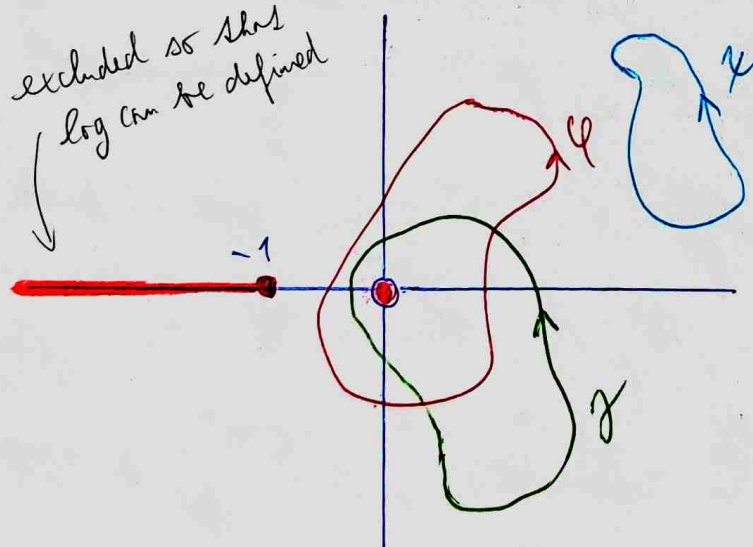
$$\Rightarrow \text{Res}(f, z_k) = \frac{1}{2\pi i} \oint_{\varphi} f, \quad \langle \varphi \rangle \subseteq \eta^*, \quad \varphi = \text{Jordan curve}$$

## Calculating Residues

$$\textcircled{1} f(z) = \frac{\ln(1+z)}{z^3} = (z - \frac{z^2}{2} + \frac{z^3}{3} - \frac{z^4}{4} + \dots) \cdot \frac{1}{z^3} \Rightarrow \text{Res}(f, 0) = -\frac{1}{2}$$

$$U = \mathbb{C} \setminus (-\infty, -1] \setminus K, \quad K = \{r\}$$

excluded so that  
log can be defined



$$\bullet \int_{\varphi} f = \int_{\gamma} f = 2\pi i \cdot (-\frac{1}{2}) = -\pi i$$

$$\bullet \int_{\varphi} f = \underline{\underline{0}}$$

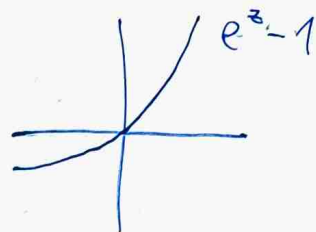
↳ but we also know this  
from the Cauchy - Goursat theorem

Proof: We will later proof a more general residue theorem formulation.

$$\textcircled{2} \quad \underline{f(z) = \frac{1}{e^z - 1}} \Rightarrow K = \{2\pi i \cdot k \mid k \in \mathbb{Z}\}$$

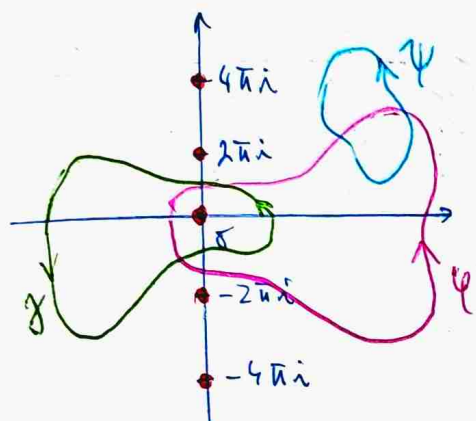
$\rightarrow$  calculate  $\text{Res}(f, 0)$

$$\textcircled{1} \text{ when } z \rightarrow 0, f(z) \rightarrow \frac{1}{z} \quad \because \lim_{z \rightarrow 0} \frac{e^z - 1}{z} = 1$$



$\Rightarrow$  guess Laurent around 0 is  $f(z) = \frac{1}{z} + B + Cz + Dz^2 + \dots$

because the first term is dominating when  $z \rightarrow 0 \Rightarrow \text{Res}(f, 0) = 1$



$$\int_{\gamma} f = \int_{\psi} f = 2\pi i$$

$$\int_{\psi} f = 0$$

Theorem: Suppose  $f \in \mathcal{H}(U)$  and  $z_0$  is a pole of  $f$ . What is  $\text{Res}(f, z_0)$ ?

① removable singularity  $\Rightarrow$  Laurent = Taylor  $\Rightarrow \underline{\text{Res}(f, z_0) = 0}$

② pole of order  $h \geq 1$   $\Rightarrow \exists g$  holomorphic on some  $\mathcal{U}_{\varepsilon}(z_0)$  s.t.  $g(z) \neq 0$  and

$$f(z) = \frac{g(z)}{(z - z_0)^h} \quad \text{and} \quad \text{Res}(f, z_0) = \frac{1}{(h-1)!} g^{(h-1)}(z_0)$$

Proof: Because  $g$  is holomorphic around  $z_0$ , it is analytic at  $z_0$  and it has a Taylor expansion at  $z_0$

$$g(z) = \sum_{n=0}^{\infty} a_n (z - z_0)^n, \quad a_n = \frac{1}{n!} g^{(n)}(z_0)$$

The Laurent expansion of  $f(z)$  around  $z_0$  therefore is

$$f(z) = \sum_{n=0}^{\infty} a_n (z - z_0)^{n-h} \Rightarrow [z^{-1}] f(z) = a_{h-1} = \frac{1}{(h-1)!} g^{(h-1)}(z_0)$$

Special cases:

$$\underline{f(z) = \frac{g(z)}{z - z_0}} \Rightarrow \text{Res}(f, z_0) = g(z_0)$$

$$\underline{f(z) = \frac{g(z)}{(z - z_0)^2}} \Rightarrow \text{Res}(f, z_0) = g'(z_0)$$

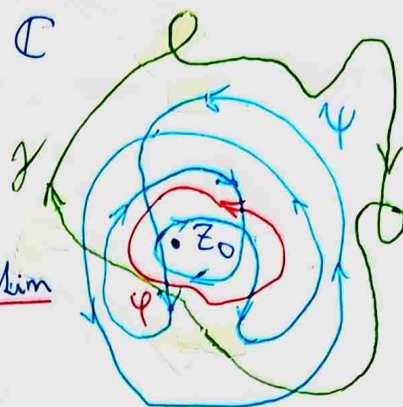
# The Winding Number

Def: Let  $\gamma \subseteq \mathbb{C}$  be a contour of finite length and let  $z_0 \in \mathbb{C} \setminus \langle \gamma \rangle$ .

The winding number of  $\gamma$  about  $z_0$  (or index of  $z_0$  w.r.t.  $\gamma$ ) is

$$\text{Ind}_\gamma(z_0) = \frac{1}{2\pi i} \int_\gamma \frac{1}{z - z_0} \in \mathbb{C}$$

Intuition: When  $\gamma$  is closed,  $\text{Ind}_\gamma$  counts the # of times  $\gamma$  winds about  $z_0$  in the positive (counterclockwise) direction



$$\text{Ind}_\psi = 1$$

$$\text{Ind}_\psi = 0$$

$$\text{Ind}_\gamma = -1$$

→ for simplicity suppose  $z_0 = \text{origin}$

→ imagine the change of  $z = r e^{i\theta}$  along  $\gamma$

↳ what is  $dz$ ? ... because  $dz$  is infinitely small:  $dz = dr + i r d\theta$

$$\Rightarrow dz = dr + i r d\theta = \frac{dz}{dr} dr + \frac{dz}{d\theta} d\theta = e^{i\theta} dr + i r e^{i\theta} d\theta$$

$$\Rightarrow \frac{dz}{z} = \frac{dr}{r} + i d\theta$$

$$\Rightarrow \int_\gamma \frac{dz}{z} = \int_\gamma \frac{dr}{r} + i \int_\gamma d\theta$$

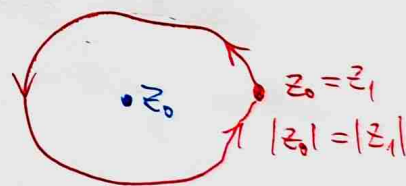
$\left. \begin{array}{l} \bullet \int_\gamma \frac{dr}{r} = \text{continuous change in } \frac{1}{r} \text{ along } \gamma \\ \bullet \int_\gamma d\theta = \text{continuous change in } \theta \text{ along } \gamma \end{array} \right\} \text{ since } \gamma \text{ is a contour } \Rightarrow$   
 $\text{ind}: \mathbb{C} \setminus \langle \gamma \rangle \rightarrow \mathbb{C} \text{ is a continuous function}$

→ what if  $\gamma$  is closed?

$\oint_\gamma \frac{dr}{r} = 0$   $\because$  the start and end  $r = |z|$  is the same  $\Rightarrow$  total change = 0

$\Rightarrow \oint_\gamma \frac{dz}{z} = i \cdot \text{The total change in Angle}$

$\Rightarrow$  that is why  $\text{Ind} = \frac{1}{2\pi i} \oint \frac{dz}{z}$  ... we want # trips about 0



## Properties of Ind

①  $\text{ind}: \mathbb{C} \setminus \langle \gamma \rangle \rightarrow \mathbb{C}$ ,  $\text{ind}(z) = \text{Ind}_\gamma(z)$  is continuous

②  $\gamma$  closed  $\Rightarrow \text{Ind}_\gamma(z_0) \in \mathbb{Z}$

③  $\gamma = \psi \oplus \phi$   $\Rightarrow \text{Ind}_\gamma(z_0) = \text{Ind}_\psi(z_0) + \text{Ind}_\phi(z_0)$

Def: The interior of a closed curve  $\gamma$  is  $\text{Int}(\gamma) := \{z \in \mathbb{C} \mid \text{Ind}_\gamma(z) \neq 0\}$

Lemma: If  $\gamma$  is a closed contour, then  $\text{ind}_\gamma: \mathbb{C} \setminus \langle \gamma \rangle \rightarrow \mathbb{Z}$  is constant on the connected components of  $\mathbb{C} \setminus \langle \gamma \rangle$ .

Proof: Directly follows from properties ① and ②

### Jordan Curve Theorem

$\rightarrow$  let  $\gamma \subseteq \mathbb{R}^2$  be Jordan curve  $\equiv$  simple & closed

Theorem (meat J. thm):  $\mathbb{R}^2 \setminus \langle \gamma \rangle$  is disconnected.

Theorem (Jordan Theorem):  $\mathbb{R}^2 \setminus \langle \gamma \rangle$  has exactly two connected components:

① a bounded region  $\rightarrow$  the interior of  $\gamma \Rightarrow \text{Int}(\gamma)$

② an unbounded region  $\rightarrow$  the exterior of  $\gamma$

and  $\gamma$  is their common boundary

Theorem (Jordan - Schoenflies thm): Moreover, the bounded component of  $\mathbb{R}^2 \setminus \langle \gamma \rangle$  is homeomorphic to an open disk in  $\mathbb{R}^2$ .

$\Rightarrow \exists$  homeomorphism  $H: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  which maps

•  $\text{Int}(\gamma)$  to the open unit disk  $\{z \in \mathbb{R}^2 \mid |z| < 1\}$

•  $\langle \gamma \rangle$  to the unit circle  $\{z \in \mathbb{R}^2 \mid |z| = 1\}$

Recall: Homeomorphism is a bijection  $f: X \rightarrow Y$  s.t. both  $f$  and  $f^{-1}$  are continuous.

~~⊗~~ Because  $\mathbb{R}^2$  and  $\mathbb{C}$  are homeomorphic, it doesn't matter where we work

Theorem (Maurer's lemma): Let  $\gamma: I \rightarrow \mathbb{C}$  be a closed curve and  $z_0, z_1 \in \mathbb{C} \setminus \langle \gamma \rangle$  s.t.

$z_1$  lies left of  $z_0$ , that is  $\text{Im}(z_0) = \text{Im}(z_1)$ ,  $\text{Re}(z_0) > \text{Re}(z_1)$ .

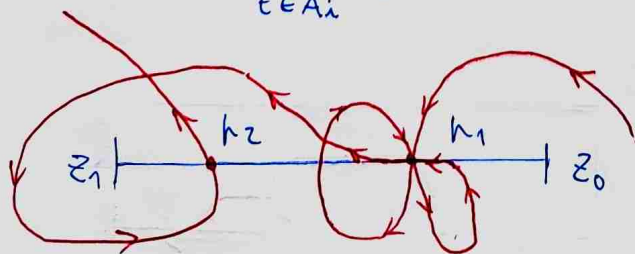
Let  $\gamma$  intersect the segment  $\overline{z_0 z_1}$  at  $\langle \gamma \rangle \cap \langle z_0 z_1 \rangle = \{t_i\}_{i \in I}$   $\rightarrow$  could be infinite

and denote  $A_i := \{t \in I \mid \gamma(t) = t_i\}$ . If  $\forall t_0 \in A_i: \gamma'(t_0)$  is continuous,

then

$$\text{Ind}_\gamma(z_1) = \text{Ind}_\gamma(z_0) + \sum_{i \in I} \delta_i, \text{ where}$$

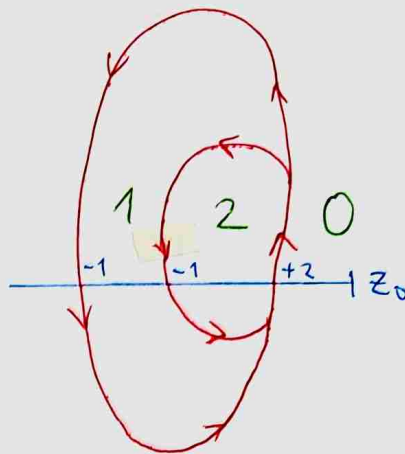
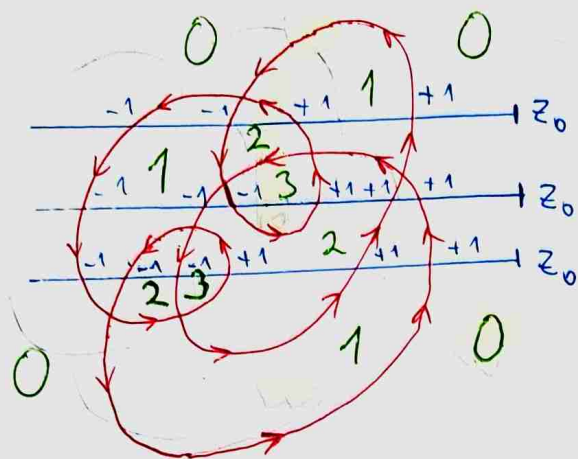
$$\delta_i := \sum_{t \in A_i} \text{sign}(\text{Im}(\gamma'(t))) = \sum \begin{pmatrix} +1 & \text{if } \gamma \text{ is going up at } \gamma(t) \\ -1 & \text{if } \gamma \text{ is going down at } \gamma(t) \end{pmatrix}$$



$$\delta_1 = -1 - 1 + 0 = -2$$

$$\delta_2 = +1$$

Example:



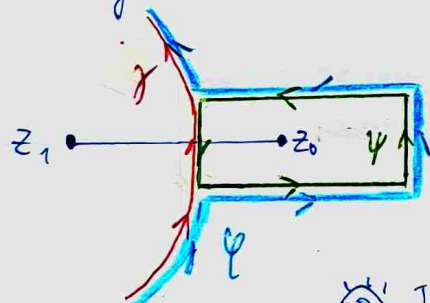
Proof: Induction by # connected components of  $\langle z_0 z_1 \rangle \setminus \langle \gamma \rangle$

① if # components = 1, then  $\gamma$  doesn't cut  $\overrightarrow{z_0 z_1}$  and so  $z_0$  and  $z_1$  are in the same component of  $\mathbb{C} \setminus \langle \gamma \rangle$  (they are connected by  $\overrightarrow{z_0 z_1}$ )

$\Rightarrow \text{Ind}_\gamma(z_0) = \text{Ind}_\gamma(z_1) \dots$  ind $_\gamma$  is constant on the components of  $\mathbb{C} \setminus \langle \gamma \rangle$

② WLOG assume # components = 2 ... bigger by induction

→ for simplicity assume that  $\langle \gamma \rangle \cap \langle z_0 z_1 \rangle = \{p\}$  and that  $\gamma$  intersects  $\overrightarrow{z_0 z_1}$  at  $p$  only once



→ we will create a simple closed  $\psi$  encapsulating  $z_0$  and going through  $p$  at the opposite direction

$$\Rightarrow \psi := \gamma \oplus \psi$$

⊙  $\text{Ind}_\psi(z_1) = \text{Ind}_\psi(z_0) \because z_0$  and  $z_1$  are in the same component of  $\mathbb{C} \setminus \langle \psi \rangle$

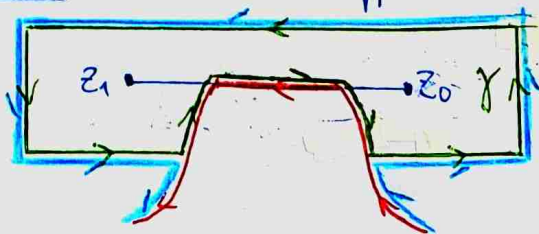
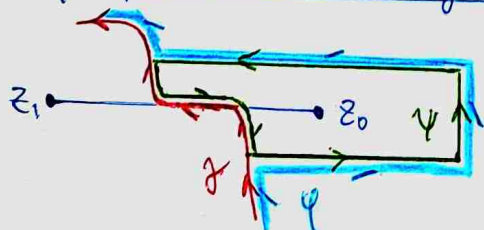
→ suppose that  $\gamma$  is going up through  $p$

$$\left. \begin{array}{l} \text{Ind}_\psi(z_1) = \text{Ind}_\gamma(z_1) + \text{Ind}_\psi(z_1) = \text{Ind}_\gamma(z_1) + 0 \\ \text{Ind}_\psi(z_0) = \text{Ind}_\gamma(z_0) + \text{Ind}_\psi(z_0) = \text{Ind}_\gamma(z_0) + 1 \end{array} \right\} \underline{\underline{\text{Ind}_\gamma(z_1) = \text{Ind}_\gamma(z_0) + 1}}$$

• if  $\gamma$  intersects  $\overrightarrow{z_0 z_1}$  at  $p$  more than once

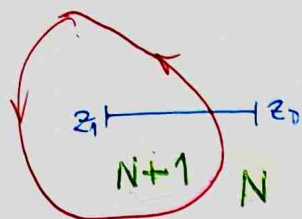
$\Rightarrow$  simply repeat this process for each intersection

• if  $\langle \gamma \rangle \cap \langle z_0 z_1 \rangle$  is a segment  $\langle v_0 v_1 \rangle \rightarrow$  create a different  $\psi$



Corollary: Jordan's weak theorem holds.

Proof: Let  $\gamma$  be a simple closed curve.



Recall:  $\text{Ind}_\gamma$  is constant on connected components of  $\mathbb{C} \setminus \langle \gamma \rangle$

Remark: It is easy to see, that there  $\exists z_0, z_1 \in \mathbb{C} \setminus \langle \gamma \rangle$ ,  $z_1$  left of  $z_0$  s.t.  $\text{Ind}_\gamma(z_1) = \text{Ind}_\gamma(z_0) \pm 1$

$\Rightarrow \text{Ind}$  is not constant  $\Rightarrow \mathbb{C} \setminus \langle \gamma \rangle$  is not connected  $\square$

## The General Residue Theorem

$\hookrightarrow$  piece wise  $C^1$

Theorem: Let  $\gamma \subseteq \mathbb{C}$  be a closed contour with finite length.

Suppose  $f \in \mathcal{H}(U)$  has isolated singularities  $K$  and denote  $U^* := U \cup K$ . If

①  $\langle \gamma \rangle \subseteq U$

②  $U^*$  is simply connected = doesn't contain any "holes"

③  $f$  has only finitely many singularities  $z_1, \dots, z_n$  s.t.  $\text{Ind}_\gamma(z_k) \neq 0$

then

$$\oint_\gamma f = 2\pi i \sum_{k=1}^n \text{Ind}_\gamma(z_k) \cdot \text{Res}(f, z_k)$$

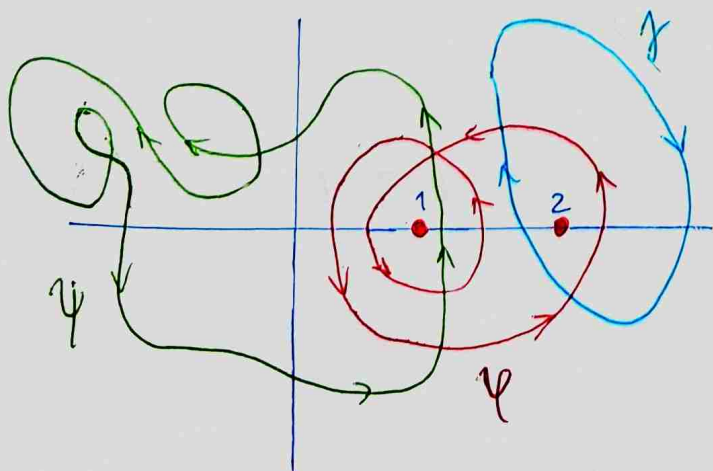
## Example

$$f(z) = \frac{\sin(\frac{\pi}{4}z)}{(z-1)(z-2)^2}$$

$\Rightarrow$  poles  $\begin{cases} z_1 = 1 \text{ of degree } 1 \\ z_2 = 2 \text{ of degree } 2 \end{cases}$

$$\text{Res}(f, 1) = \left. \frac{\sin(\frac{\pi}{4}z)}{(z-2)^2} \right|_{z=1} = \frac{\sin(\frac{\pi}{4})}{(1-2)^2} = \frac{\sqrt{2}}{2}$$

$$\text{Res}(f, 2) = \left. \frac{d}{dz} \frac{\sin(\frac{\pi}{4}z)}{z-1} \right|_{z=2} = \frac{\frac{\pi}{4} \cos(\frac{\pi}{4}z)(z-1) - \sin(\frac{\pi}{4}z)}{(z-1)^2} \Big|_{z=2} = \frac{\frac{\pi}{4} \cos(\frac{\pi}{2}) - \sin(\frac{\pi}{2})}{1} = -1$$



$$\oint_\gamma f = -(-1) = \underline{1}$$

$$\oint_\gamma f = \frac{\sqrt{2}}{2}$$

$$\oint_\gamma f = 2 \cdot \frac{\sqrt{2}}{2} - 1 = \underline{\underline{\sqrt{2} - 1}}$$

# Generalized Cauchy-Goursat Theorem

Def: For an open region  $U \subseteq \mathbb{C}$  we define its boundary as  $\partial U = \overline{U} \setminus U$ .

Theorem (Standard C.-G.): Let  $\Omega$  be a simply connected domain and  $f \in \mathcal{H}[\Omega]$ .

If  $\gamma \subseteq \Omega$  is a Jordan contour, then  $\oint_{\gamma} f = 0$ .

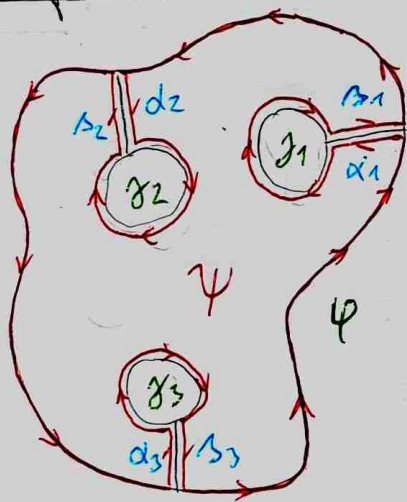
Theorem (Generalized C.-G.): Let  $\Omega$  be a bounded domain whose boundary consists of finitely many positively oriented Jordan contours

- $\mathcal{C}$  ... the outer boundary
- $\gamma_1, \dots, \gamma_n$  ... the inner boundaries of "holes" in  $\Omega$

Let  $U \subseteq \mathbb{C}$  be an open region s.t.  $\overline{\Omega} \subseteq U$  and let  $f \in \mathcal{H}[U]$ . Then

$$\oint_{\mathcal{C}} f = \sum_{i=1}^n \oint_{\gamma_i} f$$

Proof idea:



① from each  $\gamma_i$  we draw a smooth line to  $\mathcal{C}$  s.t. none of these lines intersect

② remove these lines from  $\Omega \rightsquigarrow \Omega'$

👁  $\Omega'$  is now simply connected

③ create a new Jordan contour  $\Psi \subseteq \Omega'$  which traces the boundary of  $\Omega'$  using  $\mathcal{C}$ ,  $\gamma_1, \dots, \gamma_n$  and bridges  $\alpha_i, \beta_i$  along the lines which created  $\Omega'$

$\hookrightarrow \Omega'$  is simply connected &  $\Psi \subseteq \Omega'$  is Jordan  $\Rightarrow \oint_{\Psi} f = 0$

$$\Psi = \hat{\mathcal{C}} \oplus \sum_{i=1}^n (\alpha_i \oplus (-\hat{\gamma}_i) \oplus \beta_i)$$

$\rightarrow$  where  $\hat{\mathcal{C}}, \hat{\gamma}_i$  are  $\mathcal{C}, \gamma_i$  missing a little segment

$\rightarrow$  because  $\overline{\Omega'} = \overline{\Omega}$ , we can let the bridges  $\alpha_i$  and  $\beta_i$  get arbitrarily close

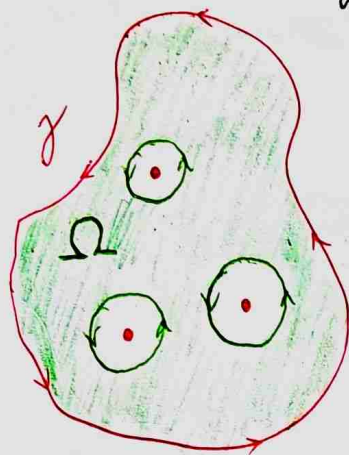
$$\Rightarrow \hat{\mathcal{C}} \rightarrow \mathcal{C}, \hat{\gamma}_i \rightarrow \gamma_i, \beta_i \rightarrow -\alpha_i \Rightarrow \Psi \rightarrow \mathcal{C} \oplus \sum_{i=1}^n (-\gamma_i)$$

$$\Rightarrow \oint_{\Psi} f = 0 \Rightarrow \oint_{\mathcal{C}} f - \sum_{i=1}^n \oint_{\gamma_i} f = 0 \Rightarrow \oint_{\mathcal{C}} f = \sum_{i=1}^n \oint_{\gamma_i} f$$



# Proof of the Residue Theorem

→ for simplicity assume that the closed contour  $\gamma$  is simple (Jordan) and positively oriented



→ let  $z_1, \dots, z_m$  be the singularities of  $f$  inside  $\text{Int}(\gamma)$

① for each  $z_i$ , choose a small positively oriented Jordan  $\gamma_i$  around  $z_i$  s.t.  $\langle \gamma_i \rangle \subseteq \text{Int}(\gamma)$  and  $\langle \gamma_i \rangle \cap \langle \gamma_j \rangle = \emptyset$

② let  $\Omega := \text{Int}(\gamma) \setminus \bigcup_{i=1}^m (\langle \gamma_i \rangle \cup \text{Int}(\gamma_i))$

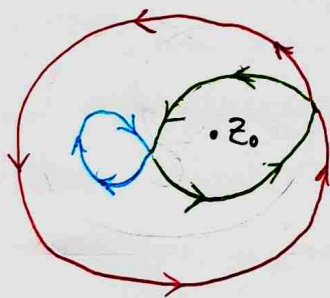
☞  $f \in \mathcal{H}[\Omega]$  because we removed all of the singularities

③ use the generalized Cauchy-Goursat theorem

$$\oint_{\gamma} f = \sum_{i=1}^m \oint_{\gamma_i} f = 2\pi i \cdot \sum_{i=1}^m \text{Res}(f, z_i) \quad \text{from the def. of residues}$$

→ what if  $\gamma$  is not simple?

☞ every closed contour  $\gamma$  of finite length can be decomposed into finitely many Jordan contours  $\gamma_1, \dots, \gamma_m$  s.t.  $\gamma = \gamma_1 \oplus \dots \oplus \gamma_m$



→ let  $z_1, \dots, z_m$  be the singularities  $z_j$  of  $f$  for which  $\exists \gamma_i$  s.t.  $z_j \in \text{Int}(\gamma_i)$

☞ for each  $\gamma_i$  we have

$$\text{Ind}_{\gamma_i}(z_j) = \begin{cases} 0, & z_j \notin \text{Int}(\gamma_i) \\ +1, & z_j \in \text{Int}(\gamma_i) \text{ \& } \gamma_i \text{ is positively oriented} \\ -1, & z_j \in \text{Int}(\gamma_i) \text{ \& } \gamma_i \text{ is negatively oriented} \end{cases}$$

⇒ using the simple version we have

$$\oint_{\gamma_i} f = 2\pi i \sum_{j=1}^m \text{Ind}_{\gamma_i}(z_j) \text{Res}(f, z_j)$$

→ earlier we assumed positive orient.  $\Rightarrow \text{Ind} = 1$

→ because  $\text{Ind}_{\alpha \oplus \beta}(z) = \text{Ind}_{\alpha}(z) + \text{Ind}_{\beta}(z)$  and  $\int_{\alpha \oplus \beta} f = \int_{\alpha} f + \int_{\beta} f$

$$\text{Ind}_{\gamma}(z_j) = \sum_{i=1}^k \text{Ind}_{\gamma_i}(z_j)$$

$$\oint_{\gamma} f = \sum_{i=1}^k \oint_{\gamma_i} f = 2\pi i \sum_{i=1}^k \sum_{j=1}^m \text{Ind}_{\gamma_i}(z_j) \text{Res}(f, z_j)$$

$$= 2\pi i \sum_{j=1}^m \text{Res}(f, z_j) \sum_{i=1}^k \text{Ind}_{\gamma_i}(z_j) = 2\pi i \sum_{j=1}^m \text{Res}(f, z_j) \text{Ind}_{\gamma}(z_j)$$

# Poles and Zeros

→ zeros of a function are the dual concept of poles

Fact:  $f$  analytic in a domain  $\Omega$ ,  $\text{zero}(f) := \{z \in \Omega \mid f(z) = 0\}$ , then either  $\text{zero}(f) = \Omega$  or  $\text{zero}(f)$  is a discrete set  $\equiv \forall z_0 \in \text{zero}(f)$  is isolated in  $\mathbb{C}$ .

Consequence:  $f \not\equiv 0$  analytic at  $z_0 \Rightarrow \exists M: \frac{f(z)}{(z-z_0)^M}$  nonzero on some  $\mathcal{N}_{\mathbb{C}}(z_0)$

↳ let  $A(x)$  be the series expansion of  $f$  and  $a_m$  the first non-zero coefficient

$$f(z) = \sum_{k=m}^{\infty} a_k (z-z_0)^k = (z-z_0)^m \underbrace{\sum_{k=0}^{\infty} a_{k+m} (z-z_0)^k}_{\text{analytic and nonzero on some } \mathcal{N}_{\mathbb{C}}(z_0)}$$

Def: If  $f \not\equiv 0$  is meromorphic on some  $\mathcal{N}_{\mathbb{C}}^*(z_0)$ , then there exists a unique  $\mu \in \mathbb{Z}$  s.t.  $(z-z_0)^\mu f(z)$  is holomorphic and nonzero on some  $\mathcal{N}_{\mathbb{C}}(z_0)$ .

- $\mu = 0 \Rightarrow z_0$  is a removable singularity of  $f$
  - $\mu > 0 \Rightarrow z_0$  is a pole of order  $\mu$  of  $f$
  - $\mu < 0 \Rightarrow z_0$  is a zero of order  $|\mu|$  of  $f$
- } simple pole / zero  $\frac{|\mu|=1}$

Intuition:

$f(z) = \frac{h(z)}{(z-z_0)^\mu}$  ...  $z_0$  is a pole of order  $\mu \Leftrightarrow h$  is analytic and nonzero on some  $\mathcal{N}_{\mathbb{C}}(z_0)$

$f(z) = (z-z_0)^\mu g(z)$  ...  $z_0$  is a zero of order  $\mu \Leftrightarrow g$  is analytic and nonzero on some  $\mathcal{N}_{\mathbb{C}}(z_0)$

Example

$$f(z) = \frac{(z-1)(z+i)^2}{(e^z-1)(z-2)^4}$$

$\Rightarrow z=1$  ... zero of order 1

$z=-i$  ... zero of order 2

$z=2$  ... pole of order 4

$e^z = 1 \Leftrightarrow z = 2\pi i \cdot k \Rightarrow z = 2\pi i \cdot k$  ... pole of order 1  
 $k \in \mathbb{Z}$

$$\hookrightarrow e^z - 1 = z + \frac{z^2}{2} + \frac{z^3}{3!} + \dots$$

👁  $z_0$  order  $\mu$  zero of  $f(z)$   $\Leftrightarrow z_0$  order  $\mu$  pole of  $\frac{1}{f(z)}$

## Laurent series around zeroes and poles

→ suppose  $z_0$  is a zero / pole of  $f(z)$  and consider the L. expansion around  $z_0$

①  $z_0$  order  $p$  zero  $\Rightarrow f(z) = \sum_{n=p}^{\infty} a_n(z-z_0)^n, a_n \neq 0$

②  $z_0$  order  $p$  pole  $\Rightarrow f(z) = \sum_{n=-p}^{\infty} a_n(z-z_0)^n, a_{-p} \neq 0$

## Calculating Residues at poles

Recall:  $z_0$  order  $p$  pole of  $f \Rightarrow \exists g$  holomorphic and nonzero on some  $\eta_{\leq \varepsilon}(z_0)$  s.t.

$$f(z) = \frac{g(z)}{(z-z_0)^h} \quad \text{and} \quad \text{Res}(f, z_0) = \frac{1}{(h-1)!} g^{(h-1)}(z_0)$$

### Special cases:

→ suppose that  $g$  is holomorphic and nonzero on some  $\eta_{\leq \varepsilon}(z_0)$

①  $f(z) = \frac{g(z)}{z-z_0} \Rightarrow \text{Res}(f, z_0) = g(z_0)$

②  $f(z) = \frac{g(z)}{(z-z_0)^2} \Rightarrow \text{Res}(f, z_0) = g'(z_0)$

→ suppose that  $h(z)$  has a simple zero at  $z_0$

③  $f(z) = \frac{1}{h(z)} \Rightarrow \text{Res}(f, z_0) = \frac{1}{h'(z_0)}$

④  $f(z) = \frac{g(z)}{h(z)} \Rightarrow \text{Res}(f, z_0) = \frac{g(z_0)}{h'(z_0)}$

### Proof of ④

$$f(z) = \frac{g(z)}{(z-z_0)\mu(z)} \Rightarrow \text{Res}(f, z_0) = [z^{-1}] f(z) = [z^{-1}] \frac{g(z)}{(z-z_0)\mu(z)} = [z^0] \frac{g(z)}{\mu(z)}$$

→ because both  $g(z)$  and  $\mu(z)$  are analytic and nonzero at  $z_0$ , this is

$$\text{Res}(f, z_0) = \frac{[z_0] g(z)}{[z_0] \mu(z)} = \frac{g(z_0)}{h'(z_0)} \quad \square$$

### Example:

$$f(z) = \frac{z-i}{(e^z-1)(z-2)^2}$$

→  $z_0 = 2$

②  $\Rightarrow \text{Res}(f, 2) = \frac{e^2-1-(z-i)e^z}{(e^z-1)^2} \Big|_{z=2}$

→  $z_0 = 2\pi i k$

④  $\Rightarrow \text{Res}(f, 2\pi i k) = \frac{z-i}{e^z(z-2)^2} \Big|_{z=2\pi i k}$

# Applications of the Residue Theorem

→ the Residue theorem is extremely powerful at evaluating certain kinds of improper integrals, even of non-elementary functions

👁 Real integrals can be calculated using curve integrals

Want:  $I = \int_a^b f(x) dx$



$\varphi: [a, b] \rightarrow \mathbb{C}$   
 $\varphi(t) = t$

$\int_{\varphi} f(z) dz = \int_a^b f(t) dt = I$

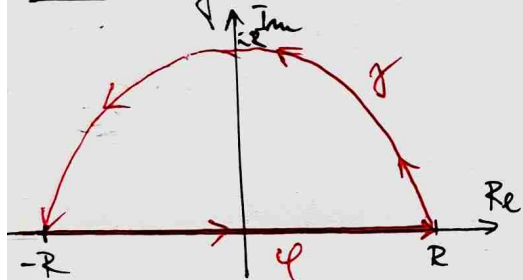
Recall: ML-equality:

$\int_{\varphi} f \leq |\varphi| \cdot \sup_{z \in \varphi} |f(z)|$

assume  $Q$  doesn't have any real roots

Method:  $f$  rational =  $\frac{P(x)}{Q(x)}$

$\Rightarrow \int_{-\infty}^{\infty} f(x) dx = ?$



Residue theorem: we can calculate  $\oint_{\varphi \cup \gamma} f$

$\oint_{\varphi \cup \gamma} f = \int_{\varphi} f + \int_{\gamma} f$

→ let  $R \rightarrow \infty$

$\int_{\varphi} f = \int_{-R}^R f(x) dx \rightarrow \int_{-\infty}^{\infty} f(x) dx \leftarrow \text{what we want}$

$\int_{\gamma} f \leq |\gamma| \cdot \sup_{z \in \gamma} |f(z)| = \pi \cdot R \cdot \sup_{z \in \gamma} |f(z)|$

→ if  $\deg(Q) \geq \deg(P) + 2$ , then as  $R \rightarrow \infty$ :

$\int_{\gamma} f \leq \pi \cdot R \cdot \frac{1}{R^2} \rightarrow 0$

$\Rightarrow \int_{-\infty}^{\infty} \frac{P(x)}{Q(x)} dx = \oint_{\Gamma} \frac{P(z)}{Q(z)} dz$ , where  $\Gamma =$   for  $\begin{cases} Q \text{ no real roots} \\ \deg(Q) \geq \deg(P) + 2 \end{cases}$

Calculating Residues

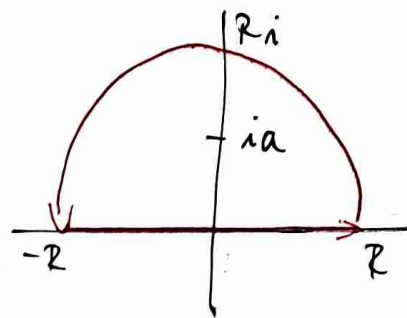
$\text{Res}\left(\frac{1}{Q(z)}, z_0\right) = \frac{1}{Q'(z_0)}$

$\text{Res}\left(\frac{P(z)}{Q(z)}, z_0\right) = \frac{P(z_0)}{Q'(z_0)}$

## Examples

$$(1) \int_{-\infty}^{\infty} \frac{1}{x^2 + a^2} dx = \frac{\pi}{a}$$

poles:  $x^2 = -a^2 \Rightarrow x = \pm ia \rightarrow a > 0$



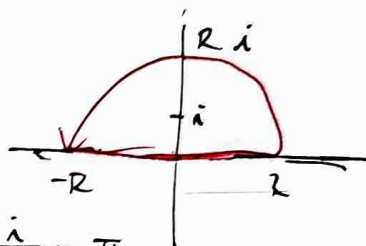
convergence:  $\deg(x^2 + a^2) \geq \deg(1) + 2 \quad \checkmark$

$$I = \int_{\Gamma} \frac{1}{z^2 + a^2} = 2\pi i \cdot \text{Res}(f, ia) = 2\pi i \cdot \frac{1}{2z} \Big|_{ia} = 2\pi i \cdot \frac{1}{2ia} = \underline{\underline{\frac{\pi}{a}}}$$

$$(2) \int_{-\infty}^{\infty} \frac{dx}{(x^2 + 1)^2} = \frac{\pi}{2}$$

• convergence  $\checkmark$

• poles:  $z^2 + 1 = 0 \Rightarrow z = \pm i$ , order = 2



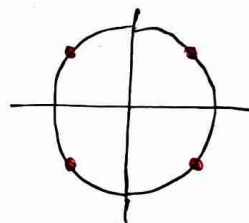
$$I = \int_{\Gamma} \frac{dz}{(z^2 + 1)^2} = 2\pi i \cdot \text{Res}(f, i) = 2\pi i \cdot \frac{-2}{(2i)^3} = \frac{-4\pi i}{-8i} = \underline{\underline{\frac{\pi}{2}}}$$

•  $f(z) = \frac{1}{(z-i)^2} \cdot \frac{1}{(z+i)^2} \Rightarrow \text{Res}(f, i) = \frac{d}{dz} \frac{1}{(z+i)^2} \Big|_{z=i} = \frac{-2}{(z+i)^3} \Big|_{z=i} = \frac{-2}{(2i)^3}$

$$(3) \int_{-\infty}^{\infty} \frac{dx}{x^4 + 1} = \frac{\pi}{\sqrt{2}}$$

poles:  $z^4 = -1 \Rightarrow 4\text{-th roots of unity}$

$$\hookrightarrow e^{4i\theta} = e^{i(\pi + 2k\pi)}$$



$$\Rightarrow 4\theta = \pi(1+2k) \Rightarrow \theta = \frac{\pi}{4}(1+2k) = \frac{\pi}{4}, \frac{3\pi}{4}, \frac{5\pi}{4}, \frac{7\pi}{4}$$

upper half-plane:  $\frac{\pi}{4}, \frac{3\pi}{4}$

•  $\theta = \frac{\pi}{4} \Rightarrow z_1 = \cos(\frac{\pi}{4}) + i \sin(\frac{\pi}{4}) = \frac{\sqrt{2}}{2} + i \frac{\sqrt{2}}{2} = \frac{1}{\sqrt{2}}(1+i)$

•  $\theta = \frac{3\pi}{4} \Rightarrow z_2 = \frac{1}{\sqrt{2}}(-1+i)$

} simple poles

$$\text{Res}(f, z_1) = \frac{1}{4z^3} \Big|_{z_1} = \frac{1}{4 e^{i\frac{3\pi}{4}}} = \frac{1}{4 \cdot \frac{1}{\sqrt{2}}(-1+i)} \cdot \frac{-1-i}{-1-i} = \frac{1}{2\sqrt{2}} \cdot \frac{-1-i}{1+1} = \frac{-1-i}{4\sqrt{2}}$$

$$\text{Res}(f, z_2) = \frac{1}{4z^3} \Big|_{z_2} = \frac{1}{4 e^{i\frac{5\pi}{4}}} = \frac{1}{4 \cdot \frac{1}{\sqrt{2}}(1+i)} \cdot \frac{1-i}{1-i} = \frac{1-i}{2\sqrt{2}(1+1)} = \frac{1-i}{4\sqrt{2}}$$

$$I = 2\pi i \sum \text{Res} = 2\pi i \cdot \left( \frac{-1-i}{4\sqrt{2}} + \frac{1-i}{4\sqrt{2}} \right) = 2\pi i \cdot \frac{-i}{2\sqrt{2}} = \underline{\underline{\frac{\pi}{\sqrt{2}}}}$$

## Picard's Theorem (E+V)

Theorem: Let  $x_0, y_0 \in \mathbb{R}$  and  $F: \mathbb{R}^2 \rightarrow \mathbb{R}$  be continuous and suppose  $\exists M > 0$  s.t.

$$\text{for } \forall x, y_1, y_2 \in \mathbb{R}: |F(x, y_1) - F(x, y_2)| \leq M \cdot |y_1 - y_2| \quad \boxed{\times}$$

Then the initial value problem

$$\textcircled{*} \quad y(x_0) = y_0 \quad \& \quad y'(x) = F(x, y(x))$$

has a unique solution  $y: U \rightarrow \mathbb{R}$  defined on some  $U = [x_0 - \delta, x_0 + \delta]$ ,  $\delta > 0$

Proof: Recall this result implied by the Fundamental Theorem of Calculus:

$$y(x) \text{ solves } \textcircled{*} \iff y(x) \text{ solves } y(x) = y_0 + \int_{x_0}^x F(t, y(t)) dt \quad (\dagger\dagger)$$

$\rightarrow$  let  $I := [x_0 - \delta, x_0 + \delta]$ , we will show that for sufficiently small  $\delta$ ,  $(\dagger\dagger)$  has a unique solution on  $I$ .

Def:  $f: (M, d) \rightarrow (M, d)$  is a contracting mapping of  $(M, d)$  into itself  $\equiv$

$$\exists \alpha \in (0, 1) \text{ s.t. } \forall a, b \in M: d(f(a), f(b)) \leq \alpha \cdot d(a, b)$$

Theorem (Banach): Every contraction  $f: M \rightarrow M$   <sup>$M$  complete</sup> has a unique fixed point  $f(a) = a$ .

Lemma: The MS  $(C[I], \|f - g\|_\infty)$  is complete.  $\|f - g\| = \max_{x \in I} |f(x) - g(x)|$

$\rightarrow$  back to the proof. Notice that  $(\dagger\dagger)$  defines a mapping  $A: C[I] \rightarrow C[I]$

$$A: y \mapsto y_0 + \int_{x_0}^x F(t, y(t)) dt$$

$\rightarrow$  plan: show that  $A$  is a contraction of  $C[I]$  into itself  $\xRightarrow{\text{Banach}}$  it has a unique fixed point

$\rightarrow$  let  $y_1, y_2 \in C[I]$  and  $\delta$  be very small, then

$$\begin{aligned} d(A(y_1), A(y_2)) &= \max_{x \in I} |A(y_1)(x) - A(y_2)(x)| = \max_{x \in I} \left| \int_{x_0}^x F(t, y_1(t)) dt - \int_{x_0}^x F(t, y_2(t)) dt \right| \\ &= \max_{x \in I} \left| \int_{x_0}^x (F(t, y_1(t)) - F(t, y_2(t))) dt \right| \leq \max_{x \in I} \int_{x_0}^x |F(t, y_1(t)) - F(t, y_2(t))| dt \end{aligned}$$

$$\begin{aligned} \boxed{\times} &\leq \max_{x \in I} \int_{x_0}^x M \cdot |y_1(t) - y_2(t)| dt \leq M \cdot \max_{x \in I} \int_{x_0}^x \underbrace{\|y_1 - y_2\|_\infty}_{\leq \delta} dt \\ &= M \cdot d(y_1, y_2) \cdot \underbrace{(x - x_0)}_{\in \mathbb{R}} \leq \delta M \cdot d(y_1, y_2) \end{aligned}$$

$\rightarrow$  we just set  $\delta$  sufficiently small that  $\delta M < 1$  and we have a contraction